

# INITIAL ACQUISITION

## OUTLINE

- Introduction and System Model
- Quantitative Analysis
- Using Pre- and Post-detection Integration and Optimality
- Practical Design Considerations
- Examples of Initial Acquisition in Wireless Communications
- Summary

# INTRODUCTION AND SYSTEM MODEL

## Receiver Synchronization Process

- Initial Acquisition
- Timing initial acquisition
- Fine initial acquisition
- Time tracking
- Frequency tracking
- Setting other receiver functions related to synchronization

*Note: This presentation will focus on initial acquisition, the carrier and timing synchronizations will be covered in subsequent presentations*

# Objectives of Initial Acquisition

- Find out if a desired signal exists
- Determine the starting point of a data block (frame synch)
- Determine signal level
  - AGC Initialization
- Determine coarse timing
  - Timing tracking loop initialization
- Determine coarse frequency offset
  - Frequency tracking loop initialization

## Signal Detection in Initial Acquisition

- Generally it can be modeled as detection of a known signal in additive, white Gaussian noise (AWGN)
- The timing of the signal to be detected is unknown, in general
- The phase of the channel is usually unknown
- The channel may be static or time variant, single path or multipath
  - The static single path channel is most important
- It is a typical problem in detection theory

## Signal Model in Initial Acquisition

- Consider a sampled digital system, at time  $kT$ , the received signal sample can be expressed as

$$r_k = h_k e^{j\phi_k} s_k + z_k$$

- Assume that the complex channel gain  $h_k e^{j\phi_k}$  in a given time interval does not change
- $s_k$  is a known, usually BPSK or QPSK, sequence
- SNR of  $r_k$  is equal to  $|h_k|^2 / \sigma_z^2$ , where  $\sigma_z^2$  is the variance of  $z_k$ , assuming  $|s_k|^2 = 1$
- Multiple samples are (coherently) combined by correlating  $\{s_k\}$  with  $\{r_k\}$  to form a detected symbol with no-loss of information
- Detected symbols can be non-coherent combined
- Both are for improving the detection reliability

## The Detection Process

- (1) Correlating  $s_k$  with  $r_k$ , assuming  $h$  and  $e^{j\phi}$  do not change, we have

$$d_n = \sum_{k=n}^{n+K-1} s_k^* r_k = \sum_{k=n}^{n+K-1} h_{c,k} e^{j\phi_k} |s_k|^2 + \sum_{k=n}^{n+K-1} s_k^* z_k = Kh_c e^{j\phi} + z'$$

The SNR of  $d_n$  is K times of the SNR of  $r_k$  ( $\gamma_d = K\gamma_r$ )

- (2) Forming the decision variable

- In most cases,  $\phi$  is unknown: none-coherent detection

$$D_n = |Kh_c e^{j\phi} + z'|^2 = |d_n|^2$$

- (3) Comparing  $D_n$  with threshold  $T$

- $D_n < T : \theta = \theta_0 \Rightarrow$  No Signal
- $D_n \geq T : \theta = \theta_1 \Rightarrow$  Signal sequence  $s_n \dots s_{n+k}$  detected!



## The Detection Process (cont.)

(4) If no signal, go to samples starting at  $T_{n+1}$  or  $T_{n+0.5}$ , until the detection of signal sequence successful

- Post detection (non-coherent) combining
  - For a time variant channel, the value of  $K$  is limited by the channel coherent time
  - Performance can be improved by summing multiple  $D_n$ 's to form a composite decision valuable

$$D_{n,L} = \sum_{l=0}^L |d_{n+lK}|^2$$

- $D_{n,L}$  is compared to a threshold to perform the same detection as above

# QUANTITATIVE ANALYSIS

## Decision variables' pdfs – without post-detection combining

- $D_n$  above has the following pdfs:
  - No signal ( $\theta = \theta_0$ ) – Central chi-square distribution with 2 degrees of freedom:

$$p_0(D) = \frac{1}{\sigma_{z'}^2} e^{-\frac{D}{\sigma_{z'}^2}}, \quad D \geq 0$$

- Signal exists ( $\theta = \theta_1$ ) – Non-central chi-square distribution with 2 degrees of freedom:

$$p_1(D) = \frac{1}{\sigma_{z'}^2} e^{-(D+\lambda^2)/\sigma_{z'}^2} I_0\left(\frac{2|\lambda|\sqrt{D}}{\sigma_{z'}^2}\right), \quad D \geq 0$$

$$\lambda = E[a_n] = K|h_c|e^{j\phi}$$

## Decision variables' pdfs – with post-detection combining

- $D_{n,L}$  given above has the following pdfs:
  - No signal ( $\theta = \theta_0$ ) – Central chi-square distribution with  $2L$  degrees of freedom:

$$p_{0,L}(D) = \frac{1}{(L-1)! (\sigma_z^2)^L} D^{L-1} e^{-\frac{D}{\sigma_z^2}}, \quad D \geq 0$$

- Signal exists ( $\theta = \theta_1$ ) – Non-central chi-square distribution with  $2L$  degrees of freedom:

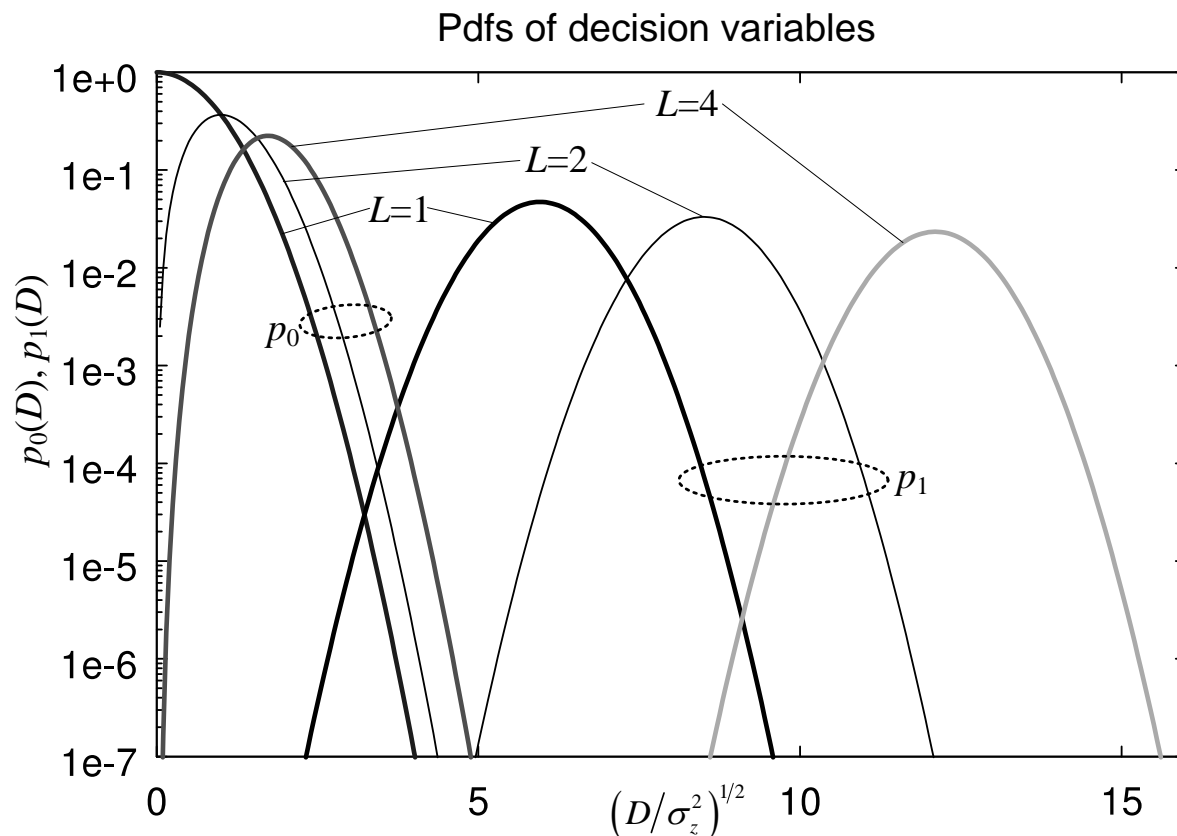
$$p_{1,L}(D) = \frac{1}{\sigma_z^2} \left( \frac{D}{s^2} \right)^{\frac{L-1}{2}} e^{-(D+s^2)/\sigma_z^2} I_{L-1} \left( \frac{2s\sqrt{D}}{\sigma_z^2} \right), \quad D \geq 0$$

$$s = \sqrt{\sum_{k=0}^{L-1} |\lambda_k|^2} \quad \lambda_k = E[a_k] = K |h_{c,k}| e^{j\phi_k}$$

$I_{L-1}$  –  $(L-1)^{\text{th}}$  order Modified Bessel function of the first kind

## Decision variables' pdfs (cont.)

Assuming all  $\lambda_k$ 's are equal



## Detection and false Probability ( $P_D$ & $P_F$ )

- False Probability ( $P_F$ ):

$$P_F = \int_{Th}^{\infty} p_{0,L}(u) du = \int_{Th}^{\infty} \frac{1}{(L-1)! (\sigma_z^2)^K} u^{L-1} e^{-\frac{u}{\sigma_z^2}} du = e^{-Th} \sum_{k=0}^{L-1} \frac{(Th)^k}{k!}$$

– where  $Th = Th / \sigma_z^2$ , – Normalized threshold

- Detection Probability ( $P_D$ ):

$$P_D = \int_{Th}^{\infty} p_{1,L}(u) du = \int_{Th}^{\infty} \frac{1}{\sigma_z^2} \left( \frac{u}{s^2} \right)^{\frac{L-1}{2}} e^{-(u+s^2)/\sigma_z^2} I_{L-1} \left( \frac{2s\sqrt{u}}{\sigma_z^2} \right) du$$

$$= \int_{Th}^{\infty} \left( \frac{v}{\tilde{s}^2} \right)^{\frac{K-1}{2}} e^{-(v+\tilde{s}^2)/\sigma_z^2} I_{L-1} (2\tilde{s}\sqrt{v}) dv$$

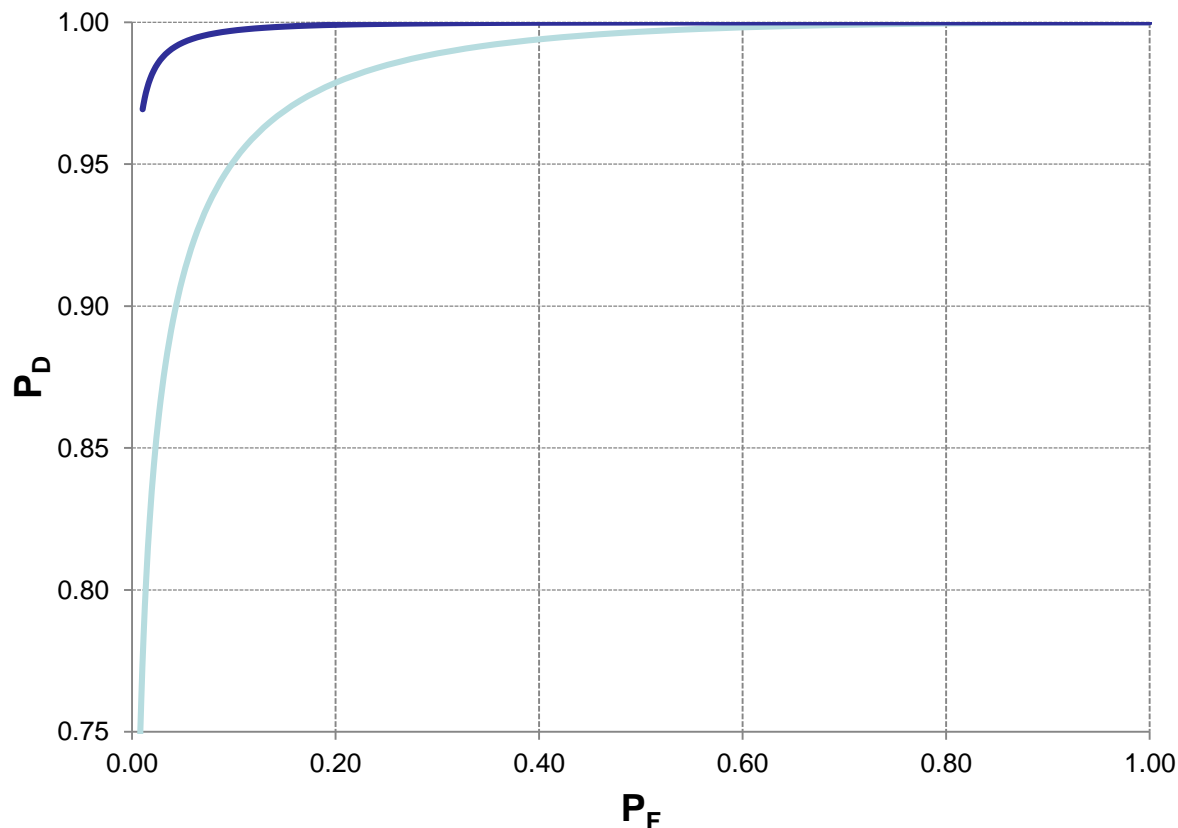
– where  $Th = Th / \sigma_z^2$ ,  $\tilde{s} = s / \sqrt{\sigma_z^2}$

## $P_D$ , $P_{\text{miss}}$ & $P_F$ : Discussion

- $P_F$  only depends on the variance of noise and interference, since there is no signal
- It is more convenient to set threshold based on a predetermined constant  $P_F$
- For the same  $P_F$ , the  $P_D$  will be larger for a larger  $L$  at the same SNR
  - For the same  $P_D$  and  $P_F$ , double  $L$  reduces required SNR by 1.8 – 2.5 dB (the gain is larger at high SNR, see examples below)
- The miss probability is defined as 1 minus the Detection probability ( $P_{\text{miss}} = 1 - P_D$ )

## $P_D$ , $P_{\text{miss}}$ & $P_F$ – Examples

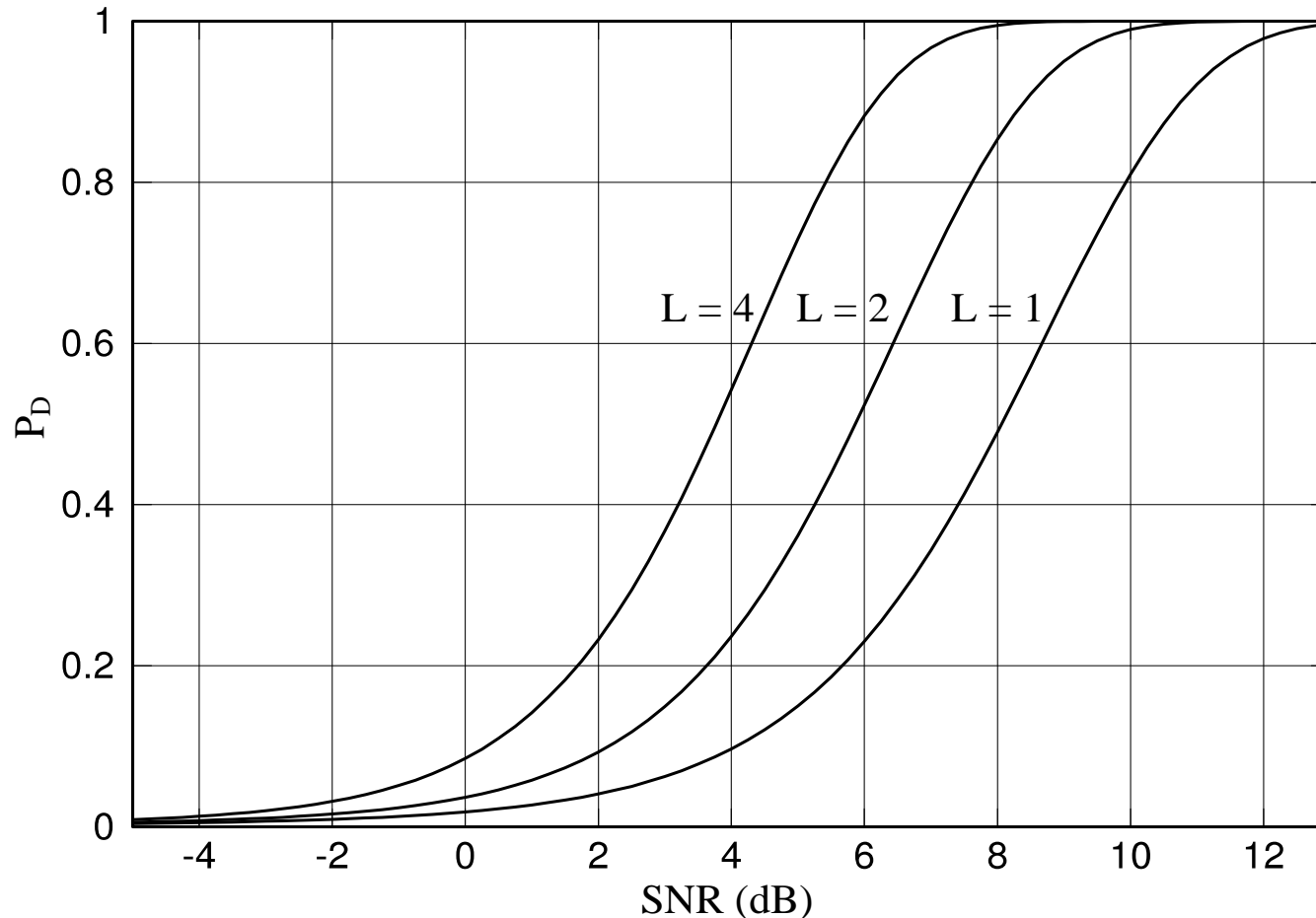
- $P_D$  vs.  $P_F$   $L = 1$  and  $2$  for the same SNR (5dB)





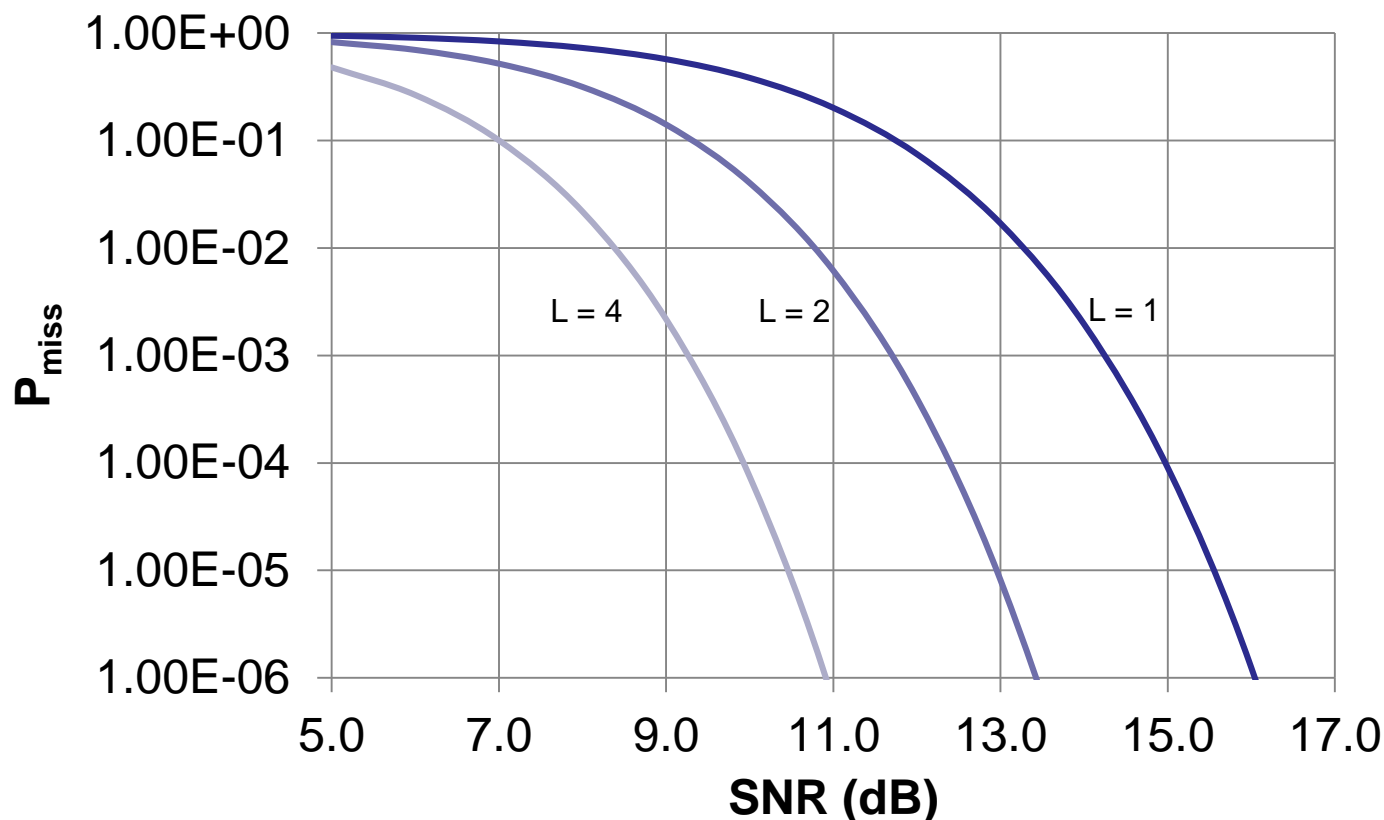
## $P_D$ , $P_{\text{miss}}$ & $P_F$ – Examples (cont.)

$P_D$  for  $L = 1, 2, 4$ , at  $P_F = 0.001$



## $P_D$ , $P_{\text{miss}}$ & $P_F$ – Examples (cont.)

- $P_{\text{miss}}$  for  $L = 1, 2, 4$  @  $P_F = 0.0001$  (high SNR)



# **USING PRE- AND POST- DETECTION INTEGRATION AND THEIR OPTIMARITY**

## Pre-detection integration

- Pre-detection coherent integration (correlation)

$$a_n = \sum_{k=n}^{n+K-1} s_k^* r_k = \sum_{k=n}^{n+K-1} h_{c,k} e^{j\phi_k} |s_k|^2 + \sum_{k=n}^{n+K-1} s_k^* z_k = Kh_c e^{j\phi} + z'$$

- Assuming phase and magnitude do not change: Coherent combining
- 3 dB gain when the samples in integration double
- For time-varying channel the maximum number of samples in coherent integration are limited
- In the simplest case, if there is a frequency offset
  - the integrated signal energy will be reduced (combining loss)
  - The lost energy becomes an additional interference
- The combining gain is less than 3 dB for doubling samples

## Pre-detection integration (cont.)

- The coherent integration operation can be viewed as signal passing through a rectangular MA filter with frequency response:

$$H(f) = \frac{\sin(\pi K T f)}{\pi K T f} = \text{sinc}(\pi K T f)$$

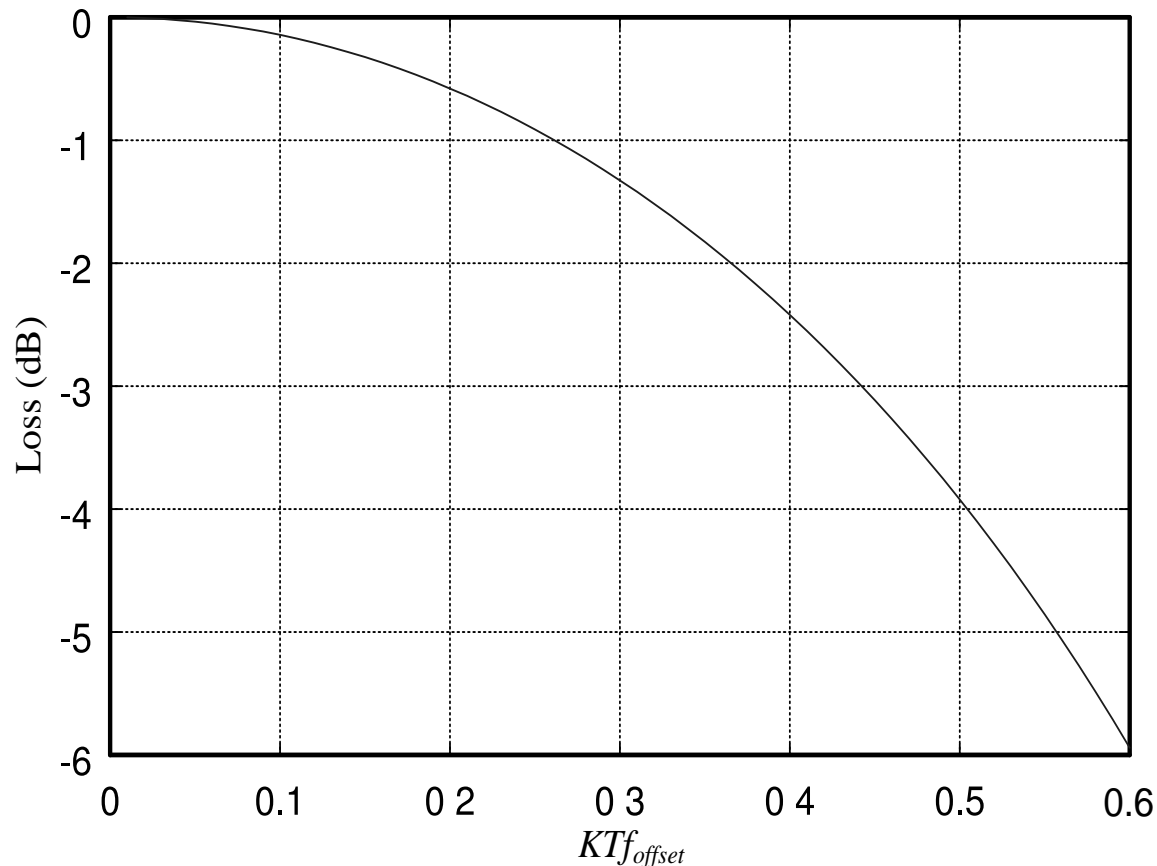
- Assuming frequency offset is  $f_{\text{offset}}$  the combined energy is equal to

$$K^2 |h_c|^2 \text{sinc}^2(\pi K T f_{\text{offset}})$$

- Loss is equal to  $10\log[\text{sinc}^2(\pi K T f_{\text{offset}})]$
- The interference due to the reduced energy is equal to

$$K^2 |h_c|^2 \times (1 - \text{sinc}^2(\pi K T f_{\text{offset}}))$$

## Loss in coherent integration due to frequency offset



## Post-Detection Integration

- As shown above, the combining gain is about 2 dB for post-detection integration if the number of samples doubles in the integration at relatively low SNR
- At high SNR, the gain can be up to 2.5 dB
- It is necessary to determine the parameters for post- and integration based on the channel coherent time and/or frequency offset

### Optimal Detection for Unknown Channel Phase

- Above we described initial acquisition procedure by comparing the squared value of the coherently integrated descrambled samples (with or without non-coherent integration) to a threshold.
- This procedure is not only convenient but also optimal when the channel phase is unknown but uniformly distributed between 0 and  $2\pi$ .
- In order for it to be optimal, we need to show that this procedure satisfies the Neyman-Pearson lemma with likelihood testing
- We can prove this in three steps



## Can We Argue It Is Optimal?

(1) Neyman-Pearson lemma for binary hypothesis test:

$$\Lambda(y) = \frac{p_1}{p_0} \begin{cases} > \eta : \theta = \theta_1 \\ \leq \eta : \theta = \theta_0 \end{cases}$$

- $\Lambda(y)$ : Likelihood ratio,  $p_1, p_0$ , pdfs (likelihood functions) of received signal with/without desired signal,  $\eta$ : threshold
- It is optimal in the sense if  $\Lambda(y) \leq \eta$  we have  $P_F$  equals to a given probability, then  $P_D$  is maximized
- Does the detection procedure discussed satisfies the N-P lemma? Two questions need to be answered:
  - (1) Are  $p_0(D)$  and  $p_1(D)$  used in detection the likelihood functions based on the observed received signal ?
  - (2) Does comparing D to a threshold equivalent to compare  $\Lambda(y)$  to  $\eta$ ?

## Can We Argue It Is Optimal? (cont.)

(2) The coherent integration output when signal exists is

$$d_n = K |h_c| e^{j\phi_n} + z'$$

- with  $\phi$  uniformly distributed between 0 and  $2\pi$ , the pdf of  $d_n$  averaged over  $\phi_n$  is

$$p_1(d_n) = \frac{1}{\sigma_{z'}^2} e^{-(D+|\lambda|^2)/\sigma_{z'}^2} I_0\left(\frac{2|\lambda|\sqrt{D}}{\sigma_{z'}^2}\right), \text{ where } (D = |d_n|^2)$$

- If signal does not exist, i.e., the noise only case, the pdf is:

$$p_0(d_n) = e^{-D/\sigma_{z'}^2} / \sigma_{z'}^2$$

- Conclusion:  $p_0(D)$  and  $p_1(D)$  are the averaged pdfs (likelihood functions) of the coherent integrator outputs (before squaring!) with and without signal, respectively

## Can We Argue It Is Optimal?(cont.)

- (3) The likelihood ratio  $\Lambda$  is a monotonically increasing function of  $D$
- $Th$  can be selected such that  $D <> Th$  is equivalent to  $\Lambda <> h$
  - Proof of detection with post-detection integration is similar

### Notes:

- We have shown in what sense the detection process is optimal
- However, the optimality in the area of statistics is always arguable 😊

# **PRACTICAL DESIGN CONSIDERATIONS**

## Noise Variance Estimation

- Noise variance estimate is the key for setting accurate detection thresholds
  - Accuracy of the estimate determines if the detection performance meets design expectation
- Examples of noise estimation
  - Very low SNR environment, e.g., CDMA voice systems (IS-95, IS-2000)
    - Total noise power is approximately equal to total power
    - With AGC, the total power is approximately a constant
    - => The noise power is a constant
    - => Threshold determined by AGC setting

## Noise Variance Estimation (cont.)

- Examples of noise estimation (cont.)
  - Medium to high SNR Environment
    - Total power at AGC output is equal to signal power plus noise power ( $P_s + P_n = A$ )
    - After correlation with the expected sequence:
      - With no desired signal:  $E[D_n] = KE[|a_n|^2] = KP_n$
      - With desired signal:
$$E[D_n] = KE[|a_n|^2] = K^2 P_s + KP_n = B$$
      - Then 
$$P_n = \left( \frac{AK^2 - B}{K(K-1)} \right) \quad \text{if } K \gg 1, \quad P_n \approx A - \frac{B}{K^2}$$
      - Comments:
        - » Estimation of A is usually more accurate due to averaging
        - » With post detection integration, the estimate can be improved by averaging multiple  $D_n$ 's

## Noise Variance Estimation (cont.)

- Further discussions:
  - For detection, the accuracy of estimation of noise variance has ultimate importance.
  - Noise variance estimation can be improved if there are known orthogonal spaces in which only contains noise but no known signal, e.g.,
    - Different frequencies
    - Different Walsh code spaces
    - “Blank out” time intervals
  - Need to make sure the noises in these orthogonal spaces has the same variance as that we want to estimate for using the hypothesis testing

## $P_D$ and $P_F$ Parameter Selection

- The target of  $P_F$  usually selected to be much smaller than  $P_{\text{miss}}$ , i.e.,  $1 - P_D$ 
  - Many possible false events would occur for one detection event, for example:
    - In CDMA-2000 initial acquisition, for each  $\theta_1$ , there could be 32767 offsets (or 65534 for half chip sampling) to result  $\theta_0$
    - For WCDMA need to try many false hypotheses to find the true P-SCH and S-SCH in addition to time offset hypotheses
      - Many effort have been made to reduce the search effort (mainly hierarchical cell-search). However there are still a lot of hypotheses to test.
  - LTE also uses hierarchical cell-search approach (PSS and SSS). Thus, there are also a lot of hypotheses to test



## $P_D$ and $P_F$ Selection (cont.)

- On the other hand, rejecting a false alarm event is usually easier than correcting a miss event
  - False alarm event may be verified by additional correlations of the same sequences with different offset
    - However, false event with additional processing may cause missing the opportunity of acquiring the signal
  - To acquired the right detection again, the acquisition need to be performed one more cycle

## $P_D$ and $P_F$ and Acquisition Performance

- The acquiring process can be expressed by a state machine
- The acquisition performance depends on:
  - The costs of verifying a wrong test results
  - The costs needed before next successful acquisition
  - Costs include the needed time and processing power consumption
- The average power and time for a successful acquisition can be computed based on  $P_D$ ,  $P_F$  and the associated cost.
- Parallel processing can reduce acquisition time but not power consumption

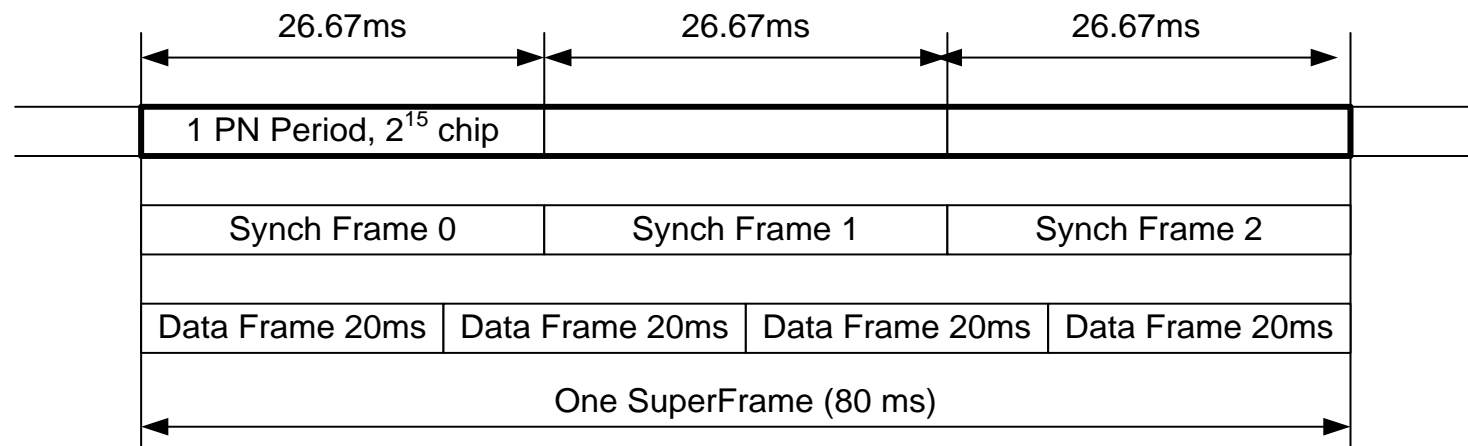
# Dealing with Large Initial Frequency Offset

- It would be desirable to use (low cost) XOs with high initial frequency error, which will impact initial acquisition performance
- Shorter coherent integration length can be used followed by longer non-coherent post-detection integration
  - Acquisition time will be longer, or  $P_D$  and/or  $P_F$  will be larger
  - Coherent integration length cannot be too short due to aperiodic integration loss
- Another method is to use multiple initial frequency hypotheses
  - Setting initial frequencies to be  $0, \pm\Delta F_h, \pm2\Delta F_h, \dots$  reduces the maximum initial frequency offset to  $\pm0.5\Delta F_h$ 
    - This will increase computational complexity of acquisition
    - May also increase initial acquisition time

# **EXAMPLES OF INITIAL ACQUISITION IN WIRELESS COMMUNICATIONS**

## CDMA-2000

- It's pilot channel is used for initial acquisition
- Pilot channel signal is periodic with period (26.6667 ms long) of 32768 with QPSK modulation (with a pair of augmented  $2^{15}-1$  long PN sequences known to receiver)
- Three period of the pilot channel constitutes an 80 ms Superframe, which contains 3 26.67 ms Synch frames and 4 20 ms data frames



## CDMA-2000 (cont.)

- To detect the pilot channel, the receiver correlates the received signal with one or more segments of the sequence.
- The received signal should be sampled more than once per sample (chip) interval, usually, 0.5 chip interval, i.e., 2 correlations per one chip interval is appropriate
- For parallel processing and/or post-detection combining, segments of the PN sequence can be used to correlate with the same or different signal sequences
- Once a match is found, the receiver knows the beginning of the PN sequence
- A PN sequence period aligns with a frame of sync channel

## CDMA-2000 (cont.)

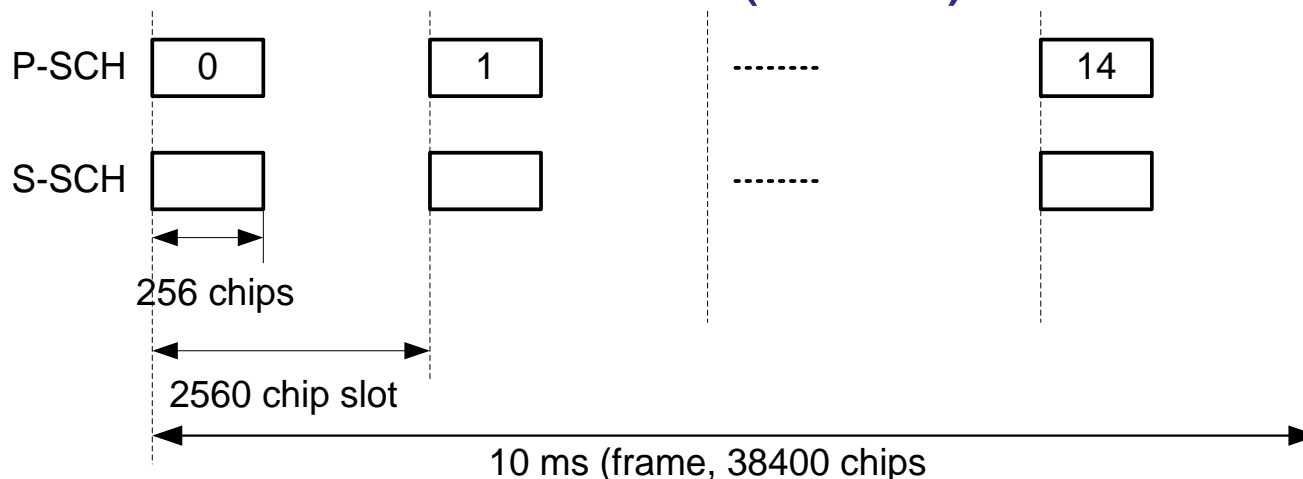
- Once the beginning of PN sequence, the receiver demodulate the synch channel to determine the start of the Superframe and information for demodulating other forward link channels
- Selection of coherent integration length:
  - Assume we have initial frequency accuracy of 2ppm ( $2 \times 10^{-6}$ )
  - For 800 MHz band, the frequency offset is 1600 Hz
  - The CDMA2000 chip rate is 1.2288 Mchips/sec
  - If we choose to integrate 100 chips, we will have a loss of
$$10\log\left[\text{sinc}^2(\pi * 100 * 1.2288 * 10^{-6} * 1600)\right] = -0.64\text{dB}$$
  - For 1.9G band, the integration will be 40 chips to have the same loss
- Multiple such coherent integrated outputs could be non-coherently combined

## WCDMA

- WCDMA employs a two stage initial acquisition procedure with two Synchronization Channels:
  - Primary Synchronization Channel (P-SCH)
    - Utilize a 256 chip spreading sequence
    - Same for all of the cells
  - Secondary Synchronization Channel (S-SCH)
    - Each cell transmits one out of 64 possible S-SCH codes
    - Each S-SCH codes is a combination of 15 different sequences, each of which is from a group of 16 256 chip sequences
- WCDMA SCH channel structure is as shown below



## WCDMA (cont.)



- Acquisition process:
  - First search for P-SCH
    - 256 chip (@ 3.84 MHz = 66.67  $\mu$ s) coherent integration
    - Non-coherent combining of coherent integration output may be used.
    - Successful P-SCH search determines slot boundary

## WCDMA (cont.)

- Acquisition process (cont.)
  - Search for S-SCH
    - Determine S-SCH code sequences at slot boundaries by correlating all 16 possible 256 S-SCH chip sequences
    - The largest peaks at the correlator output determines the S-SCH chip sequences transmitted by the cell
    - Match the determined chip sequences to one of the 64 possible S-SCH code words (may need to check 15 start positions)
    - Once the S-SCH code word is determined, the receiver knows the frame boundary
    - Search for primary scrambling codes of the pilot and data channels (Each S-SCH code word corresponding to a code group with 8 scrambling codes)

## LTE

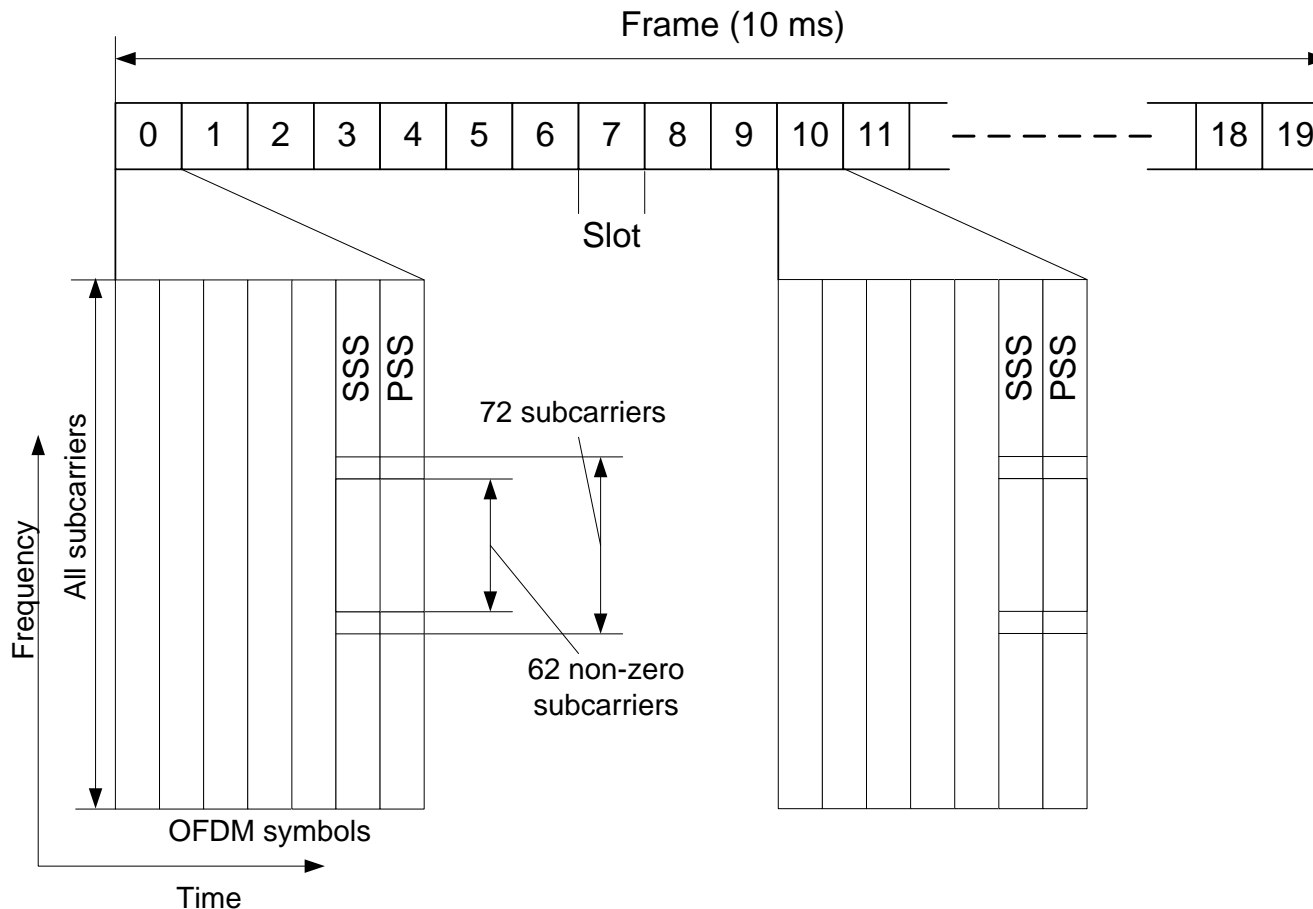
- LTE has 6 possible transmission signal bandwidths: 1.4, 3, 5, 10, 15 and 20
- LTE has FDD (discussed here) and TDD modes
- To facilitate the initial acquisition, the synch channel bandwidth is 1.4 MHz (72 subcarriers, 62 non-zero data).
  - For wider bandwidth transmission, the synch channels occupy the center 72 subcarriers (73 including the zero subcarrier).
- Similar to WCDMA, LTE employs a two stage initial acquisition procedure using two Synch Channels:
  - Primary Synchronization Channel (P-SCH or PSS)
  - Secondary Synchronization Channel (S-SCH or SSS)
    - PSS and SSS occupies one OFDM symbol each
    - A pair of PSS and SSS symbols are transmitted every 5 ms

## LTE (Cont.)

- PSS OFDM Symbol
  - It is generated from a frequency domain Zadoff-Chu sequence with two 32 long segments
    - Constant Amplitude (low peak to average power ratio)
    - Impulse (time domain) autocorrelation
    - There are three such PSS symbols ( $N_{ID}^{(2)} = 0, 1, 2$ )
  - It is the last OFDM symbol in the 0<sup>th</sup> and 10<sup>th</sup> slot
- SSS OFDM Symbol:
  - Consists of 2 interleaved length-31 m-sequences, each of which has a different cyclic shift
  - There are 168 such SSS OFDM symbols ( $N_{ID}^{(1)} = 0, 1, \dots, 167$ ), with combinations of different shifts
  - scrambled according to  $N_{ID}^{(2)}$
  - There are a total of 504 cell ID's:  $N_{ID}^{cell} = 3N_{ID}^{(2)} + N_{ID}^{(1)}$
  - It is the OFDM symbol proceeding PSS

## LTE (Cont.)

- PSS and SSS in time and frequency



## LTE (Cont.)

- PSS Acquisition:
  - Even though PSS is defined in frequency domain, the detection is most efficient done in time domain.
  - The total data bandwidth of PSS is 945KHz, the signal can be first filtered to between 0.945 to 1.08 MHz and down sampled
  - The down sampled signals are correlated the three possible sample sequences of the time domain representations of PSS
    - OFDM symbol length is  $67\mu\text{s}$  so coherent combining can be used
  - The correlator output are squared, likely non-coherently combined with multiple such output spaced by 5 ms, and compared to a threshold.
  - Such hypothesis testing need to performed every 0.5 sample interval until a success is declared
  - This determines the half frame boundary and the cell ID  $N_{ID}^{(2)}$

## LTE (Cont.)

- SSS Detection:
  - The scramble code of SSS is known with  $N_{ID}^{(2)}$  from PSS detection
  - The received signal corresponding to SSS position is correlated with the 168 time domain representations of SSS
  - The largest correlation output determines the cell ID
  - The frame boundary is determined by based on SSS
    - The zero<sup>th</sup> and 10<sup>th</sup> SSS has the same two 31 sequences but swapped in place
  - Non-ideal cross-correlation property between SSS sequences may require extra steps to reduce the false probability
- Cell ID (PSS and SSS) determines the scrambling sequences of other channels

## Further Discussions

- In a multipath channel a moving average filter of the squared detection outputs as the decision variable may provide a better detection probability
- The received signal sample sequence that passed the detection hypotheses can provide a rough timing estimate
  - In LTE, the timing will need to be refined if the data bandwidth is wider than the PSS/SSS bandwidth, i.e., 1.4 MHz
- The phase differences between the consecutive correlation outputs can provide an estimate of the carrier phase shift between them and thus frequency offset
- These conclusions can be used for all of the three examples discussed above
  - Due to the large number of possible bands for LTE deployment, pre-PSS frequency scanning may be necessary to determine which bands contain valid LTE signals



## SUMMARY

- Initial acquisition is usually done by the receiver trying to find a known sequence sent at regular interval by Tx
- The detection is done by correlating a known transmitted sequence with the received signal samples and the squared outputs are compared to a threshold for detection
- The theoretical pre-detection (coherent) and post-detection (non-coherent) characteristics were derived
- The coherent and non-coherent combining performances were shown and their trade-offs were discussed
  - It is shown numerically, post-detection (non-coherent) combining has about 2 dB gain or higher when samples are doubled
  - In theory pre-detection (coherent) combining has a 3 dB gain or when samples are doubled. However, the gain is reduced when channel is time-varying

- It is shown the square detection metrics are optimal in statistical sense
- Practical design considerations were discussed
- Three examples of wireless communication initial acquisitions were presented, including CDMA2000, WCDMA and LTE
- Initial acquisition can provide initial estimates for receiver frequency, timing and AGC blocks
- Only the simplest case of single path static AWGN channel was discussed, because:
  - It can be used base-line for system design and accurate verification of receiver performance in simulation and lab testing
  - It is the foundation of system initial acquisition for more complex system models
  - Special considerations must be given for specific systems, e.g. LTE, especially TDD LTE