## Appendix SA3.1 Basic Relationships in the Multiregional Input–Output Model

In standard input–output fashion, total demand for commodity *i* in region *s* is given by

$$\sum_{j=1}^{n} a_{ij}^{s} x_{j}^{s} + f_{i}^{s}$$
 (A3.1.1)

The total supply of commodity *i* in region *s* is the total that is shipped in from other regions,

$$\sum_{r=1}^{p} z_i^{rs} (r \neq s)$$

plus the amount that is supplied from within the region,  $z_i^{ss}$ . This is just  $T_i^s$ , the sum of the elements in column *s* in Table 3.8, as defined in (3.18). Since shipments (supplies) occur only to satisfy needs (demands), we have, for each commodity *i* 

$$T_i^s = \sum_{j=1}^n a_{ij}^s x_j^s + f_i^s$$
(A3.1.2)

Total production of i in region r is equivalent to the total amount of i shipped from r, including that kept within the region

$$x_i^r = \sum_{s=1}^p z_i^{rs}$$
(A3.1.3)

From the definition of the interregional proportions in section 3.4.2,  $c_i^{rs} = z_i^{rs} T_i^s$ , (A3.1.3) can be rewritten as

$$x_i^r = \sum_{s=1}^p c_i^{rs} T_i^s$$
 (A3.1.4)

Putting  $T_i^s$  as defined in (A3.1.2), into (A3.1.4)

$$x_{i}^{r} = \sum_{s=1}^{p} c_{i}^{rs} \left( \sum_{j=1}^{n} a_{ij}^{s} x_{j}^{s} + f_{i}^{s} \right) \quad (i = 1, \dots, n)$$
(A3.1.5)

Using familiar matrix notation, let

$$\mathbf{x}^{r} = \begin{bmatrix} x_{1}^{r} \\ \vdots \\ x_{n}^{r} \end{bmatrix}, \ \mathbf{x}^{s} = \begin{bmatrix} x_{1}^{s} \\ \vdots \\ x_{n}^{s} \end{bmatrix}, \ \mathbf{f}^{s} = \begin{bmatrix} f_{1}^{s} \\ \vdots \\ f_{n}^{s} \end{bmatrix}$$
$$\mathbf{A}^{s} = \begin{bmatrix} a_{11}^{s} & \cdots & a_{1n}^{s} \\ \vdots & \vdots \\ a_{n1}^{s} & a_{nn}^{s} \end{bmatrix}, \ \mathbf{\hat{c}}^{rs} = \begin{bmatrix} c_{1}^{rs} & 0 & \cdots & 0 \\ 0 & c_{2}^{rs} & \vdots \\ 0 & & c_{n}^{rs} \end{bmatrix}$$

The reader should be convinced that the entire set of n equations for outputs of goods in region r can be expressed as

$$\mathbf{x}^{r} = \sum_{s=1}^{p} \hat{\mathbf{c}}^{rs} (\mathbf{A}^{s} \mathbf{x}^{s} + \mathbf{f}^{s}) = \sum_{s=1}^{p} \hat{\mathbf{c}}^{rs} \mathbf{A}^{s} \mathbf{x}^{s} + \sum_{s=1}^{p} \hat{\mathbf{c}}^{rs} \mathbf{f}^{s}$$
(A3.1.6)

There will be p such matrix equations, one for each region r (r = 1, ..., p). Again using matrix notation, as in section 3.4, we can construct

$$\mathbf{x} = \begin{bmatrix} \mathbf{x}^{1} \\ \vdots \\ \mathbf{x}^{s} \\ \vdots \\ \mathbf{x}^{p} \end{bmatrix}, \mathbf{f} = \begin{bmatrix} \mathbf{f}^{1} \\ \vdots \\ \mathbf{f}^{s} \\ \vdots \\ \mathbf{f}^{p} \end{bmatrix}, \mathbf{A} = \begin{bmatrix} \mathbf{A}^{1} \cdots \mathbf{0} \cdots \mathbf{0} \\ \vdots & \vdots \\ \mathbf{0} & \mathbf{A}^{s} & \mathbf{0} \\ \vdots & \vdots \\ \mathbf{0} & \cdots & \mathbf{0} & \cdots & \mathbf{A}^{p} \end{bmatrix} \text{ and }$$
$$\mathbf{C} = \begin{bmatrix} \hat{\mathbf{c}}^{11} \cdots \hat{\mathbf{c}}^{1s} \cdots \hat{\mathbf{c}}^{1p} \\ \vdots & \vdots & \vdots \\ \hat{\mathbf{c}}^{r1} \cdots \hat{\mathbf{c}}^{rs} \cdots \hat{\mathbf{c}}^{rp} \\ \vdots & \vdots & \vdots \\ \hat{\mathbf{c}}^{p1} \cdots \hat{\mathbf{c}}^{ps} & \cdots \hat{\mathbf{c}}^{pp} \end{bmatrix}$$

Then the p matrix equations in (A3.1.6) can be compactly expressed as

$$\mathbf{x} = \mathbf{C}(\mathbf{A}\mathbf{x} + \mathbf{f}) = \mathbf{C}\mathbf{A}\mathbf{x} + \mathbf{C}\mathbf{f}$$
  
(I-CA)x = Cf (A3.1.7)

from which

$$\mathbf{x} = (\mathbf{I} - \mathbf{C}\mathbf{A})^{-1}\mathbf{C}\mathbf{f}$$
(A3.1.8)

as in (3.22) and (3.23) in the text.