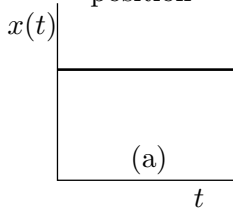
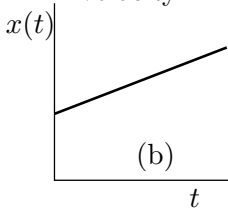


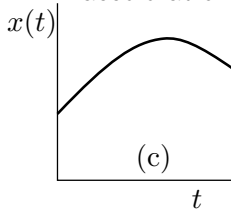
constant  
position



constant  
velocity



constant  
acceleration



variable  
acceleration

