Fundamentals of Signals and Systems: A Building Block Approach by Philip D. Cha and John I. Molinder

LIST OF ERRATA

Errata in Text

- 1. Page 9, 4th line after Eq. (1.10): Change "...of the sinusoid of Eq. (1.8)..." to "...of the sinusoid of Eq. (1.9)..."
- 2. Page 31, 3rd line after Eq. (2.4): Change "...large positive and negative power errors..." to "...large and positive and negative errors..."
- 3. Page 50, Fig. 2.24: Change

$$-1/2Ae^{j\theta}$$
 to $1/2Ae^{-j\theta}$

- 4. Page 61, 9th line from the bottom: Change "...to $c_{(N/2)} 1$ " to "... $c_{(N/2)-1}$ "
- 5. Page 61, 5th line from the bottom: Change "...and frequencies $\{-\alpha f_0, -f_0, 0, f_0\}...$ " to "...and frequencies $\{-2f_0, -f_0, 0, f_0\}...$ "
- 6. Page 62, Eq. (2.75): Change

$$X[k] = \sum_{n=1}^{N} x[n-1]e^{-jk\frac{2\pi}{N}(n-1)} \quad \text{to} \quad X[k] = \sum_{n=1}^{N} x[n-1]e^{-j(k-1)\frac{2\pi}{N}(n-1)}$$

- 7. Page 62, 2nd line from the bottom: Change "...to 100 the agreement between..." to "...to 1000 the agreement between..."
- 8. Page 152, Problem 4-7 (Fig. 4.44): The length of the rod is l, and the attachment point for the spring and damper is at l/2.
- 9. Page 271, line 2: Change "In general, $X_0 = c_0$ and for k = 0 $X_k = 2c_k$ for real functions" to "In general, $X_0 = c_0$ and for $k \neq 0$ $X_k = 2c_k$ for real functions"
- 10. Page 284, Fig. 8.13. Change the x-axis label from " $\hat{\omega}$ (rad/s)" to " $\hat{\omega}$ (rad)"
- 11. Page 336, Problem 9-3: The frequencies of interests f_1 and f_2 are both less than $f_s/2$ [NOT $f_{\hat{s}}/2$ as shown].

12. Page 339, Problem 9-6(c): Change

$$H(e^{j\hat{\omega}}) = \frac{1}{1 - \frac{1}{2}e^{j\hat{\omega}}}$$
 to $H(e^{j\hat{\omega}}) = \frac{1}{1 - \frac{1}{2}e^{-j\hat{\omega}}}$

Errata on Disk

1. Chapter 3, fig3_20.m, line 18: Change

subplot(2, 1, 2, k') to subplot(2, 1, 2)