

Chapter 9

```
In[1]:= Needs["DiscreteMath`RSolve`"]
```

```
In[2]:= Needs["Graphics`MultipleListPlot`"]
```

```
In[3]:= Needs["Graphics`Graphics3D`"]
```

```
In[4]:= Needs["Graphics`PlotField`"]
```

à Question 1

```
In[5]:= Clear[p, Q, q1, q2, pi1, pi2]
```

```
In[6]:= Q = q1 + q2
p = A - B Q
pi1 = p q1 - a q1
pi2 = p q2 - a q2
```

```
Out[6]= q1 + q2
```

```
Out[7]= A - B (q1 + q2)
```

```
Out[8]= -a q1 + q1 (A - B (q1 + q2))
```

```
Out[9]= -a q2 + q2 (A - B (q1 + q2))
```

```
In[10]:= Solve[D[pi1, q1] == 0, q2]
```

```
Out[10]= {{q2 -> -\frac{a - A + 2 B q1}{B}}}
```

```
In[11]:= Solve[D[pi2, q2] == 0, q2]
```

```
Out[11]= {{q2 -> -\frac{a - A + B q1}{2 B}}}
```

```
In[12]:= solq1 = Simplify[Solve[-\frac{a - A + 2 B q1}{B} == -\frac{a - A + B q1}{2 B}, q1]]
```

```
Out[12]= {{q1 -> -\frac{a + A}{3 B}}}
```

```
In[13]:= solq2 = Simplify[-\frac{a - A + 2 B q1}{B}] /. solq1
```

```
Out[13]= {\frac{-a + A - \frac{2}{3} (-a + A)}{B}}
```

```
In[14]:= Simplify[Expand[\frac{-a + A - \frac{2}{3} (-a + A)}{B}]]
```

```
Out[14]= \frac{-a + A}{3 B}
```

Hence, equilibrium quantities are identical.

à Question 2

This question is best done with paper and pencil. Summations over j not equal to i are not conveniently dealt with in software packages.

à Question 3

■ (i)

```
In[15]:= Clear[p, Q, q1, q2, pi1, pi2]
```

```
In[16]:= Q = q1 + q2
          p = A - B Q
          pi1 = p q1 - a1 q1
          pi2 = p q2 - a2 q2
```

```
Out[16]= q1 + q2
```

```
Out[17]= A - B (q1 + q2)
```

```
Out[18]= -a1 q1 + q1 (A - B (q1 + q2))
```

```
Out[19]= -a2 q2 + q2 (A - B (q1 + q2))
```

```
In[20]:= Solve[D[pi1, q1] == 0, q2]
```

```
Out[20]= {{q2 -> -\frac{-A + a1 + 2 B q1}{B}}}
```

```
In[21]:= Solve[D[pi2, q2] == 0, q2]
```

```
Out[21]= {{q2 -> -\frac{-A + a2 + B q1}{2 B}}}
```

```
In[22]:= solq1 = Simplify[Solve[-\frac{-A + a1 + 2 B q1}{B} == -\frac{-A + a2 + B q1}{2 B}, q1]]
```

```
Out[22]= {{q1 -> \frac{A - 2 a1 + a2}{3 B}}}
```

```
In[23]:= solq2 = Simplify[-\frac{-A + a1 + 2 B q1}{B}] /. solq1
```

```
Out[23]= {\frac{A - a1 - \frac{2}{3} (A - 2 a1 + a2)}{B}}
```

```
In[24]:= Simplify[Expand[\frac{A - a1 - \frac{2}{3} (A - 2 a1 + a2)}{B}]]
```

```
Out[24]= \frac{A + a1 - 2 a2}{3 B}
```

■ (ii)

We already have the following as the reaction functions in the static model:

$$q_1 = \frac{A-a_1}{2B} - \frac{q_2}{2} \text{ for firm 1}$$

$$q_2 = \frac{A-a_2}{2B} - \frac{q_1}{2} \text{ for firm 2}$$

So the dynamic reaction functions are:

$$q_1(t) = \frac{A-a_1}{2B} - \frac{q_2(t)}{2}$$

$$q_2(t) = \frac{A-a_2}{2B} - \frac{q_1(t)}{2}$$

```
In[25] := RSolve[{q1[t] ==  $\frac{A - a_1}{2B} - \frac{q2[t-1]}{2}$ ,
  q2[t] ==  $\frac{A - a_2}{2B} - \frac{q1[t-1]}{2}$ , q1[0] == q10, q2[0] == q20}, {q1[t], q2[t]}, t]
```

```
Out[25] = {{q1[t] ->  $\frac{1}{3B} (2^{-1-t} (-2 (-1)^t A + 2^{1+t} A + 3 B q10 + 3 (-1)^t B q10 -$ 
   $3 B q20 + 3 (-1)^t B q20 + (3 + (-1)^t - 2^{2+t}) a_1 + (-3 + (-1)^t + 2^{1+t}) a_2)$ ),
  q2[t] ->  $\frac{1}{3B} (2^{-1-t} (-2 (-1)^t A + 2^{1+t} A - 3 B q10 + 3 (-1)^t B q10 + 3 B q20 +$ 
   $3 (-1)^t B q20 + (-3 + (-1)^t + 2^{1+t}) a_1 + (3 + (-1)^t - 2^{2+t}) a_2)$ )}]}
```

This could be simplified but we do not do this here. What matters is that the stability is governed purely by the coefficients of $q_2(t-1)$ and $q_1(t-1)$ in the reaction functions of firms 1 and 2 respectively. Since these are less than unity, then the system is asymptotically stable. In fact, the coefficients must each take the value of $-1/2$. Consequently the coefficients of $q10$ and $q20$ in the results involve only $(\frac{1}{2})^t$ or $(-\frac{1}{2})^t$ and so tend to zero in the limit regardless of the values of $q10$ and $q20$. (Note that the term B cancels.)

à Question 4

```
In[26] := Clear[p, Q, q1, q2, pi1, pi2]
```

■ (i)

```

In[27]:= p = 9 - Q
         Q = q1 + q2
         TC1 = a1 q1
         TC2 = a2 q2
         pi1 = p q1 - TC1
         pi2 = p q2 - TC2

```

```
Out[27]= 9 - Q
```

```
Out[28]= q1 + q2
```

```
Out[29]= a1 q1
```

```
Out[30]= a2 q2
```

```
Out[31]= -a1 q1 + q1 (9 - q1 - q2)
```

```
Out[32]= -a2 q2 + (9 - q1 - q2) q2
```

```
In[33]:= Solve[D[pi1, q1] == 0, q2]
```

```
Out[33]= {{q2 -> 9 - a1 - 2 q1}}
```

```
In[34]:= Solve[D[pi2, q2] == 0, q2]
```

```
Out[34]= {{q2 -> 1/2 (9 - a2 - q1)}}
```

```
In[35]:= solq1 = Simplify[Solve[9 - a1 - 2 q1 == 1/2 (9 - a2 - q1), q1]]
```

```
Out[35]= {{q1 -> 1/3 (9 - 2 a1 + a2)}}
```

```
In[36]:= solq2 = 9 - a1 - 2 q1 /. solq1
```

```
Out[36]= {9 - a1 - 2/3 (9 - 2 a1 + a2)}
```

```
In[37]:= Simplify[Expand[9 - a1 - 2/3 (9 - 2 a1 + a2)]]
```

```
Out[37]= 1/3 (9 + a1 - 2 a2)
```

```
In[38]:= Simplify[1/3 (9 - 2 a1 + a2) - 1/3 (9 + a1 - 2 a2)]
```

```
Out[38]= -a1 + a2
```

Hence, equilibrium q_1 is greater than equilibrium q_2 if $a_1 < a_2$.

■ (ii) $a_1 = 3$ and $a_2 = 5$

The model is then

$$\begin{aligned} p &= 9 - Q \\ Q &= q_1 + q_2 \\ TC_1 &= 3 q_1 \\ TC_2 &= 5 q_2 \end{aligned}$$

```
In[39]:= pi1 /. a1 -> 3
```

```
Out[39]= -3 q1 + q1 (9 - q1 - q2)
```

```
In[40]:= pi2 /. a2 -> 5
```

```
Out[40]= -5 q2 + (9 - q1 - q2) q2
```

```
In[41]:= Solve[D[-3 q1 + q1 (9 - q1 - q2), q1] == 0, q1]
```

```
Out[41]= {{q1 -> (6 - q2)/2}}
```

```
In[42]:= Solve[D[-5 q2 + (9 - q1 - q2) q2, q2] == 0, q2]
```

```
Out[42]= {{q2 -> (4 - q1)/2}}
```

Our reaction functions are therefore

$$q_1(t) = 3 - \frac{1}{2} q_2(t-1)$$

$$q_2(t) = 2 - \frac{1}{2} q_1(t-1)$$

The monopoly points are (3, 0) for firm 1 and (0, 2) for firm 2.

■ (a) firm 1 monopolist

```
In[43]:= RSolve[{q1[t] == 3 - (1/2) q2[t-1],
                 q2[t] == 2 - (1/2) q1[t-1], q1[0] == 3, q2[0] == 0}, {q1[t], q2[t]}, t]
```

```
Out[43]= {{q1[t] -> (1/3) 2^{-1-t} (3 - (-1)^t + 2^{4+t}), q2[t] -> (1/3) 2^{-1-t} (-3 - (-1)^t + 2^{2+t})}}
```

■ (b) firm 2 monopolist

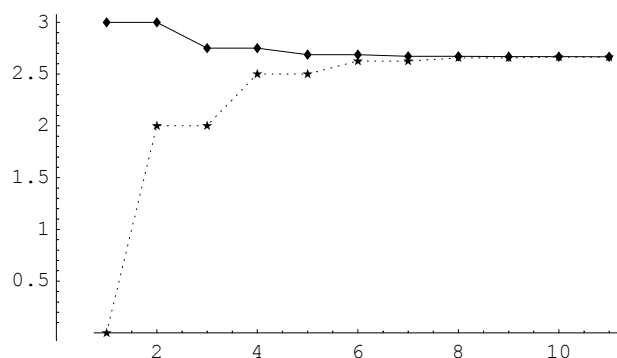
```
In[44]:= RSolve[{q1[t] == 3 - (1/2) q2[t-1],
                 q2[t] == 2 - (1/2) q1[t-1], q1[0] == 0, q2[0] == 2}, {q1[t], q2[t]}, t]
```

```
Out[44]= {{q1[t] -> (1/3) 2^{1-t} (-3 - (-1)^t + 2^{2+t}), q2[t] -> (1/3) 2^{1-t} (3 - (-1)^t + 2^t)}}
```

```
In[45]:= q1firm1 = Table[(1/3) 2^{-1-t} (3 - (-1)^t + 2^{4+t}), {t, 0, 10}];
```

```
In[46]:= q1firm2 = Table[(1/3) 2^{1-t} (-3 - (-1)^t + 2^{2+t}), {t, 0, 10}];
```

```
In[47]:= MultipleListPlot[q1firm1, q1firm2,
  PlotJoined → True, PlotRange → All, AxesOrigin → {0, 0}];
```



The equilibrium is reached sooner when firm 1 is the monopolist. This should not be surprising, since firm 1 has the lower unit costs.

à Question 5

```
In[48]:= Clear[p, Q, q1, q2, q3, pi1, pi2, pi3]
```

■ (i)

```
In[49]:= pi1 = (9 - q1 - q2 - q3) q1 - 5 q1
  pi2 = (9 - q1 - q2 - q3) q2 - 5 q2
  pi3 = (9 - q1 - q2 - q3) q3 - 5 q3
```

```
Out[49]= -5 q1 + q1 (9 - q1 - q2 - q3)
```

```
Out[50]= -5 q2 + q2 (9 - q1 - q2 - q3)
```

```
Out[51]= -5 q3 + (9 - q1 - q2 - q3) q3
```

```
In[52]:= D[pi1, q1]
```

```
Out[52]= 4 - 2 q1 - q2 - q3
```

```
In[53]:= D[pi2, q2]
```

```
Out[53]= 4 - q1 - 2 q2 - q3
```

```
In[54]:= D[pi3, q3]
```

```
Out[54]= 4 - q1 - q2 - 2 q3
```

```
In[55]:= Solve[{4 - 2 q1 - q2 - q3 == 0, 4 - q1 - 2 q2 - q3 == 0, 4 - q1 - q2 - 2 q3 == 0}, {q1, q2, q3}]
```

```
Out[55]= {{q1 → 1, q2 → 1, q3 → 1}}
```

```
In[56]:= Solve[4 - 2 q1 - q2 - q3 == 0, q1]
```

```
Out[56]= {{q1 → 1/2 (4 - q2 - q3)}}
```

```
In[57]:= Solve[4 - q1 - 2 q2 - q3 == 0, q2]
```

```
Out[57]= {{q2 -> 1/2 (4 - q1 - q3)}}
```

```
In[58]:= Solve[4 - q1 - q2 - 2 q3 == 0, q3]
```

```
Out[58]= {{q3 -> 1/2 (4 - q1 - q2)}}
```

Hence, the reaction curves are:

$$q_1(t) = 2 - \frac{1}{2} q_2(t-1) - \frac{1}{2} q_3(t-1)$$

$$q_2(t) = 2 - \frac{1}{2} q_1(t-1) - \frac{1}{2} q_3(t-1)$$

$$q_3(t) = 2 - \frac{1}{2} q_1(t-1) - \frac{1}{2} q_2(t-1)$$

■ (iii)

```
In[59]:= RSolve[{q1[t] == 2 - (1/2) q2[t-1] - (1/2) q3[t-1],
  q2[t] == 2 - (1/2) q1[t-1] - (1/2) q3[t-1],
  q3[t] == 2 - (1/2) q1[t-1] - (1/2) q2[t-1], q1[0] == q10,
  q2[0] == q20, q3[0] == q30}, {q1[t], q2[t], q3[t]}, t]
```

```
Out[59]= {{q1[t] -> 1/3 2^-t (-3 (-2)^t + 3 2^t + (2 + (-2)^t) q10 + (-1 + (-2)^t) q20 - q30 + (-2)^t q30),
  q2[t] -> 1/3 2^-t (-3 (-2)^t + 3 2^t + (-1 + (-2)^t) q10 + (2 + (-2)^t) q20 - q30 + (-2)^t q30),
  q3[t] -> 1/3 2^-t (-3 (-2)^t + 3 2^t + (-1 + (-2)^t) q10 + (-1 + (-2)^t) q20 + 2 q30 + (-2)^t q30)}}
```

Because of the occurrence of the terms $(-1)^t$ then the system also oscillates, eventually oscillating with constant amplitude.

à Question 6

```
In[60]:= Clear[p, Q, q1, q2, q3, pi1, pi2, pi3]
```

■ (i)

```
In[61]:= pi1 = (9 - q1 - q2 - q3) q1 - 3 q1
  pi2 = (9 - q1 - q2 - q3) q2 - 2 q2
  pi3 = (9 - q1 - q2 - q3) q3 - q3
```

```
Out[61]= -3 q1 + q1 (9 - q1 - q2 - q3)
```

```
Out[62]= -2 q2 + q2 (9 - q1 - q2 - q3)
```

```
Out[63]= -q3 + (9 - q1 - q2 - q3) q3
```

```
In[64]:= D[pi1, q1]
```

```
Out[64]= 6 - 2 q1 - q2 - q3
```

```
In[65]:= D[pi2, q2]
```

```
Out[65]= 7 - q1 - 2 q2 - q3
```

```
In[66]:= D[pi3, q3]
```

```
Out[66]= 8 - q1 - q2 - 2 q3
```

```
In[67]:= Solve[{6 - 2 q1 - q2 - q3 == 0, 7 - q1 - 2 q2 - q3 == 0, 8 - q1 - q2 - 2 q3 == 0}, {q1, q2, q3}]
```

```
Out[67]= {{q1 -> 3/4, q2 -> 7/4, q3 -> 11/4}}
```

■ (ii)

```
In[68]:= Solve[6 - 2 q1 - q2 - q3 == 0, q1]
```

```
Out[68]= {{q1 -> 1/2 (6 - q2 - q3)}}
```

```
In[69]:= Solve[7 - q1 - 2 q2 - q3 == 0, q2]
```

```
Out[69]= {{q2 -> 1/2 (7 - q1 - q3)}}
```

```
In[70]:= Solve[8 - q1 - q2 - 2 q3 == 0, q3]
```

```
Out[70]= {{q3 -> 1/2 (8 - q1 - q2)}}
```

Hence, the reaction curves are:

$$q_1(t) = 3 - \frac{1}{2} q_2(t-1) - \frac{1}{2} q_3(t-1)$$

$$q_2(t) = \frac{7}{2} - \frac{1}{2} q_1(t-1) - \frac{1}{2} q_3(t-1)$$

$$q_3(t) = 4 - \frac{1}{2} q_1(t-1) - \frac{1}{2} q_2(t-1)$$

Monopoly points are (3, 0, 0) for firm 1, (0, 7/2, 0) for firm 2 and (0, 0, 4) for firm 3.

■ (a) firm 1 monopolist

```
In[71]:= Clear[q1, q2, q3]
```

```
In[72]:= RSolve[{q1[t] == 3 - (1/2) q2[t-1] - (1/2) q3[t-1],
  q2[t] == (7/2) - (1/2) q1[t-1] - (1/2) q3[t-1],
  q3[t] == 4 - (1/2) q1[t-1] - (1/2) q2[t-1], q1[0] == 3,
  q2[0] == 0, q3[0] == 0}, {q1[t], q2[t], q3[t]}, t]
```

```
Out[72]= {{q1[t] -> -3 (-1/4 - 2^-t + 1/4 e^(i pi t)), q2[t] -> 7/4 - 2^-t - 3/4 e^(i pi t), q3[t] -> 11/4 - 3 (-1)^t/4 - 2^(1-t)}}
```

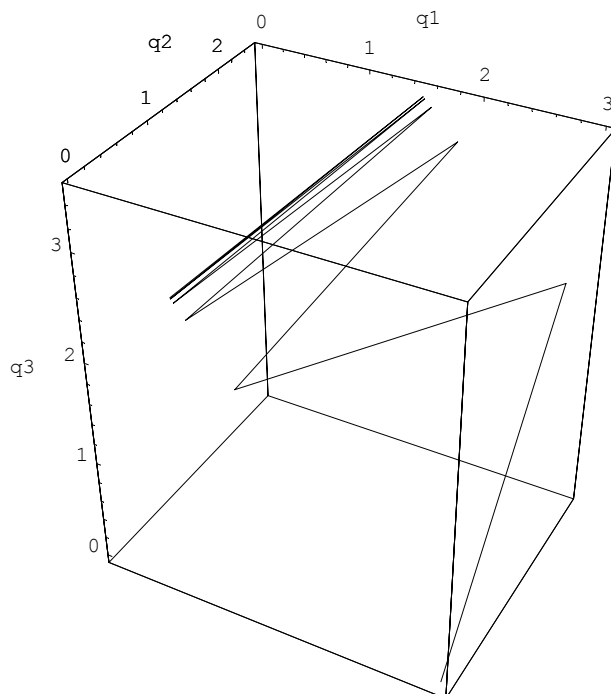
```
In[73]:= q1[t_] := -3 (-1/4 - 2^-t + 1/4 e^(i pi t))
```

```
In[74]:= q2[t_] := 7/4 - 2^-t - 3/4 e^(i pi t)
```

```
In[75]:= q3[t_] :=  $\frac{11}{4} - \frac{3(-1)^t}{4} - 2^{1-t}$ 
```

```
In[76]:= points6a = Table[{q1[t], q2[t], q3[t]}, {t, 0, 10}];
```

```
In[77]:= ScatterPlot3D[points6a, PlotJoined → True, AxesLabel → {"q1", "q2", "q3"}];
```



■ (b) firm 2 as monopolist

```
In[78]:= Clear[q1, q2, q3]
```

```
In[79]:= RSolve[{q1[t] == 3 - (1/2) q2[t - 1] - (1/2) q3[t - 1],  
q2[t] == (7/2) - (1/2) q1[t - 1] - (1/2) q3[t - 1],  
q3[t] == 4 - (1/2) q1[t - 1] - (1/2) q2[t - 1], q1[0] == 0,  
q2[0] == 7/2, q3[0] == 0}, {q1[t], q2[t], q3[t]}, t]
```

```
Out[79]= {{q1[t] →  $\frac{1}{12} (9 - 7(-1)^t - 2^{1-t})$ ,  
q2[t] →  $-\frac{7}{12} (-3 - 2^{2-t} + e^{i\pi t})$ , q3[t] →  $\frac{1}{3} 2^{-2-t} (-26 - 7(-2)^t + 33 2^t)$ }}
```

```
In[80]:= q1[t_] :=  $\frac{1}{12} (9 - 7(-1)^t - 2^{1-t})$ 
```

```
In[81]:= q2[t_] :=  $-\frac{7}{12} (-3 - 2^{2-t} + e^{i\pi t})$ 
```

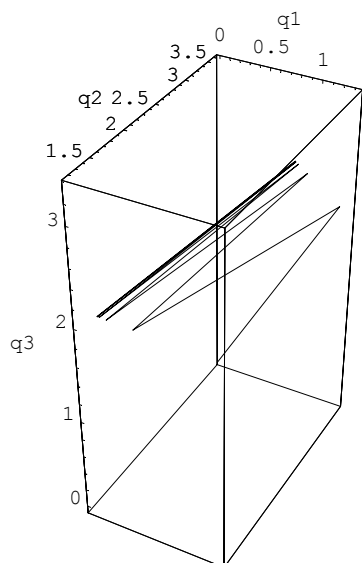
```
In[82]:= q3[t_] :=  $\frac{1}{3} 2^{-2-t} (-26 - 7(-2)^t + 33 2^t)$ 
```

```
In[83]:= points6b = Table[{q1[t], q2[t], q3[t]}, {t, 0, 10}];
```

General::spell1 :

Possible spelling error: new symbol name "points6b" is similar to existing symbol "points6a".

```
In[84]:= ScatterPlot3D[points6b, PlotJoined → True, AxesLabel → {"q1", "q2", "q3"}];
```



■ (c) firm 3 monopolist

```
In[85]:= Clear[q1, q2, q3]
```

```
In[86]:= RSolve[{q1[t] == 3 - (1/2) q2[t - 1] - (1/2) q3[t - 1],
  q2[t] == (7/2) - (1/2) q1[t - 1] - (1/2) q3[t - 1],
  q3[t] == 4 - (1/2) q1[t - 1] - (1/2) q2[t - 1], q1[0] == 0,
  q2[0] == 0, q3[0] == 4}, {q1[t], q2[t], q3[t]}, t]
```

```
Out[86]= {{q1[t] →  $\frac{3}{4} - \frac{2^{-t}}{3} - \frac{5}{12} e^{i\pi t}$ ,
  q2[t] →  $\frac{1}{12} (21 - 5(-1)^t - 2^{4-t})$ , q3[t] →  $\frac{11}{4} + \frac{5 \cdot 2^{-t}}{3} - \frac{5}{12} e^{i\pi t}$ }}
```

```
In[87]:= q1[t_] :=  $\frac{3}{4} - \frac{2^{-t}}{3} - \frac{5}{12} e^{i\pi t}$ 
```

```
In[88]:= q2[t_] :=  $\frac{1}{12} (21 - 5(-1)^t - 2^{4-t})$ 
```

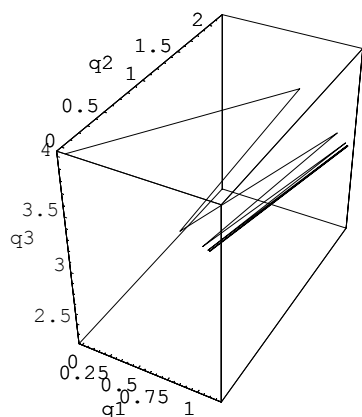
```
In[89]:= q3[t_] :=  $\frac{11}{4} + \frac{5 \cdot 2^{-t}}{3} - \frac{5}{12} e^{i\pi t}$ 
```

```
In[90]:= points6c = Table[{q1[t], q2[t], q3[t]}, {t, 0, 10}];
```

General::spell :

Possible spelling error: new symbol name "points6c" is similar to existing symbols {points6a, points6b}.

```
In[91]:= ScatterPlot3D[points6c, PlotJoined → True, AxesLabel → {"q1", "q2", "q3"}];
```



■ (iii)

```
In[92]:= Clear[q1, q2, q3]
```

```
In[93]:= RSolve[{q1[t] == 3 - (1/2) q2[t - 1] - (1/2) q3[t - 1],
  q2[t] == (7/2) - (1/2) q1[t - 1] - (1/2) q3[t - 1],
  q3[t] == 4 - (1/2) q1[t - 1] - (1/2) q2[t - 1], q1[0] == q10,
  q2[0] == q20, q3[0] == q30}, {q1[t], q2[t], q3[t]}, t]
```

```
Out[93]= {{q1[t] →  $\frac{1}{3} 2^{-2-t} (12 + 9 \cdot 2^t + 8 q_{10} - 4 q_{20} - 4 q_{30} + 2^t e^{i \pi t} (-21 + 4 q_{10} + 4 q_{20} + 4 q_{30}))$ ,
  q2[t] →
   $\frac{1}{3} 2^{-2-t} (-21 (-2)^t + 21 \cdot 2^t + 4 (-1 + (-2)^t) q_{10} + 4 (2 + (-2)^t) q_{20} - 4 q_{30} + (-1)^t 2^{2+t} q_{30})$ ,
  q3[t] →  $\frac{1}{3} 2^{-2-t} (-12 - 21 (-2)^t + 33 \cdot 2^t + 4 (-1 + (-2)^t) q_{10} +$ 
   $4 (-1 + (-2)^t) q_{20} + 8 q_{30} + (-1)^t 2^{2+t} q_{30})$ }}
```

à Question 7

```
In[94]:= Clear[p, Q, q1, q2, q3, pi1, pi2, pi3]
```

■ (i)

```
In[95]:= pi1 = (15 - 2 q1 - 2 q2 - 2 q3) q1 - 5 q1
  pi2 = (15 - 2 q1 - 2 q2 - 2 q3) q2 - 3 q2
  pi3 = (15 - 2 q1 - 2 q2 - 2 q3) q3 - 2 q3
```

```
Out[95]= -5 q1 + q1 (15 - 2 q1 - 2 q2 - 2 q3)
```

```
Out[96]= -3 q2 + q2 (15 - 2 q1 - 2 q2 - 2 q3)
```

```
Out[97]= -2 q3 + (15 - 2 q1 - 2 q2 - 2 q3) q3
```

```
In[98]:= D[pi1, q1]
```

```
Out[98]= 10 - 4 q1 - 2 q2 - 2 q3
```

```
In[99]:= D[pi2, q2]
```

```
Out[99]= 12 - 2 q1 - 4 q2 - 2 q3
```

```
In[100]:= D[pi3, q3]
```

```
Out[100]= 13 - 2 q1 - 2 q2 - 4 q3
```

```
In[101]:= Solve[{10 - 4 q1 - 2 q2 - 2 q3 == 0,
                  12 - 2 q1 - 4 q2 - 2 q3 == 0, 13 - 2 q1 - 2 q2 - 4 q3 == 0}, {q1, q2, q3}]
```

```
Out[101]= {{q1 -> 5/8, q2 -> 13/8, q3 -> 17/8}}
```

```
In[102]:= Solve[10 - 4 q1 - 2 q2 - 2 q3 == 0, q1]
```

```
Out[102]= {{q1 -> 1/2 (5 - q2 - q3)}}
```

```
In[103]:= Solve[12 - 2 q1 - 4 q2 - 2 q3 == 0, q2]
```

```
Out[103]= {{q2 -> 1/2 (6 - q1 - q3)}}
```

```
In[104]:= Solve[13 - 2 q1 - 2 q2 - 4 q3 == 0, q3]
```

```
Out[104]= {{q3 -> 1/4 (13 - 2 q1 - 2 q2)}}
```

Hence, the reaction functions are:

$$q_1(t) = \frac{5}{2} - \frac{1}{2} q_2(t-1) - \frac{1}{2} q_3(t-1)$$

$$q_2(t) = 3 - \frac{1}{2} q_1(t-1) - \frac{1}{2} q_3(t-1)$$

$$q_3(t) = \frac{13}{4} - \frac{1}{2} q_1(t-1) - \frac{1}{2} q_2(t-1)$$

Monopoly points are $(\frac{5}{2}, 0, 0)$ for firm 1, $(0, 3, 0)$ for firm 2 and $(0, 0, \frac{13}{4})$ for firm 3.

■ (a) firm 1 monopolist

```
In[105]:= RSolve[{q1[t] == (5/2) - (1/2) q2[t-1] - (1/2) q3[t-1],
                  q2[t] == 3 - (1/2) q1[t-1] - (1/2) q3[t-1],
                  q3[t] == (13/4) - (1/2) q1[t-1] - (1/2) q2[t-1],
                  q1[0] == 5/2, q2[0] == 0, q3[0] == 0}, {q1[t], q2[t], q3[t]}, t]
```

```
Out[105]= {{q1[t] -> -5 2^-3-t (-4 - 2^t + 2^t e^i pi t),
             q2[t] -> 13/8 - 5 (-1)^t / 8 - 2^-t, q3[t] -> 2^-3-t (-12 - 5 (-2)^t + 17 2^t)}}
```

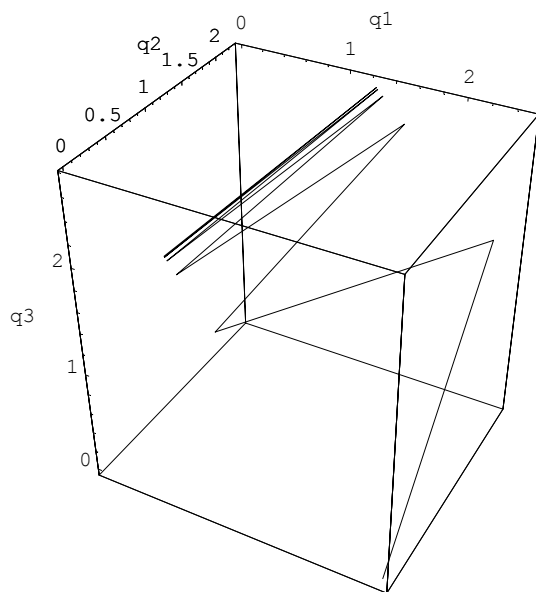
```
In[106]:= q1[t_] := -5 2^-3-t (-4 - 2^t + 2^t e^i pi t)
```

```
In[107]:= q2[t_] := 13/8 - 5 (-1)^t / 8 - 2^-t
```

```
In[108]:= q3[t_] := 2^-3-t (-12 - 5 (-2)^t + 17 2^t)
```

```
In[109]:= points7a = Table[{q1[t], q2[t], q3[t]}, {t, 0, 10}];
```

```
In[110]:= ScatterPlot3D[points7a, PlotJoined → True, AxesLabel → {"q1", "q2", "q3"}];
```



■ (b) firm 2 as monopolist

```
In[111]:= Clear[q1, q2, q3]
```

```
In[112]:= RSolve[{q1[t] == (5/2) - (1/2) q2[t - 1] - (1/2) q3[t - 1],
  q2[t] == 3 - (1/2) q1[t - 1] - (1/2) q3[t - 1],
  q3[t] == (13/4) - (1/2) q1[t - 1] - (1/2) q2[t - 1],
  q1[0] == 0, q2[0] == 3, q3[0] == 0}, {q1[t], q2[t], q3[t]}, t]
```

```
Out[112]= {{q1[t] →  $\frac{1}{3} 2^{-3-t} (-4 - 11 (-2)^t + 15 2^t)$ ,
  q2[t] →  $\frac{1}{3} 2^{-3-t} (44 - 11 (-2)^t + 39 2^t)$ , q3[t] →  $\frac{1}{24} (51 - 11 (-1)^t - 5 2^{3-t})$ }}
```

```
In[113]:= q1[t_] :=  $\frac{1}{3} 2^{-3-t} (-4 - 11 (-2)^t + 15 2^t)$ 
```

```
In[114]:= q2[t_] :=  $\frac{1}{3} 2^{-3-t} (44 - 11 (-2)^t + 39 2^t)$ 
```

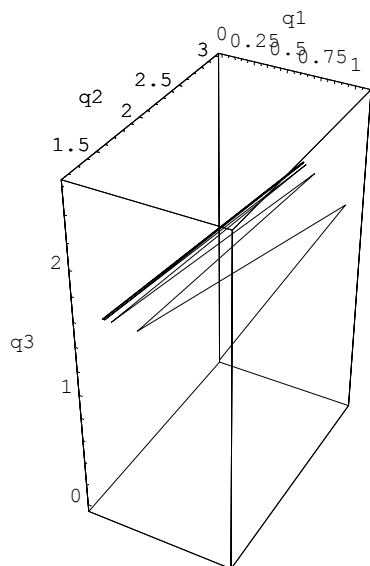
```
In[115]:= q3[t_] :=  $\frac{1}{24} (51 - 11 (-1)^t - 5 2^{3-t})$ 
```

```
In[116]:= points7b = Table[{q1[t], q2[t], q3[t]}, {t, 0, 10}];
```

General::spell1 :

Possible spelling error: new symbol name "points7b" is similar to existing symbol "points7a".

```
In[117]:= ScatterPlot3D[points7b, PlotJoined → True, AxesLabel → {"q1", "q2", "q3"}];
```



■ (c) firm 3 monopolist

```
In[118]:= Clear[q1, q2, q3]
```

```
In[119]:= RSolve[{q1[t] == (5/2) - (1/2) q2[t - 1] - (1/2) q3[t - 1],
  q2[t] == 3 - (1/2) q1[t - 1] - (1/2) q3[t - 1],
  q3[t] == (13/4) - (1/2) q1[t - 1] - (1/2) q2[t - 1], q1[0] == 0,
  q2[0] == 0, q3[0] == 13/4}, {q1[t], q2[t], q3[t]}, t]
```

```
Out[119]= {{q1[t] → 2-3-t (-2 - 3 (-2)t + 5 2t),
  q2[t] → 2-3-t (-10 - 3 (-2)t + 13 2t), q3[t] →  $\frac{1}{8} (17 + 3 2^{2-t} - 3 e^{i \pi t})$ }}
```

```
In[120]:= q1[t_] := 2-3-t (-2 - 3 (-2)t + 5 2t)
```

```
In[121]:= q2[t_] := 2-3-t (-10 - 3 (-2)t + 13 2t)
```

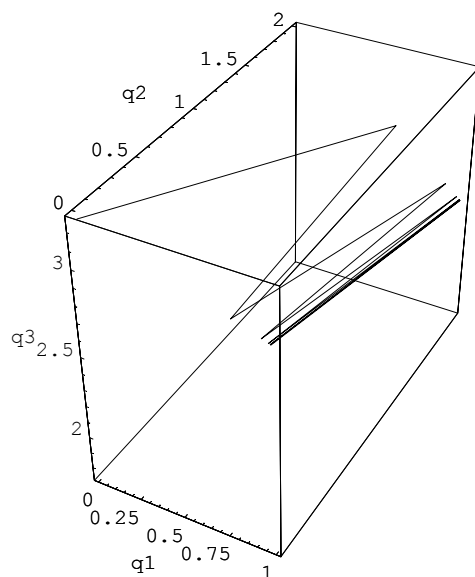
```
In[122]:= q3[t_] :=  $\frac{1}{8} (17 + 3 2^{2-t} - 3 e^{i \pi t})$ 
```

```
In[123]:= points7c = Table[{q1[t], q2[t], q3[t]}, {t, 0, 10}];
```

General::spell :

Possible spelling error: new symbol name "points7c" is similar to existing symbols {points7a, points7b}.

```
In[124]:= ScatterPlot3D[points7c, PlotJoined → True, AxesLabel → {"q1", "q2", "q3"}];
```



■ (iii)

```
In[125]:= Clear[q1, q2, q3]
```

```
In[126]:= RSolve[{q1[t] == (5/2) - (1/2) q2[t - 1] - (1/2) q3[t - 1],
  q2[t] == 3 - (1/2) q1[t - 1] - (1/2) q3[t - 1],
  q3[t] == (13/4) - (1/2) q1[t - 1] - (1/2) q2[t - 1], q1[0] == q10,
  q2[0] == q20, q3[0] == q30}, {q1[t], q2[t], q3[t]}, t]
```

```
Out[126]= {{q1[t] →  $\frac{1}{3} 2^{-3-t}$ 
  (20 - 35 (-2)^t + 15 2^t + 8 (2 + 2^t e^{i \pi t}) q10 + 8 (-1 + (-2)^t) q20 - 8 q30 + (-1)^t 2^{3+t} q30),
  q2[t] →  $\frac{1}{3} 2^{-3-t}$  (-4 - 35 (-2)^t + 39 2^t + 8 (-1 + (-2)^t) q10 +
  8 (2 + (-2)^t) q20 - 8 q30 + (-1)^t 2^{3+t} q30),
  q3[t] →  $\frac{1}{3} 2^{-3-t}$  (-16 - 35 (-2)^t + 51 2^t + 8 (-1 + (-2)^t) q10 +
  8 (-1 + (-2)^t) q20 + 16 q30 + (-1)^t 2^{3+t} q30)}}
```

No. Because of the presence of $(-1)^t$, the system will eventually oscillate.

à Question 8

```
In[127]:= Clear[p, Q, q1, q2, pi1, pi2]
```

■ (i)

■ (a)

```
In[128]:= Q = q1 + q2
```

```
p = 20 - 3 Q
```

```
pi1 = p q1 - 4 q1
```

```
pi2 = p q2 - 4 q2
```

```
Out[128]= q1 + q2
```

```
Out[129]= 20 - 3 (q1 + q2)
```

```
Out[130]= -4 q1 + q1 (20 - 3 (q1 + q2))
```

```
Out[131]= -4 q2 + q2 (20 - 3 (q1 + q2))
```

```
In[132]:= D[pi1, q1]
```

```
Out[132]= 16 - 3 q1 - 3 (q1 + q2)
```

```
In[133]:= D[pi2, q2]
```

```
Out[133]= 16 - 3 q2 - 3 (q1 + q2)
```

```
In[134]:= Solve[{16 - 3 q1 - 3 (q1 + q2) == 0, 16 - 3 q2 - 3 (q1 + q2) == 0}, {q1, q2}]
```

```
Out[134]= {{q1 -> 16/9, q2 -> 16/9}}
```

■ (b)

```
In[135]:= Clear[p, Q, q1, q2, q3, pi1, pi2, pi3]
```

```
In[136]:= Q = q1 + q2 + q3
```

```
p = 20 - 3 Q
```

```
pi1 = p q1 - 4 q1
```

```
pi2 = p q2 - 4 q2
```

```
pi3 = p q3 - 4 q3
```

```
Out[136]= q1 + q2 + q3
```

```
Out[137]= 20 - 3 (q1 + q2 + q3)
```

```
Out[138]= -4 q1 + q1 (20 - 3 (q1 + q2 + q3))
```

```
Out[139]= -4 q2 + q2 (20 - 3 (q1 + q2 + q3))
```

```
Out[140]= -4 q3 + q3 (20 - 3 (q1 + q2 + q3))
```

```
In[141]:= D[pi1, q1]
```

```
Out[141]= 16 - 3 q1 - 3 (q1 + q2 + q3)
```

```
In[142]:= D[pi2, q2]
```

```
Out[142]= 16 - 3 q2 - 3 (q1 + q2 + q3)
```

```
In[143]:= D[pi3, q3]
```

```
Out[143]= 16 - 3 q3 - 3 (q1 + q2 + q3)
```

```
In[144]:= Solve[{16 - 3 q1 - 3 (q1 + q2 + q3) == 0,
                  16 - 3 q2 - 3 (q1 + q2 + q3) == 0, 16 - 3 q3 - 3 (q1 + q2 + q3) == 0}, {q1, q2, q3}]
```

```
Out[144]= {{q1 -> 4/3, q2 -> 4/3, q3 -> 4/3}}
```

■ (c)

```
In[145]:= Clear[p, Q, q1, q2, pi1, pi2]
```

```
In[146]:= Q = q1 + q2
          p = 20 - 3 Q
          pi1 = p q1 - 4 q1^2
          pi2 = p q2 - 4 q2^2
```

```
Out[146]= q1 + q2
```

```
Out[147]= 20 - 3 (q1 + q2)
```

```
Out[148]= -4 q1^2 + q1 (20 - 3 (q1 + q2))
```

```
Out[149]= -4 q2^2 + q2 (20 - 3 (q1 + q2))
```

```
In[150]:= D[pi1, q1]
```

```
Out[150]= 20 - 11 q1 - 3 (q1 + q2)
```

```
In[151]:= D[pi2, q2]
```

```
Out[151]= 20 - 11 q2 - 3 (q1 + q2)
```

```
In[152]:= Solve[{20 - 11 q1 - 3 (q1 + q2) == 0, 20 - 11 q2 - 3 (q1 + q2) == 0}, {q1, q2}]
```

```
Out[152]= {{q1 -> 20/17, q2 -> 20/17}}
```

■ (d)

```
In[153]:= Clear[p, Q, q1, q2, q3, pi1, pi2, pi3]
```

```
In[154]:= Q = q1 + q2 + q3
          p = 20 - 3 Q
          pi1 = p q1 - 4 q1^2
          pi2 = p q2 - 4 q2^2
          pi3 = p q3 - 4 q3^2
```

```
Out[154]= q1 + q2 + q3
```

```
Out[155]= 20 - 3 (q1 + q2 + q3)
```

```
Out[156]= -4 q1^2 + q1 (20 - 3 (q1 + q2 + q3))
```

```
Out[157]= -4 q2^2 + q2 (20 - 3 (q1 + q2 + q3))
```

```
Out[158]= -4 q3^2 + q3 (20 - 3 (q1 + q2 + q3))
```

```

In[159]:= D[pi1, q1]
Out[159]= 20 - 11 q1 - 3 (q1 + q2 + q3)

In[160]:= D[pi2, q2]
Out[160]= 20 - 11 q2 - 3 (q1 + q2 + q3)

In[161]:= D[pi3, q3]
Out[161]= 20 - 11 q3 - 3 (q1 + q2 + q3)

In[162]:= Solve[{20 - 11 q1 - 3 (q1 + q2 + q3) == 0,
                  20 - 11 q2 - 3 (q1 + q2 + q3) == 0, 20 - 11 q3 - 3 (q1 + q2 + q3) == 0}, {q1, q2, q3}]
Out[162]= {{q1 -> 1, q2 -> 1, q3 -> 1}}

```

■ (ii)

Here we are comparing models (a) and (b).

```

In[163]:= Clear[p, Q, q1, q2, pi1, pi2]

In[164]:= Solve[16 - 3 q1 - 3 (q1 + q2) == 0, q1]
Out[164]= {{q1 -> 1/6 (16 - 3 q2)}}

In[165]:= Solve[16 - 3 q2 - 3 (q1 + q2) == 0, q2]
Out[165]= {{q2 -> 1/6 (16 - 3 q1)}}

```

The two reaction functions are therefore:

$$q_1(t) = \frac{8}{3} - \frac{1}{2} q_2(t-1)$$

$$q_2(t) = \frac{8}{3} - \frac{1}{2} q_1(t-1)$$

If firm 1 is the monopolist then the initial point is (8/3, 0).

```

In[166]:= RSolve[{q1[t] == (8/3) - (1/2) q2[t-1],
                  q2[t] == (8/3) - (1/2) q1[t-1], q1[0] == 8/3, q2[0] == 0}, {q1[t], q2[t]}, t]
Out[166]= {{q1[t] -> 1/9 2^{2-t} (3 - (-1)^t + 2^{2+t}), q2[t] -> 1/9 2^{2-t} (-3 - (-1)^t + 2^{2+t})}}

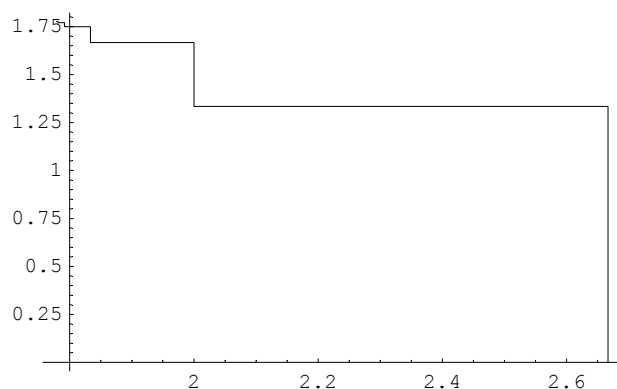
In[167]:= q1[t_] := 1/9 2^{2-t} (3 - (-1)^t + 2^{2+t})

In[168]:= q2[t_] := 1/9 2^{2-t} (-3 - (-1)^t + 2^{2+t})

In[169]:= points8a = Table[{q1[t], q2[t]}, {t, 0, 10}];

```

```
In[170]:= ListPlot[points8a, PlotJoined → True, AxesOrigin → {1.8, 0}];
```



```
In[171]:= Clear[p, Q, q1, q2, q3, pi1, pi2, pi3]
```

```
In[172]:= Solve[16 - 3 q1 - 3 (q1 + q2 + q3) == 0, q1]
```

```
Out[172]= {{q1 → 1/6 (16 - 3 q2 - 3 q3)}}
```

```
In[173]:= Solve[16 - 3 q2 - 3 (q1 + q2 + q3) == 0, q2]
```

```
Out[173]= {{q2 → 1/6 (16 - 3 q1 - 3 q3)}}
```

```
In[174]:= Solve[16 - 3 q3 - 3 (q1 + q2 + q3) == 0, q3]
```

```
Out[174]= {{q3 → 1/6 (16 - 3 q1 - 3 q2)}}
```

The three reaction functions are therefore:

$$q_1(t) = \frac{8}{3} - \frac{1}{2} q_2(t-1) - \frac{1}{2} q_3(t-1)$$

$$q_2(t) = \frac{8}{3} - \frac{1}{2} q_1(t-1) - \frac{1}{2} q_3(t-1)$$

$$q_3(t) = \frac{8}{3} - \frac{1}{2} q_1(t-1) - \frac{1}{2} q_2(t-1)$$

If firm 1 is the monopolist then the initial point is (8/3, 0, 0).

```
In[175]:= RSolve[{q1[t] == (8/3) - (1/2) q2[t-1] - (1/2) q3[t-1],
  q2[t] == (8/3) - (1/2) q1[t-1] - (1/2) q3[t-1],
  q3[t] == (8/3) - (1/2) q1[t-1] - (1/2) q2[t-1],
  q1[0] == 8/3, q2[0] == 0, q3[0] == 0}, {q1[t], q2[t], q3[t]}, t]
```

```
Out[175]= {{q1[t] → -1/9 2^{2-t} (-4 + (-2)^t - 3 2^t),
  q2[t] → 4/9 (3 - 2^{-t} (2 + (-2)^t)), q3[t] → 4/9 (3 - 2^{-t} (2 + (-2)^t))}}
```

```
In[176]:= q1[t_] := -1/9 2^{2-t} (-4 + (-2)^t - 3 2^t)
```

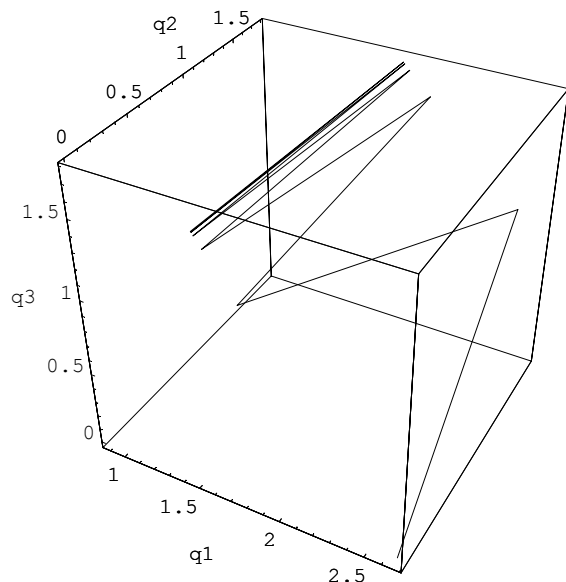
```
In[177]:= q2[t_] := 4/9 (3 - 2^{-t} (2 + (-2)^t))
```

```
In[178]:= q3[t_] := 4/9 (3 - 2^{-t} (2 + (-2)^t))
```

```
In[179]:= points8b = Table[{q1[t], q2[t], q3[t]}, {t, 0, 10}];
```

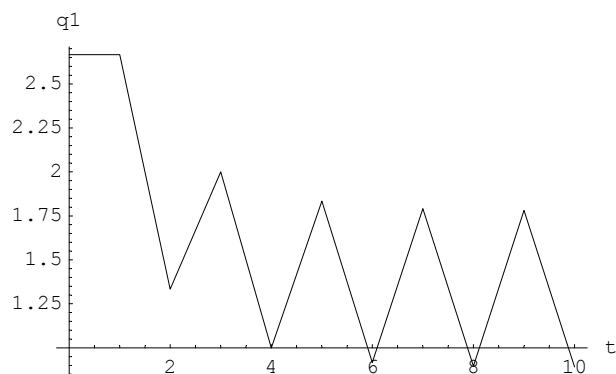
```
General::spell1 :  
Possible spelling error: new symbol name "points8b" is similar to existing symbol "points8a".
```

```
In[180]:= ScatterPlot3D[points8b, PlotJoined → True, AxesLabel → {"q1", "q2", "q3"}];
```



```
In[181]:= points8b1 = Table[{t, q1[t]}, {t, 0, 10}];
```

```
In[182]:= ListPlot[points8b1, PlotJoined → True, AxesLabel → {"t", "q1"}];
```



When $n = 2$ the system was stable. However, for $n = 3$ the system soon begins to oscillate. Here we show it only for $q1$ but it applies equally to $q2$ and $q3$, which is apparent from the presence of $(-1)^t$ in the solutions.

■ (iii)

Part (ii) already compares (a) and (b) and so here we consider just (c) and (d).

```
In[183]:= Clear[p, Q, q1, q2, pi1, pi2]
```

```
In[184]:= Solve[20 - 11 q1 - 3 (q1 + q2) == 0, q1]
```

```
Out[184]= {{q1 →  $\frac{1}{14} (20 - 3 q2)$ }}
```

```
In[185]:= Solve[20 - 11 q2 - 3 (q1 + q2) == 0, q2]
```

```
Out[185]= {{q2 -> 1/14 (20 - 3 q1)}}
```

Hence the reaction curves are:

$$q_1(t) = \frac{10}{7} - \frac{3}{14} q_2(t-1)$$

$$q_2(t) = \frac{10}{7} - \frac{3}{14} q_1(t-1)$$

If firm 1 is a monopoly then the initial point is (10/7, 0).

```
In[186]:= RSolve[{q1[t] == (10/7) - (3/14) q2[t-1],
                  q2[t] == (10/7) - (3/14) q1[t-1], q1[0] == 10/7, q2[0] == 0}, {q1[t], q2[t]}, t]
```

```
Out[186]= {{q1[t] -> 5/17 2^-t 7^-1-t (17 3^t + 2^2+t 7^1+t - 11 3^t e^i pi t),
            q2[t] -> 5/119 (28 - 11 (-3/14)^t - 17 (3/14)^t)}}
```

```
In[187]:= q1[t_] := 5/17 2^-t 7^-1-t (17 3^t + 2^2+t 7^1+t - 11 3^t e^i pi t)
```

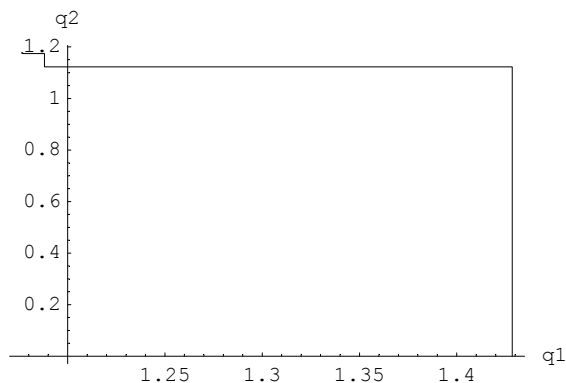
```
In[188]:= q2[t_] := 5/119 (28 - 11 (-3/14)^t - 17 (3/14)^t)
```

```
In[189]:= points8c = Table[{q1[t], q2[t]}, {t, 0, 10}];
```

General::spell :

Possible spelling error: new symbol name "points8c" is similar to existing symbols {points8a, points8b}.

```
In[190]:= ListPlot[points8c, PlotJoined -> True, AxesLabel -> {"q1", "q2"}];
```



```
In[191]:= Clear[p, Q, q1, q2, q3, pi1, pi2, pi3]
```

```
In[192]:= Solve[20 - 11 q1 - 3 (q1 + q2 + q3) == 0, q1]
```

```
Out[192]= {{q1 -> 1/14 (20 - 3 q2 - 3 q3)}}
```

```
In[193]:= Solve[20 - 11 q2 - 3 (q1 + q2 + q3) == 0, q2]
```

```
Out[193]= {{q2 -> 1/14 (20 - 3 q1 - 3 q3)}}
```

```
In[194]:= Solve[20 - 11 q3 - 3 (q1 + q2 + q3) == 0, q3]
```

```
Out[194]= {{q3 -> 1/14 (20 - 3 q1 - 3 q2)}}
```

Hence the reaction curves are:

$$q_1(t) = \frac{10}{7} - \frac{3}{14} q_2(t-1) - \frac{3}{14} q_3(t-1)$$

$$q_2(t) = \frac{10}{7} - \frac{3}{14} q_1(t-1) - \frac{3}{14} q_3(t-1)$$

$$q_3(t) = \frac{10}{7} - \frac{3}{14} q_1(t-1) - \frac{3}{14} q_2(t-1)$$

With firm 1 the monopolist, then the initial point is (10/7, 0, 0).

```
In[195]:= RSolve[{q1[t] == (10/7) - (3/14) q2[t-1] - (3/14) q3[t-1],
  q2[t] == (10/7) - (3/14) q1[t-1] - (3/14) q3[t-1],
  q3[t] == (10/7) - (3/14) q1[t-1] - (3/14) q2[t-1],
  q1[0] == 10/7, q2[0] == 0, q3[0] == 0}, {q1[t], q2[t], q3[t]}, t]
```

```
Out[195]= {{q1[t] -> -1/3 2^-t 7^-1-t (11 (-6)^t - 20 3^t - 3 2^t 7^1+t),
  q2[t] -> -1/3 2^-t 7^-1-t (11 (-6)^t + 10 3^t - 3 2^t 7^1+t),
  q3[t] -> -1/3 2^-t 7^-1-t (11 (-6)^t + 10 3^t - 3 2^t 7^1+t)}}
```

```
In[196]:= q1[t_] := -1/3 2^-t 7^-1-t (11 (-6)^t - 20 3^t - 3 2^t 7^1+t)
```

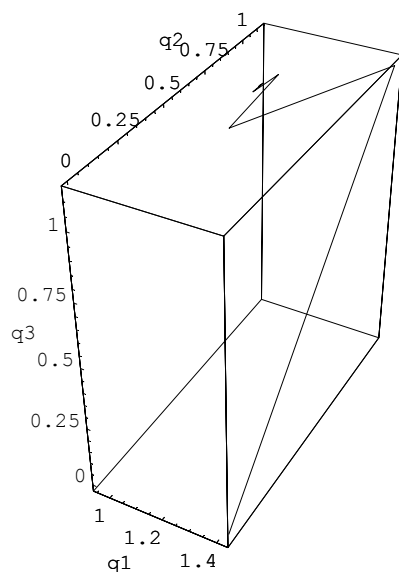
```
In[197]:= q2[t_] := -1/3 2^-t 7^-1-t (11 (-6)^t + 10 3^t - 3 2^t 7^1+t)
```

```
In[198]:= q3[t_] := -1/3 2^-t 7^-1-t (11 (-6)^t + 10 3^t - 3 2^t 7^1+t)
```

```
In[199]:= points8d = Table[{q1[t], q2[t], q3[t]}, {t, 0, 10}];
```

```
General::spell : Possible spelling error: new symbol
name "points8d" is similar to existing symbols {points8a, points8b, points8c}.
```

```
In[200]:= ScatterPlot3D[points8d, PlotJoined → True, AxesLabel → {"q1", "q2", "q3"}];
```

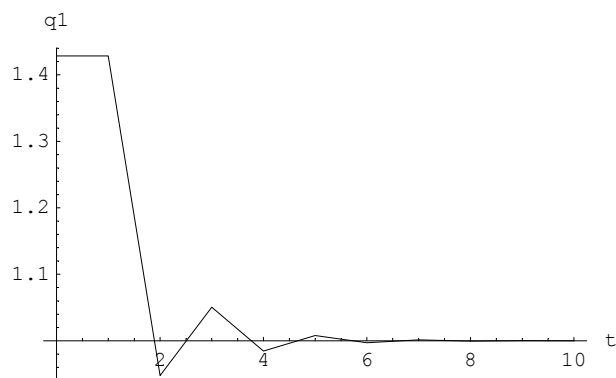


```
In[201]:= points8d1 = Table[{t, q1[t]}, {t, 0, 10}];
```

General::spell1 :

Possible spelling error: new symbol name "points8d1" is similar to existing symbol "points8b1".

```
In[202]:= ListPlot[points8d1, PlotJoined → True, AxesLabel → {"t", "q1"}];
```



When marginal costs are not constant then the system is more stable and equilibrium is reached sooner. The oscillatory pattern observed for $n = 3$ under constant marginal costs now disappears and the system is stable.

à Question 9

```
In[203]:= Clear[p, Q, q1, q2, pi1, pi2]
```

■ (i)

The Cournot solution is the same as for model 8(i)(a), namely $(\frac{16}{9}, \frac{16}{9})$.

■ (ii)

In question 8(ii) we derived the reaction functions, which in their continuous dynamic form are:

$$x_1(t) = \frac{8}{3} - \frac{1}{2} q_2(t)$$

$$x_2(t) = \frac{8}{3} - \frac{1}{2} q_1(t)$$

Hence

$$q_1'(t) = 0.2 \left(\frac{8}{3} - \frac{1}{2} q_2(t) - q_1(t) \right)$$

$$q_2'(t) = 0.2 \left(\frac{8}{3} - \frac{1}{2} q_1(t) - q_2(t) \right)$$

```
In[204]:= Simplify[0.2 ((8/3) - (1/2) q2[t] - q1[t])]
```

```
Out[204]= 0.533333 - 0.2 q1[t] - 0.1 q2[t]
```

```
In[205]:= Simplify[0.2 ((8/3) - (1/2) q1[t] - q2[t])]
```

```
Out[205]= 0.533333 - 0.1 q1[t] - 0.2 q2[t]
```

The matrix of the system is therefore

```
In[206]:= mA = {{-0.2, -0.1}, {-0.1, -0.2}}
```

```
Out[206]= {{-0.2, -0.1}, {-0.1, -0.2}}
```

```
In[207]:= Tr[mA]
```

```
Out[207]= -0.4
```

```
In[208]:= Det[mA]
```

```
Out[208]= 0.03
```

```
In[209]:= Tr[mA]^2 - 4 Det[mA]
```

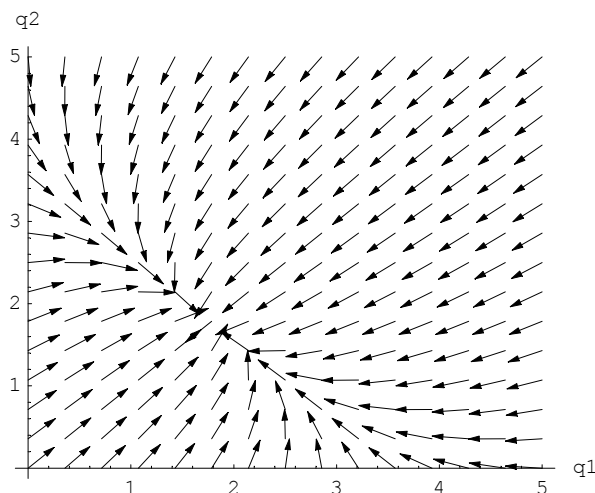
```
Out[209]= 0.04
```

Hence the equilibrium is dynamically stable.

■ (iii)

The initial points are $(8/3, 0)$ for firm 1 a monopolist and $(0, 8/3)$ for firm 2 being a monopolist and $(0, 0)$ indicating both firms are to enter the industry.

```
In[210]:= arrows9 = PlotVectorField[{0.2 ((8/3) - (1/2) q2 - q1), 0.2 ((8/3) - (1/2) q1 - q2)},
    {q1, 0, 5}, {q2, 0, 5}, Axes → True, AxesLabel → {"q1", "q2"},
    ScaleFunction → (1 &), AspectRatio → 0.8];
```



```
In[211]:= path91 = NDSolve[{q1'[t] == 0.2 ((8/3) - (1/2) q2[t] - q1[t]), q2'[t] ==
    0.2 ((8/3) - (1/2) q1[t] - q2[t]), q1[0] == 8/3, q2[0] == 0}, {q1, q2}, {t, 0, 20}]
```

```
Out[211]= {{q1 → InterpolatingFunction[{{0., 20.}}, <>],
    q2 → InterpolatingFunction[{{0., 20.}}, <>]}}
```

```
In[212]:= path92 = NDSolve[{q1'[t] == 0.2 ((8/3) - (1/2) q2[t] - q1[t]), q2'[t] ==
    0.2 ((8/3) - (1/2) q1[t] - q2[t]), q1[0] == 0, q2[0] == 8/3}, {q1, q2}, {t, 0, 20}]
```

```
Out[212]= {{q1 → InterpolatingFunction[{{0., 20.}}, <>],
    q2 → InterpolatingFunction[{{0., 20.}}, <>]}}
```

```
In[213]:= path93 = NDSolve[{q1'[t] == 0.2 ((8/3) - (1/2) q2[t] - q1[t]), q2'[t] ==
    0.2 ((8/3) - (1/2) q1[t] - q2[t]), q1[0] == 0, q2[0] == 0}, {q1, q2}, {t, 0, 20}]
```

```
Out[213]= {{q1 → InterpolatingFunction[{{0., 20.}}, <>],
    q2 → InterpolatingFunction[{{0., 20.}}, <>]}}
```

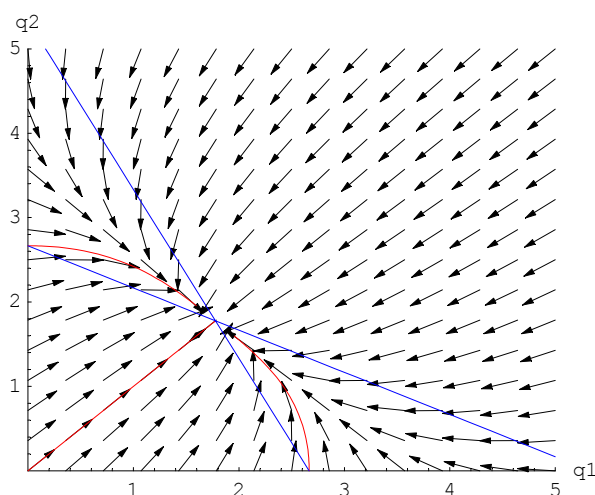
```
In[214]:= traj91 = ParametricPlot[
    Evaluate[{q1[t], q2[t]} /. path91], {t, 0, 20}, DisplayFunction → Identity,
    PlotStyle → {{RGBColor[1, 0, 0]}, {Thickness[.02]}}];
```

```
In[215]:= traj92 = ParametricPlot[
    Evaluate[{q1[t], q2[t]} /. path92], {t, 0, 20}, DisplayFunction → Identity,
    PlotStyle → {{RGBColor[1, 0, 0]}, {Thickness[.02]}}];
```

```
In[216]:= traj93 = ParametricPlot[
    Evaluate[{q1[t], q2[t]} /. path93], {t, 0, 20}, DisplayFunction → Identity,
    PlotStyle → {{RGBColor[1, 0, 0]}, {Thickness[.02]}}];
```

```
In[217]:= lines9 = Plot[{16/3 - 2 q1, 8/3 - (1/2) q1}, {q1, 0, 5}, PlotRange → {0, 5},
    PlotStyle → {{RGBColor[0, 0, 1]}, {RGBColor[0, 0, 1]}, {Thickness[.02]}},
    DisplayFunction → Identity];
```

```
In[218]:= Show[arrows9, traj91, traj92, traj93, lines9, PlotRange -> {{0, 5}, {0, 5}}];
```



The diagram reveals the stability of the Cournot solution.

à Question 10

```
In[219]:= Clear[p, Q, q1, q2, pi1, pi2, mA]
```

■ (i)

The Cournot solution is the same as for model 8(i)(c), namely $(\frac{20}{17}, \frac{20}{17})$.

■ (ii)

In question 8(iii) we derived the reaction functions, which in their continuous dynamic form are:

$$x_1(t) = \frac{10}{7} - \frac{3}{14} q_2(t)$$

$$x_2(t) = \frac{10}{7} - \frac{3}{14} q_1(t)$$

Hence

$$q_1'(t) = 0.2 \left(\frac{10}{7} - \frac{3}{14} q_2(t) - q_1(t) \right)$$

$$q_2'(t) = 0.2 \left(\frac{10}{7} - \frac{3}{14} q_1(t) - q_2(t) \right)$$

```
In[220]:= Simplify[0.2 ((10 / 7) - (3 / 14) q2[t] - q1[t])]
```

```
Out[220]= 0.285714 - 0.2 q1[t] - 0.0428571 q2[t]
```

```
In[221]:= Simplify[0.2 ((10 / 7) - (3 / 14) q1[t] - q2[t])]
```

```
Out[221]= 0.285714 - 0.0428571 q1[t] - 0.2 q2[t]
```

The matrix of the system is therefore

```
In[222]:= mA = {{-0.2, -0.0428571}, {-0.0428571, -0.2}}
```

```
Out[222]= {{-0.2, -0.0428571}, {-0.0428571, -0.2}}
```

```
In[223]:= Tr[mA]
```

```
Out[223]= -0.4
```

```
In[224]:= Det[mA]
```

```
Out[224]= 0.0381633
```

```
In[225]:= Tr[mA]^2 - 4 Det[mA]
```

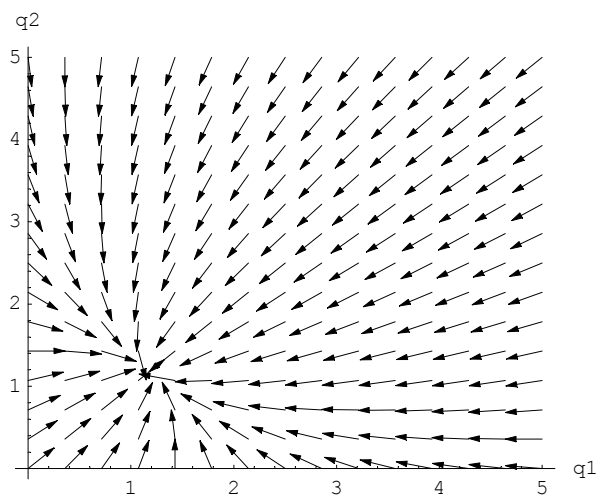
```
Out[225]= 0.00734692
```

Hence the equilibrium is dynamically stable.

■ (iii)

The initial points are $(\frac{10}{7}, 0)$ for firm 1 a monopolist and $(0, \frac{10}{7})$ for firm 2 being a monopolist and $(0, 0)$ indicating both firms are to enter the industry.

```
In[226]:= arrows10 =  
  PlotVectorField[{0.2 ((10/7) - (3/14) q2 - q1), 0.2 ((10/7) - (3/14) q1 - q2)},  
    {q1, 0, 5}, {q2, 0, 5}, Axes → True, AxesLabel → {"q1", "q2"},  
    ScaleFunction → (1 &), AspectRatio → 0.8];
```



```
In[227]:= path101 = NDSolve[{q1'[t] == 0.2 ((10/7) - (3/14) q2[t] - q1[t]),  
  q2'[t] == 0.2 ((10/7) - (3/14) q1[t] - q2[t]),  
  q1[0] == 10/7, q2[0] == 0}, {q1, q2}, {t, 0, 20}]
```

```
Out[227]= {{q1 → InterpolatingFunction[{{0., 20.}}, <>],  
  q2 → InterpolatingFunction[{{0., 20.}}, <>]}}
```

```

In[228]:= path102 = NDSolve[{q1'[t] == 0.2 ((10/7) - (3/14) q2[t] - q1[t]),
    q2'[t] == 0.2 ((10/7) - (3/14) q1[t] - q2[t]),
    q1[0] == 0, q2[0] == 10/7}, {q1, q2}, {t, 0, 20}]

Out[228]= {{q1 → InterpolatingFunction[{{0., 20.}}, <>],
    q2 → InterpolatingFunction[{{0., 20.}}, <>]}}

In[229]:= path103 = NDSolve[{q1'[t] == 0.2 ((10/7) - (3/14) q2[t] - q1[t]), q2'[t] ==
    0.2 ((10/7) - (3/14) q1[t] - q2[t]), q1[0] == 0, q2[0] == 0}, {q1, q2}, {t, 0, 20}]

Out[229]= {{q1 → InterpolatingFunction[{{0., 20.}}, <>],
    q2 → InterpolatingFunction[{{0., 20.}}, <>]}}

In[230]:= traj101 = ParametricPlot[
    Evaluate[{q1[t], q2[t]} /. path101], {t, 0, 20}, DisplayFunction → Identity,
    PlotStyle → {{RGBColor[1, 0, 0]}, {Thickness[.02]}}];

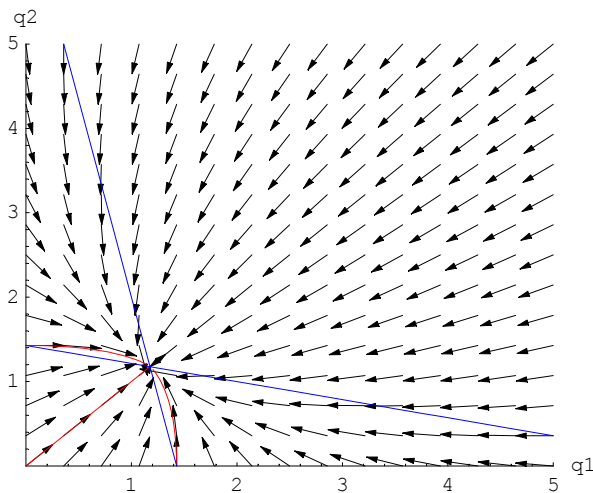
In[231]:= traj102 = ParametricPlot[
    Evaluate[{q1[t], q2[t]} /. path102], {t, 0, 20}, DisplayFunction → Identity,
    PlotStyle → {{RGBColor[1, 0, 0]}, {Thickness[.02]}}];

In[232]:= traj103 = ParametricPlot[
    Evaluate[{q1[t], q2[t]} /. path103], {t, 0, 20}, DisplayFunction → Identity,
    PlotStyle → {{RGBColor[1, 0, 0]}, {Thickness[.02]}}];

In[233]:= lines10 = Plot[{20/3 - (14/3) q1, 10/7 - (3/14) q1}, {q1, 0, 5}, PlotRange → {0, 5},
    PlotStyle → {{RGBColor[0, 0, 1]}, {RGBColor[0, 0, 1]}, {Thickness[.02]}}],
    DisplayFunction → Identity];

In[234]:= Show[arrows10, traj101, traj102, traj103, lines10, PlotRange → {{0, 5}, {0, 5}}];

```



The diagram reveals the stability of the Cournot solution for the chosen initial points.

```

In[235]:= DSolve[{q1'[t] == 0.2 ((10/7) - (3/14) q2[t] - q1[t]),
    q2'[t] == 0.2 ((10/7) - (3/14) q1[t] - q2[t]),
    q1[0] == q10, q2[0] == q20}, {q1[t], q2[t]}, t]

Out[235]= {{q1[t] → 0.0294118 e-0.242857 t
    (-40. + 40. e0.242857 t + 17. q10 + 17. e0.0857143 t q10 + 17. q20 - 17. e0.0857143 t q20),
    q2[t] → 0.0294118 e-0.242857 t
    (-40. + 40. e0.242857 t + 17. q10 - 17. e0.0857143 t q10 + 17. q20 + 17. e0.0857143 t q20)}}

```

Since all coefficients of q_{10} and q_{20} involve $e^{-0.242857t}$, $e^{0.242857t}$, or $e^{0.0857143t}$ then the system converges on the Cournot equilibrium regardless of the initial values.

à Questions 11-15

These questions are more easily done with a spreadsheet and are therefore not undertaken here with *Mathematica*.