

# Fundamentals of High-Frequency CMOS Analog Integrated Circuits

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## Chapter 5

### RF Oscillators

# Classification of oscillators

## a) Non sinusoidal oscillators

- Relaxation oscillators (charge-discharge osc.)
- Astable flip-flops
- Ring oscillators

## b) Sinusoidal oscillators

- R-C oscillators
- L-C oscillators
  - Lumped or distributed L-C oscillators
  - Crystal oscillators

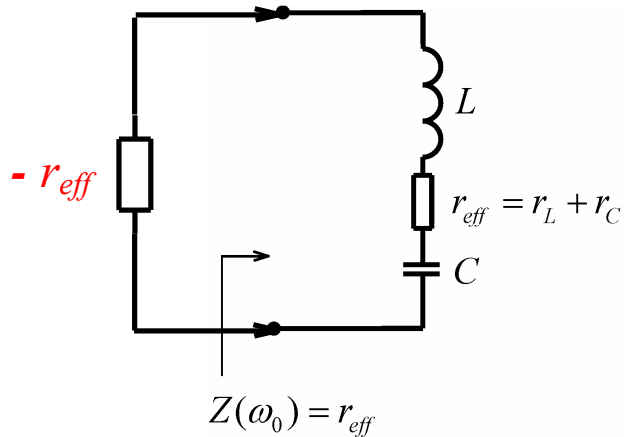
## Principles of oscillation:

### a) Negative resistance oscillators

### b) Feedback oscillators

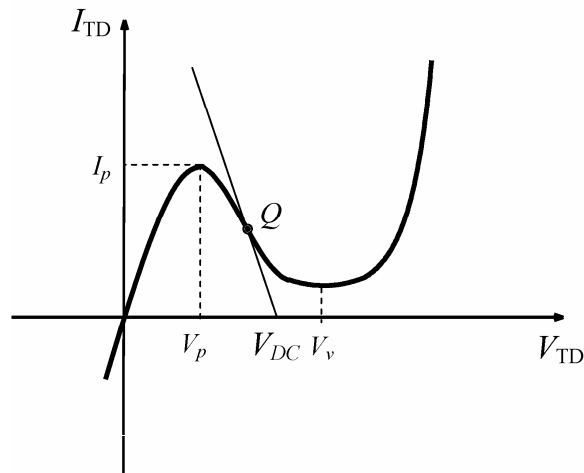
# Negative resistance oscillators

## 1. Oscillators operating at series resonance:

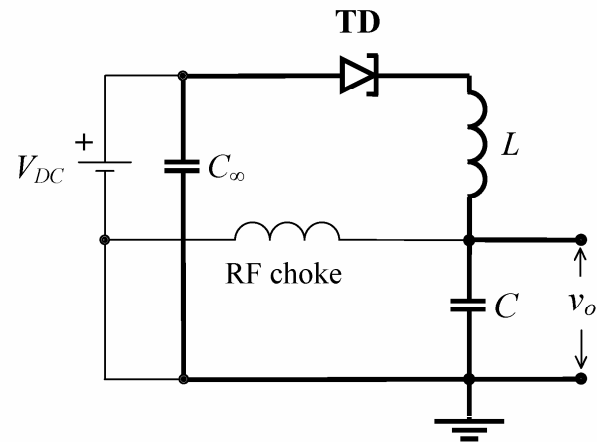


$$\omega_0 = \sqrt{\frac{1}{LC}}$$

### Example: Tunnel diode oscillator

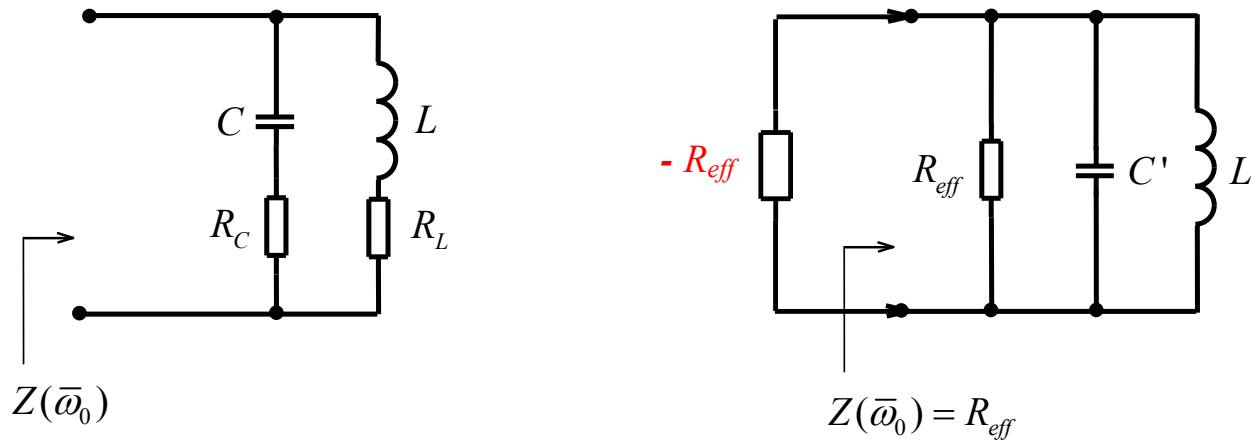


(a)



(b)

## 2. Oscillators operating at parallel resonance:



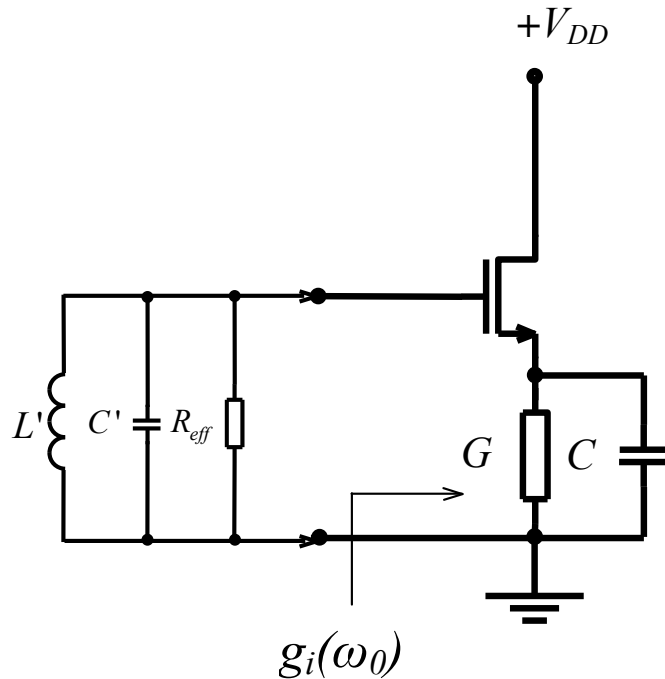
$$\omega_{(Re)} = \sqrt{\frac{1}{L'C'}} = \sqrt{\frac{1}{LC}} \times \sqrt{\frac{L - Cr_L^2}{L - Cr_C^2}}$$

$$C' = \frac{C}{1 + \omega_{(Re)}^2 C^2 r_C^2} \quad L' = L + \frac{r_L^2}{\omega_{(Re)}^2 L}$$

$$G_{eff} = \frac{1}{r_C(Q_C^2 + 1)} + \frac{1}{r_L(Q_L^2 + 1)} = \frac{1}{R_{eff}}$$

# Examples to negative resistance oscillators:

a) With a single ended negative resistance circuit

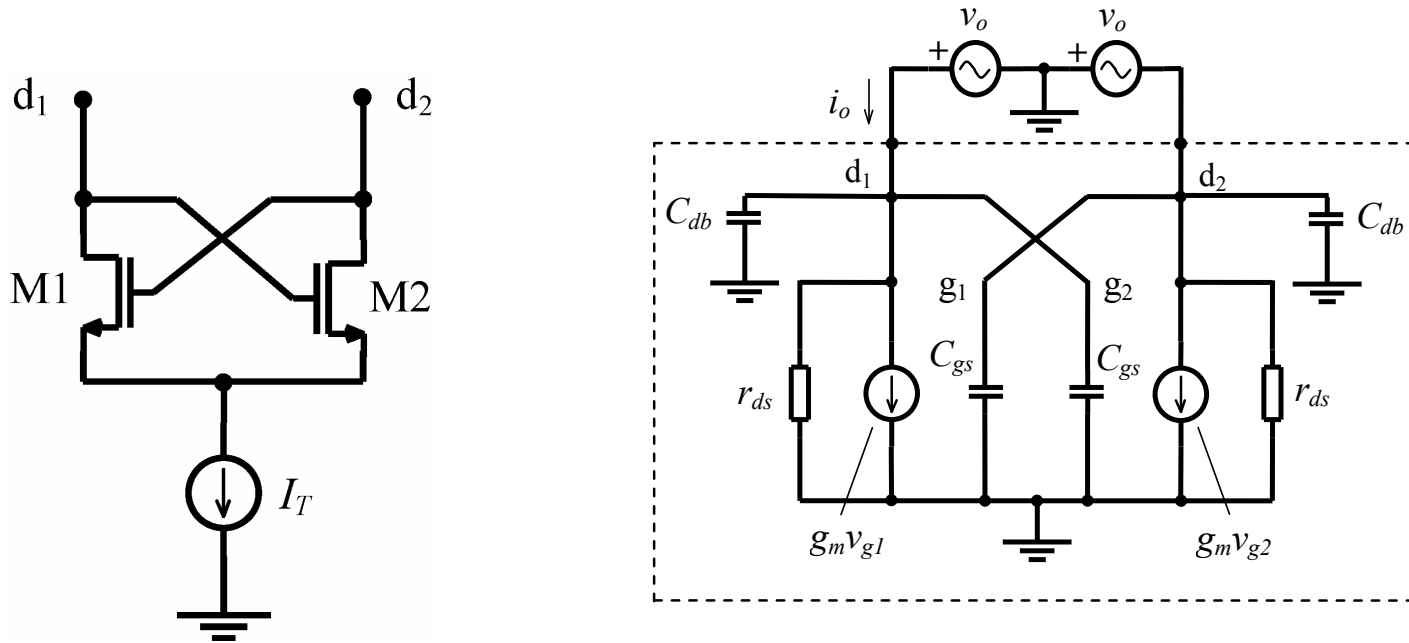


$$g_i(\omega) = \frac{C_{gs}}{(C_{gs} + C)^2} (GC_{gs} - g_m C) \frac{1}{1 + (\omega_p / \omega)^2}$$

$$\omega_p = \frac{(g_m + G)}{(C_{gs} + C)}$$

$$g_i(\omega_0) = -\frac{1}{R_{eff}}$$

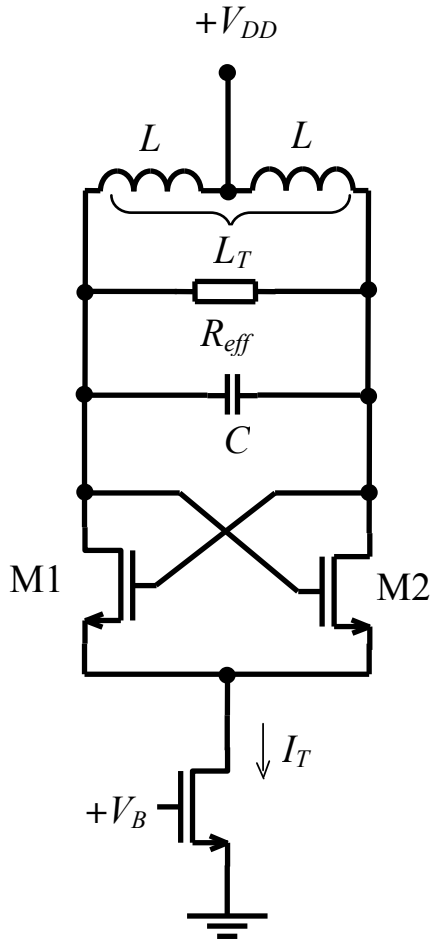
b) With a differential negative resistance circuit:



(Small signal eq. circuit to calculate  $d_1$  -  $d_2$  output resistance)

$$y_o = -\frac{1}{2}(g_m - g_{ds}) + s\frac{1}{2}(C_{gs} + C_{db})$$

$$r_o = -\frac{2}{(g_m - g_{ds})} \cong -\frac{2}{g_m} \Rightarrow g_o \cong -\frac{g_m}{2}$$



$$\omega_0 = \frac{1}{\sqrt{C_T L_T}}$$

$$C_T = C + \frac{1}{2}(C_{gs} + C_{db})$$

$$L_T = 2L(1 + k)$$

The condition of oscillation:

$$|g_o| \geq \frac{1}{R_{eff}} \Rightarrow g_m \geq \frac{2}{R_{eff}}$$

Note that:

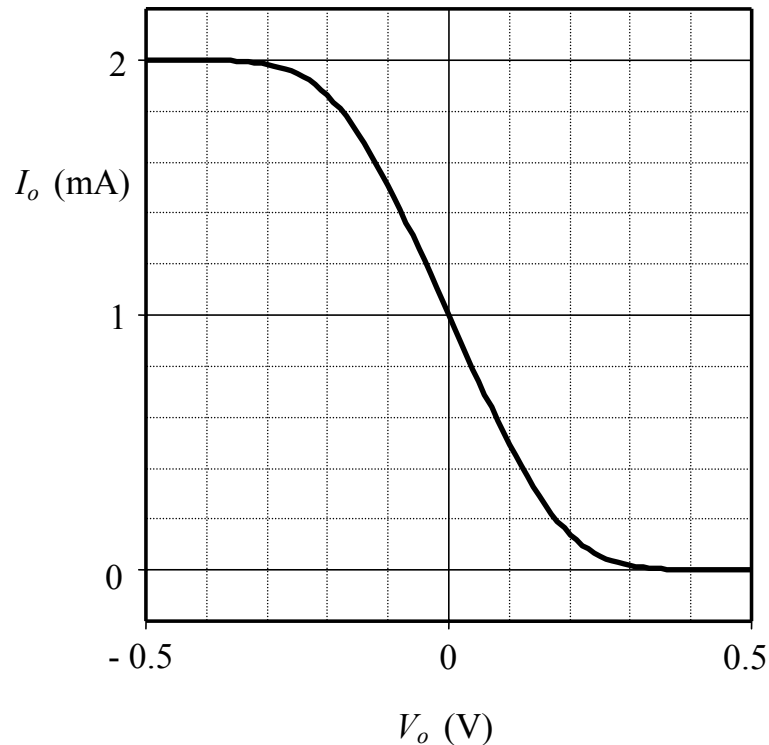
- If M1 and M2 operate without velocity saturation ;

$$g_m = \sqrt{2\mu C_{ox} (W / L) I_D} \quad (\text{can be controlled with } I_T !)$$

- If M1 and M2 operate with velocity saturation ;

$$g_m = kW C_{ox} v_{sat} \quad (\text{can not be controlled with } I_T !)$$

## Effects of the non-linearity:

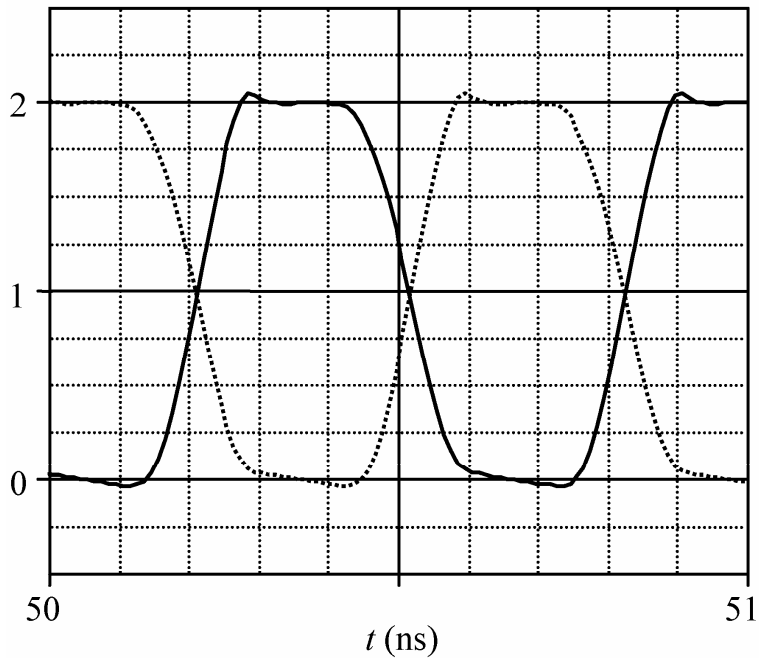


- Slope is maximum and equal to  $g_o$  at mid-point.
- Therefore to guarantee the oscillation  $g_m$  must be 1..10% higher then the calculated value.
- The saturation of the current at both ends results in flattening of the current waveform at peaks.

## Simulation results :

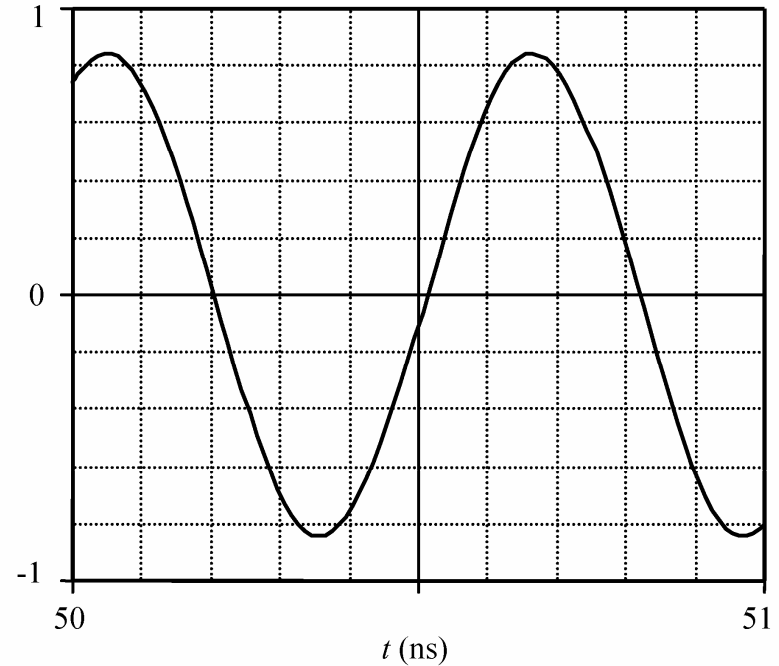
$$(f_0 = 1,6 \text{ GHz}, L = 5 \text{ nH}, Q_L = 7, I_T = 2 \text{ mA}, (W / L) = 108)$$

$I_{D1}, I_{D2} \text{ (mA)}$



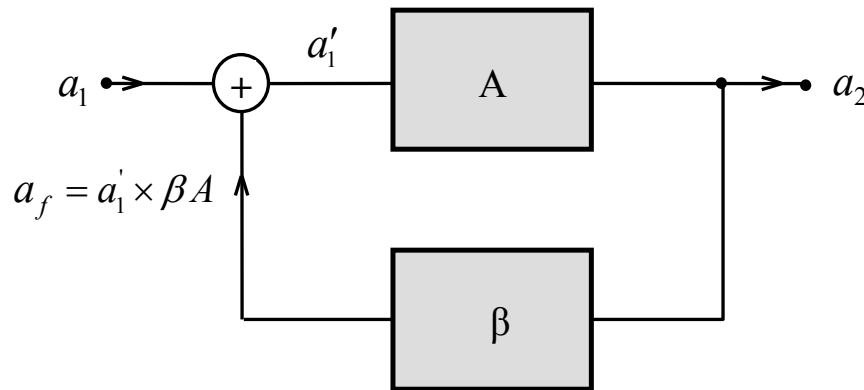
(a)

$v_o \text{ (V)}$



(b)

# Feedback Oscillators (H. Georg Barkhausen, 1921)



$$A = \frac{a_2}{a_1'} , \quad \beta = \frac{a_f}{a_2} , \quad a_1' = a_1 + a_f , \quad A_f = \frac{a_2}{a_1}$$

$$A_f = \frac{A}{(1 - \beta A)}$$

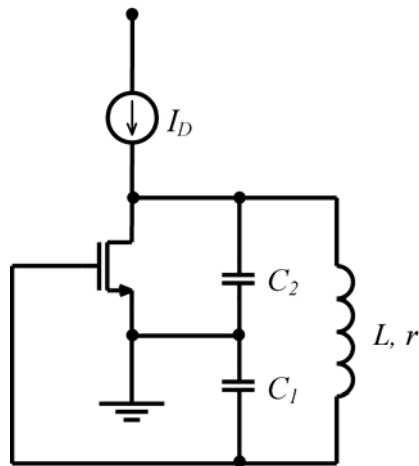
Condition of oscillation:  $\beta A = 1 + j.0$

$\Downarrow$

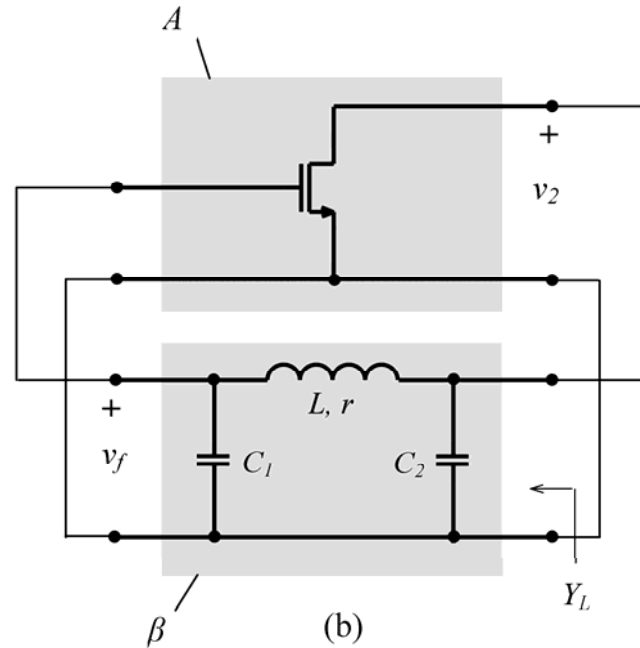
$$\text{Re}\{\beta A\} = 1 \quad \text{and} \quad \text{Im}\{\beta A\} = 0$$

$$\text{or} \quad |\beta A| = 1 \quad \text{and} \quad \varphi(\beta A) = 0$$

## Example: The Colpitts oscillator



(a)



(b)

$$Y_L = sC_2 + \frac{1}{sL + r + \frac{1}{sC_1}} = \frac{s^3 LC_1 C_2 + s^2 C_1 C_2 r + s(C_1 + C_2)}{s^2 LC_1 + sC_1 r + 1}$$

$$A_v = -g_m \frac{1}{(g_{ds} + Y_L)}$$

$$\beta = \frac{1}{s^2 LC_1 + sC_1 r + 1}$$

$$\beta A_v = -g_m \frac{1}{s^3 LC_1 C_2 + s^2 (C_1 C_2 r + LC_1 g_{ds}) + s[(C_1 + C_2) + rC_1 g_{ds}] + g_{ds}}$$

$$\text{Im}\{\beta A_v\} = 0 \quad \Rightarrow \quad \omega_{osc} = \omega_0 \sqrt{1 + r \cdot g_{ds} \frac{C_1}{C_1 + C_2}}$$

$$\text{Re}\{\beta A_v\} = +1, |\beta A_v| = 1 \quad \Rightarrow \quad g_m = \omega^2 C_1 (C_2 \cdot r + L \cdot g_o) - g_o$$

For  $g_m \square g_o$  and  $C_1 \square C_2$

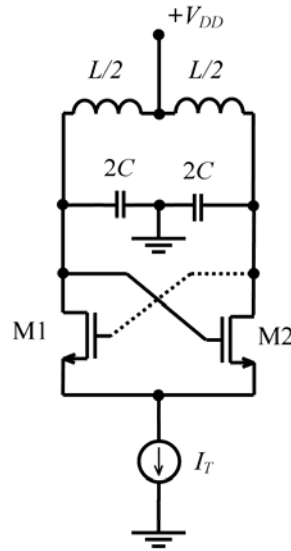
$$g_m \cong \frac{1}{R_{eff}} \frac{C_1 + C_2}{C_2} \quad \text{or} \quad g_m \cong \frac{1}{rQ^2} \frac{C_1 + C_2}{C}$$

$$\text{To guarantee the oscillation; } g_m = k_s \frac{1}{rQ^2} \frac{C_1 + C_2}{C}$$

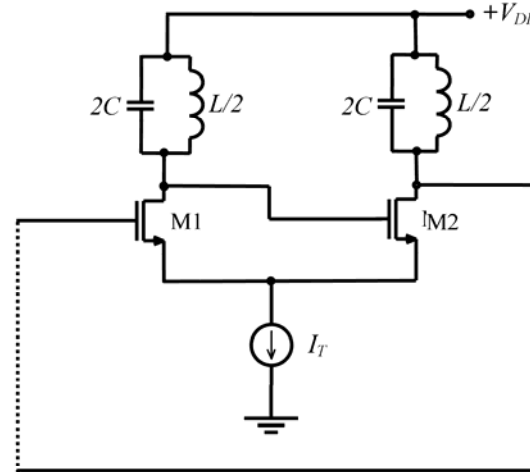
where the safety factor  $k_s = 1.01 \dots 1.1$

# Negative resistance oscillators

from the point of view of feedback oscillators:



(a)



(b)

$$A_{vT}(\omega_0) = (-g_m \cdot R'_{eff})^2$$

$$R'_{eff} = \left( \frac{L}{2} \right) \omega_0 \times Q_{eff}$$

$$A_{vT}(\omega_0) = g_m^2 \frac{1}{4} \left( L \omega_0 \times Q_{eff} \right)^2 = g_m^2 \frac{1}{4} R_{eff}^2$$

$$\beta A_{vT}(\omega_0) = g_m^2 \frac{1}{4} R_{eff}^2 \quad \Rightarrow \quad g_m = \frac{2}{R_{eff}}$$

# Frequency stability of L-C oscillators

Example - 1:

Oscillation frequency expression of a Colpitts oscillator can be arranged as:

$$\omega_{osc} = \frac{1}{\sqrt{LC}} \sqrt{1 + k_s \frac{g_{ds}}{g_m} \frac{1}{Q^2} \frac{C_1 + C_2}{C_2}}$$

$$\omega_{osc} = \frac{1}{\sqrt{LC}} \sqrt{1 + \varepsilon}$$

This is a general form valid for all L-C oscillators, where  $\varepsilon$  (the error term) depends on the circuit parameters.

For a stable oscillation frequency  $\varepsilon$  must be as small as possible.

- In case of a Colpitts oscillator

□ High  $Q$ ,

□ High  $g_m$ ,

□ Small  $g_{ds}$  is advantageous.

A more general expression:

$$d\omega_{osc} = \frac{\partial \omega_{osc}}{\partial L} dL + \frac{\partial \omega_{osc}}{\partial C_1} dC_1 + \frac{\partial \omega_{osc}}{\partial C_2} dC_2 + \frac{\partial \omega_{osc}}{\partial g_m} dg_m + \frac{\partial \omega_{osc}}{\partial g_{ds}} dg_{ds} + \frac{\partial \omega_{osc}}{\partial Q} dQ$$

provides information about the effects of the **tolerances** and **dependences** of several parameters on  $d\omega_{osc}$ , the shifts of the oscillation frequency.

## Example - 2:

Differential negative resistance oscillator:

$$\omega_{(\text{Re})} = \omega_{(\text{osc})} = \sqrt{\frac{1}{LC}} \times \sqrt{\frac{L - Cr_L^2}{L - Cr_C^2}}$$

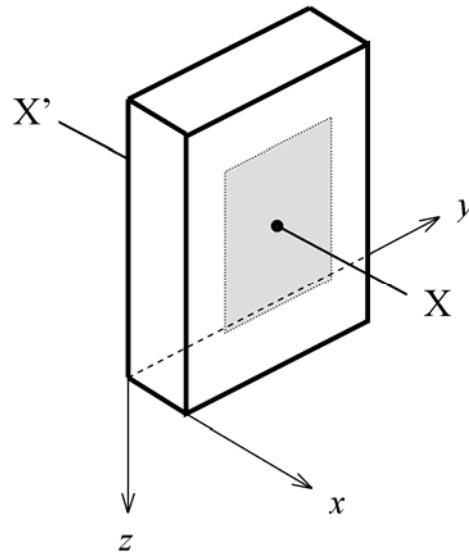
- $r_L$  and  $r_C$  must be as low as possible  
(  $Q_L$  and  $Q_C$  must be as high as possible)

- An interesting possibility:

For  $r_L = r_C$ ,  $\omega_{(\text{osc})}$  depends only on  $L$  and  $C$ .

# Crystal oscillators

To reach better frequency stability, a piezoelectric crystal (a quartz crystal as the best piezoelectric material) having appropriate dimensions, can be used as the resonator of an electronic oscillator circuit.



$x$ : Electrical axis  
 $y$ : Mechanical axis

- If a sinusoidal voltage is applied to  $X - X'$  the crystal vibrates in  $y$  dimension.
- Amplitude is maximum for the mechanical resonance frequency of the crystal in  $y$  direction, for which the losses are very small, consequently  $Q$  very high.
- This mechanical vibration provokes a voltage on  $X - X'$ ; therefore a piezoelectric crystal **can be used as a very high  $Q$  resonance circuit from its  $X - X'$  port.**

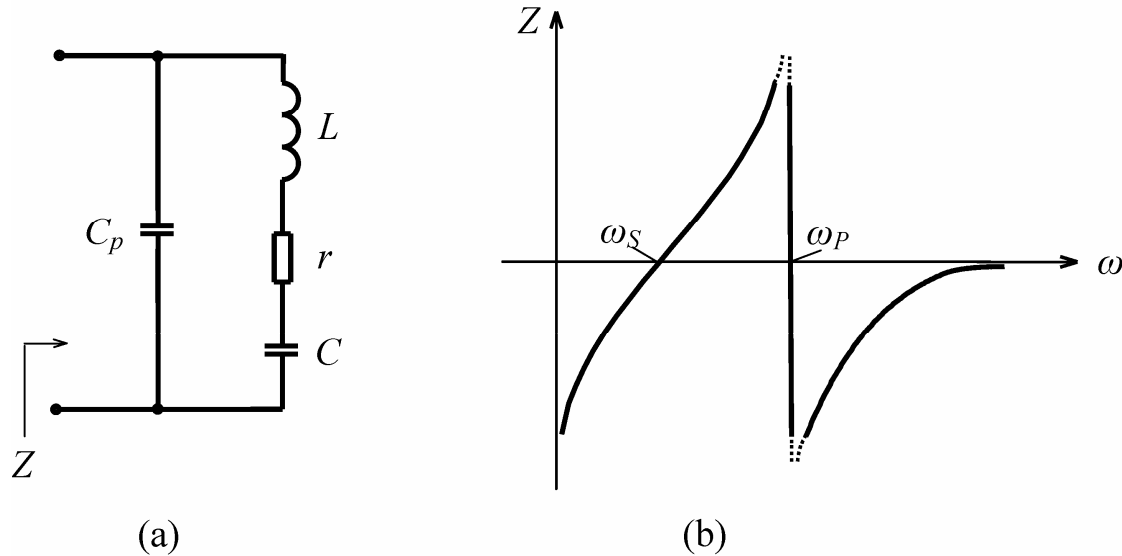
Mechanical resonance frequencies of a prism shaped body:

$$f = \frac{1}{2} \sqrt{\frac{y}{\rho}} \left[ \left( \frac{n_x}{l_x} \right)^2 + \left( \frac{n_y}{l_y} \right)^2 + \left( \frac{n_z}{l_z} \right)^2 \right]^{1/2}$$

( $y$ : Young modulus,  $\rho$ : density)

The fundamental resonance frequency in  $y$  direction:  $f_0 = \frac{1}{2l_y} \sqrt{\frac{y}{\rho}}$

## Electrical equivalent circuit of a piezoelectric crystal:



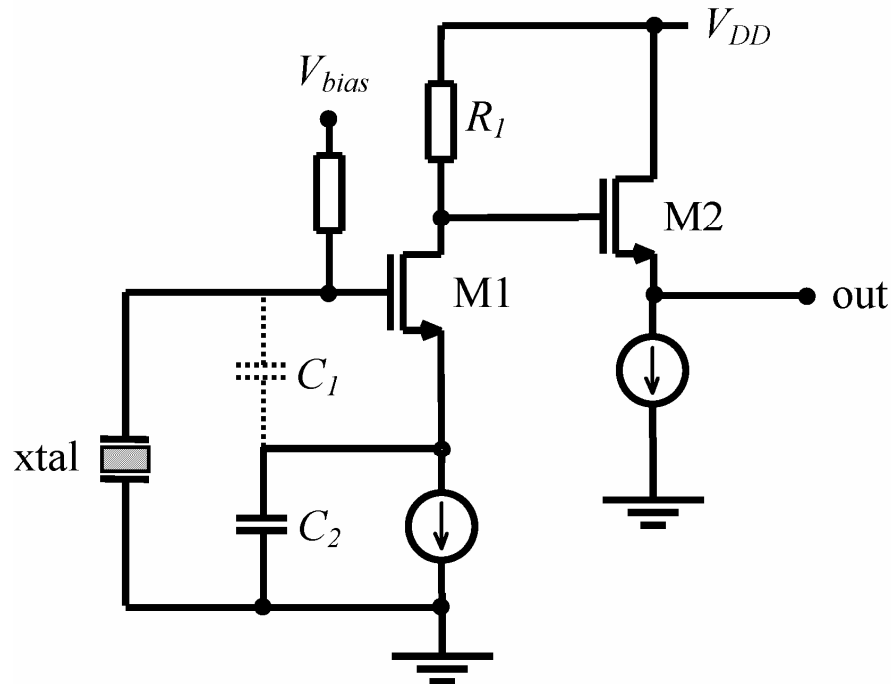
Example:

$$l_x = 0.636 \text{ cm}, l_y = 2.75 \text{ cm}, l_z = 3.33 \text{ cm}; f_0 = 430 \text{ kHz}$$

$$L = 3.3 \text{ H}, R = 4500 \text{ ohm}, C = 42 \text{ fF}, C_p = 5.8 \text{ pF} \Rightarrow Q \approx 2000$$

## Example:

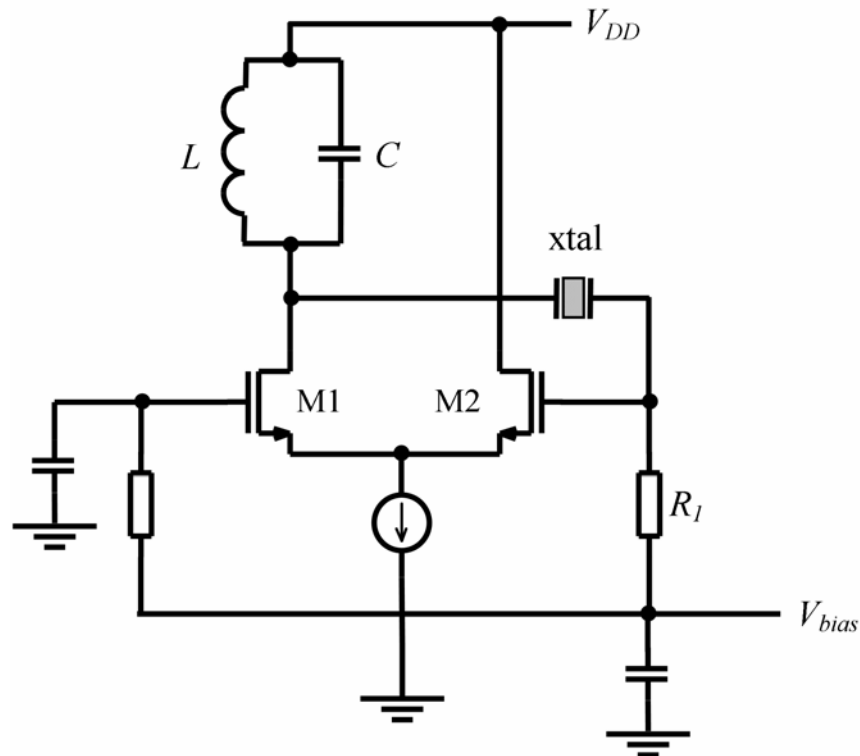
An oscillator operating at the parallel resonance frequency of the crystal



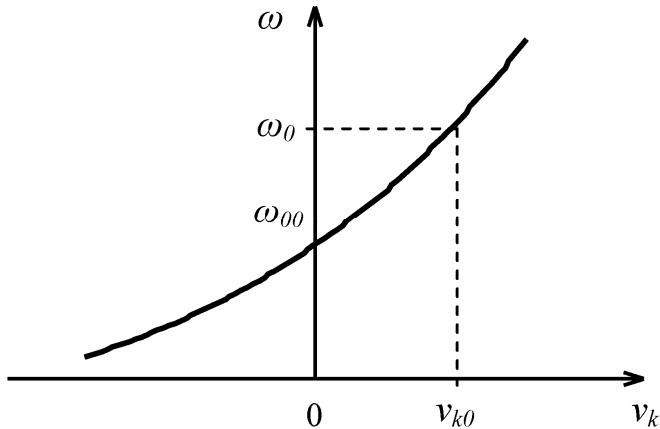
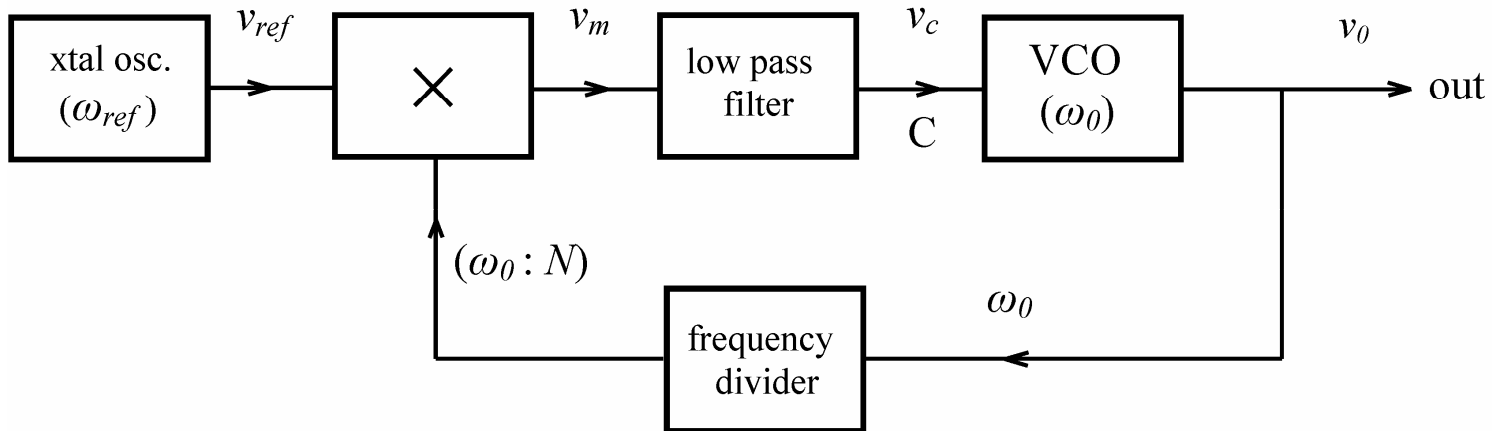
(A negative resistance oscillator or a Colpitts oscillator?)

## Example:

An oscillator operating at the series resonance frequency of the crystal



# Phase-lock technique



$$v_{ref} = V_{ref} \sin(\omega_{ref} t)$$

$$v_0 = V_0 \sin(\omega_{00} t + \varphi_0)$$

$$v_x = V_x \sin\left(\frac{\omega_{00}}{N} + \varphi_x\right)$$

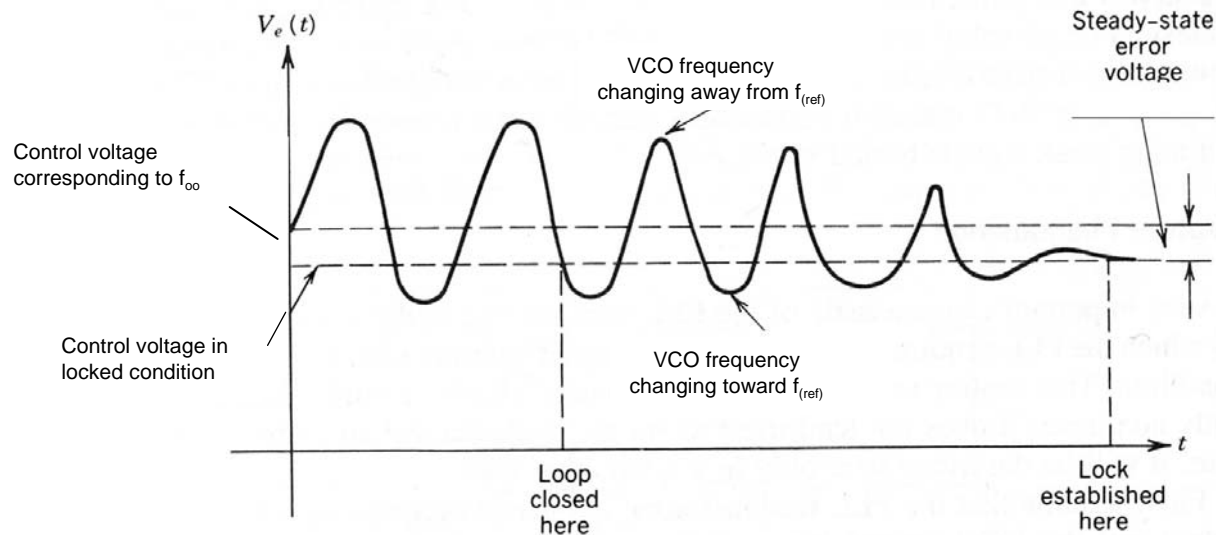
When the loop is open at C:

$$v_c = k \left[ V_{ref} \sin(\omega_{ref} t) \right] \times \left[ V_x \sin \left( \frac{\omega_{00}}{N} + \varphi_x \right) \right]$$

$$v_m = \frac{1}{2} k V_{ref} V_x \cos \left[ \left( \omega_{ref} - \frac{\omega_{00}}{N} \right) t - \varphi_x \right] - \frac{1}{2} k V_{ref} V_x \cos \left[ \left( \omega_{ref} + \frac{\omega_{00}}{N} \right) t + \varphi_x \right]$$

$$v_c = \frac{1}{2} k V_{ref} V_x \cos \left[ \left( \omega_{ref} - \frac{\omega_{00}}{N} \right) t - \varphi_x \right]$$

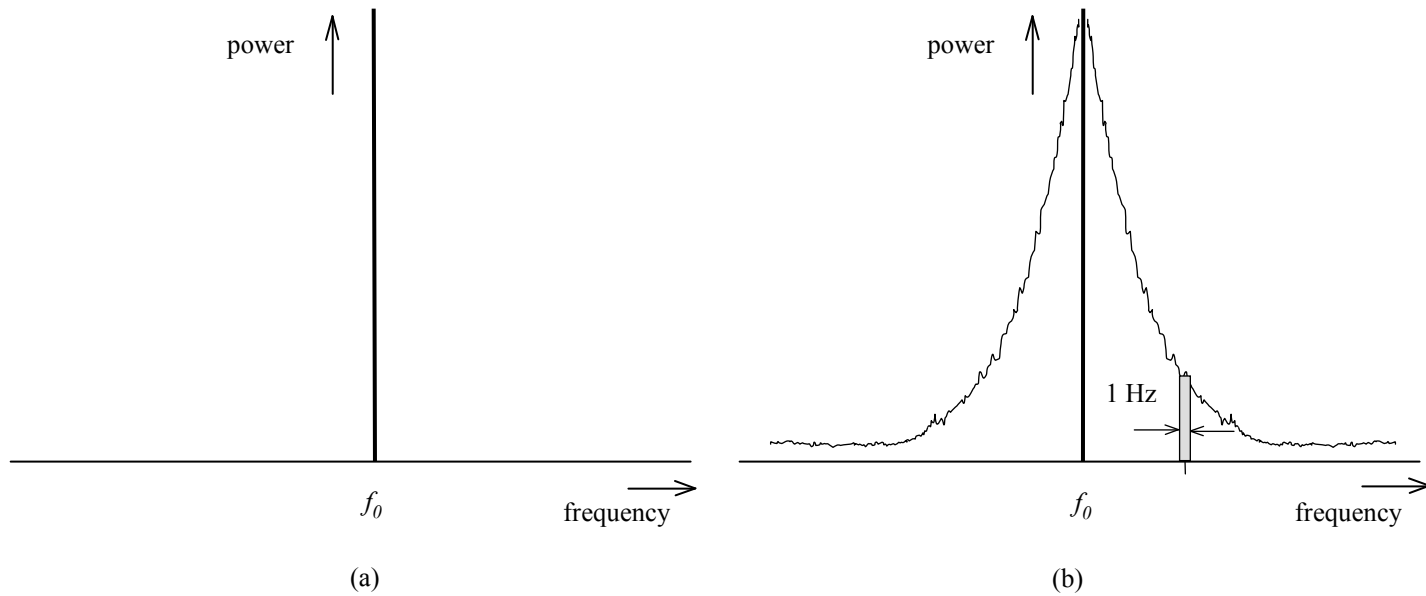
The on-set of locking upon the closing of the loop:



At the on-set of locking;  $f_0 = f_{ref}$

(After Alan B. Grebene)

# Phase noise in oscillators



(a) Frequency spectrum of an ideal oscillator.

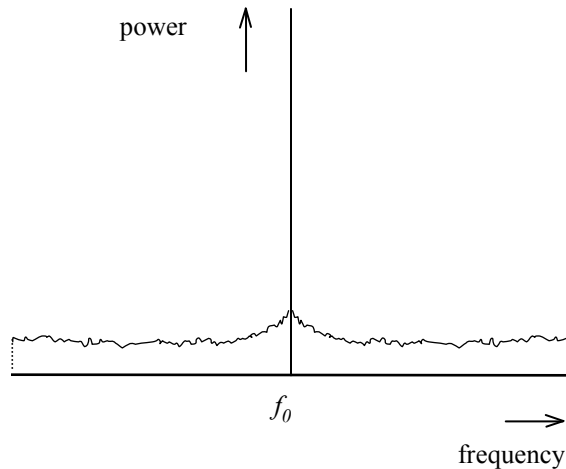
(b) Frequency spectrum of a non-ideal oscillator.

$$\text{Phase noise: } L(\Delta\omega) = 10 \log \left( \frac{P(f_0 + \Delta f)_{B=1\text{Hz}}}{P(f_0)} \right)$$

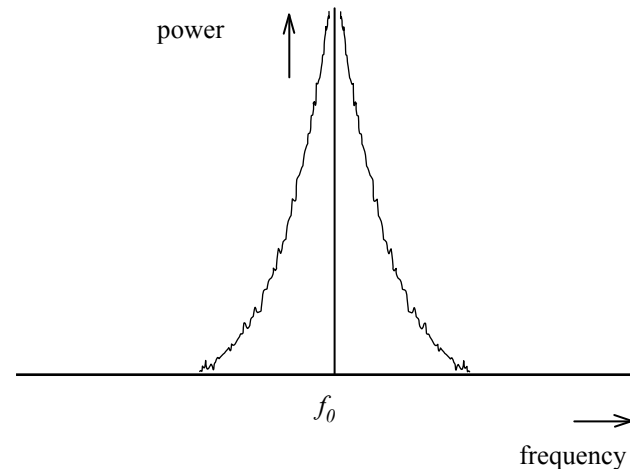
There are several mechanisms contributing to the phase noise:

- Random changes of the frequency due to the low stability,
- The thermal noise on the voltages and currents in the circuit,
- Shifts of the zero-crossing point of the output signal,
- Frequency modulation of  $f_0$  with thermal noise.

## Frequency modulation of $f_0$ with thermal noise



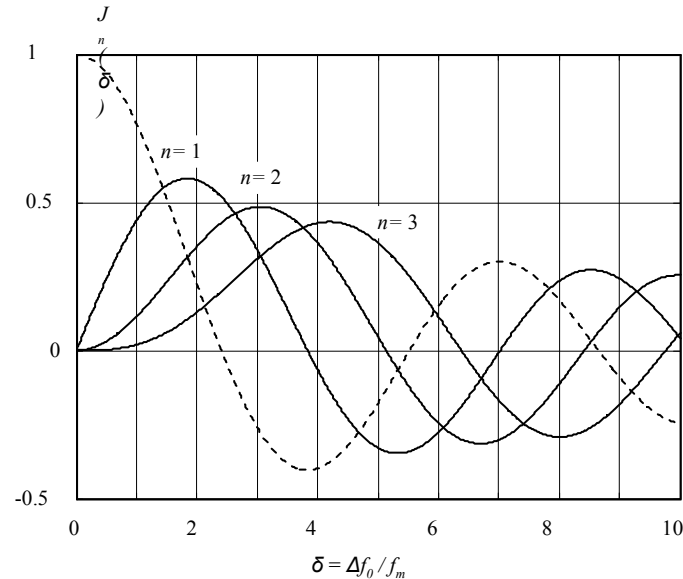
(a)



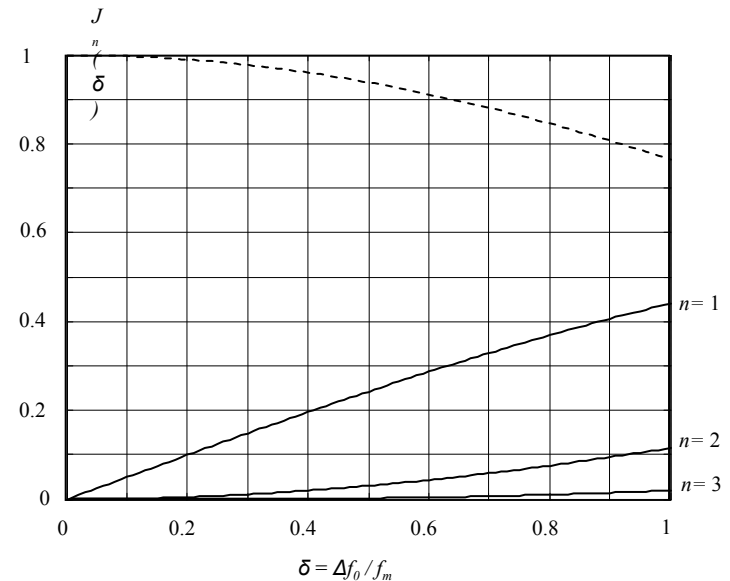
(b)

- (a) Spectrum of an oscillator, amplitude modulated with white noise,  
(b) Spectrum of an oscillator, frequency modulated with white noise.

- One of the reasons behind the random frequency modulation of  $\omega_0$  is the uncertainty of the oscillation frequency, due to the three frequencies,  $\omega_0$ ,  $\omega_{(\text{Re})}$  and  $\omega_{\text{max}}$ , different but very close to each other.
- The amplitudes of the side frequencies of a carrier  $f_0$ , frequency modulated with a signal,  $f_m$  are given in terms of Bessel functions of the modulation index,  $\delta = \Delta f_0 / f_m$ , where  $\Delta f_0$  is the frequency deviation that is very small and random in our case.



(a)

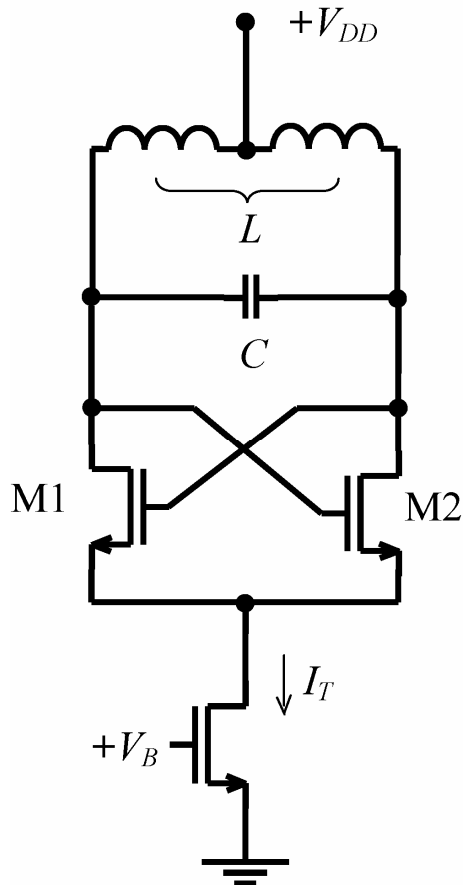


(b)

- From these data, for small values of  $\delta$ , the rate of decrease of the r.m.s. values of the side frequencies can be calculated as approximately 20 dB/decade, in good agreement with the measured data.
- Another important issue related to the **phase noise** is the **"jitter"**, the RMS amplitude of the variations of the zero cross point of the signal in time axis, that is related to the phase noise in  $f_1$  to  $f_2$  interval as

$$J_{RMS}|_{(f_1 \text{ to } f_2)} = \frac{1}{2\pi f_0} \sqrt{2 \int_{f_1}^{f_2} 10 \frac{L(f)}{10} df}$$

# Example:



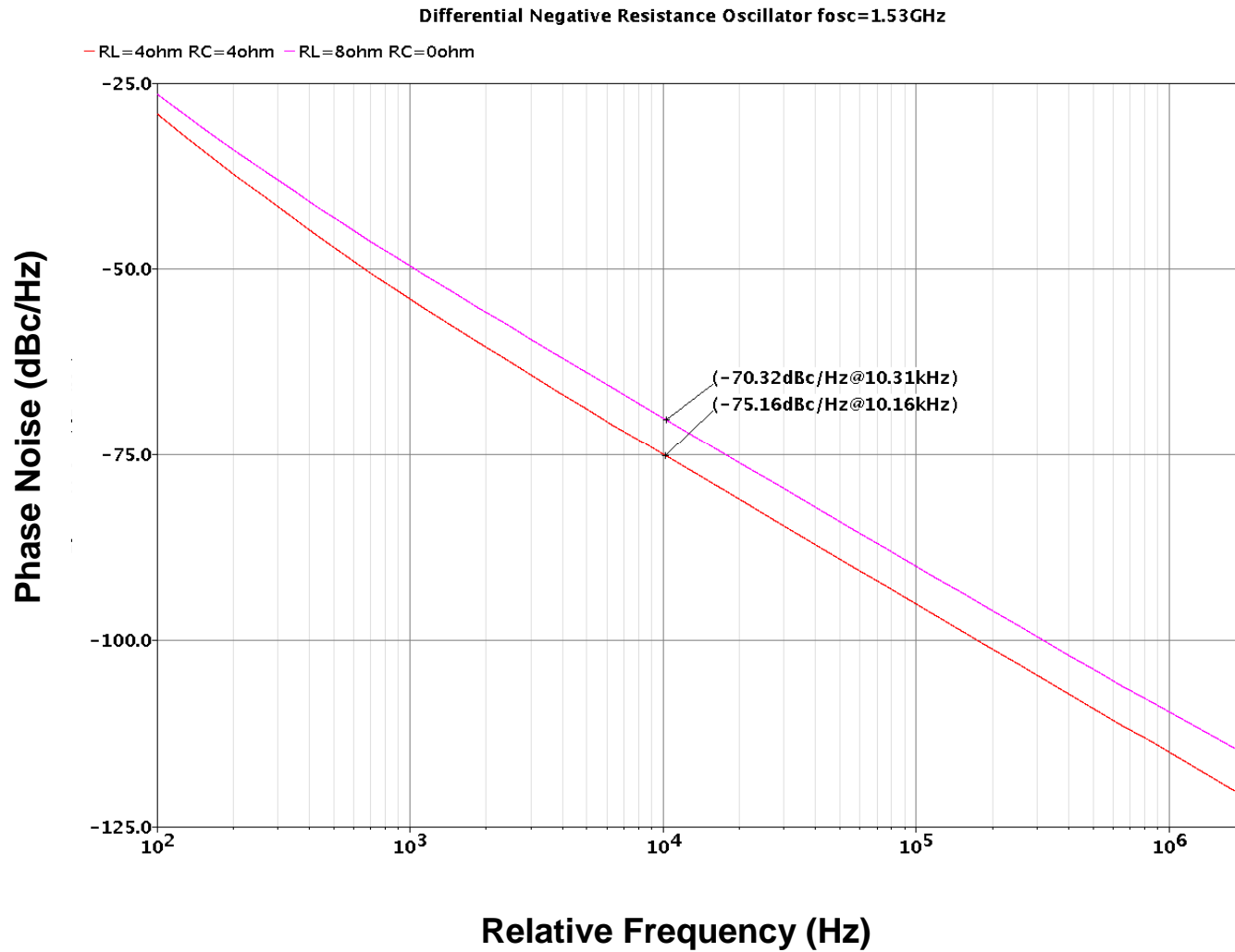
$$W/L = 100, L = 0.18 \mu\text{m}$$

$$I_T = 1.2 \text{ mA}$$

$$L = 10 \text{ nH}$$

$$C = 1 \text{ pF}$$

$$f_o = 1.6 \text{ GHz}$$



**Jitter = 1.12 ps**  
**Jitter = 515 fs**