

Chapter 8

```
> with(linalg):
```

```
Warning, the protected names norm and trace have been redefined and
unprotected
```

```
> with(plots):
```

```
Warning, the name changecoords has been redefined
```

Question 1

(i)

This is a purely theoretical question. Given

$$q_d(t) = a - b p(t)$$

$$q_s(t) = c + d p(t+1)$$

and $q_d(t) = q_s(t)$, in equilibrium, which we set equal to $q(t)$, then

```
> solve(a-b*pt=c+d*pt_1,pt);
```

$$\frac{a - c - d \text{pt}_1}{b}$$

or

$$p(t) = \frac{a - c}{b} + \left(-\frac{d}{b}\right) p(t-1)$$

Since $b < 1$, then $1 < -b$ and with $0 < d$, then $0 < -\frac{d}{b}$. If $0 < -\frac{d}{b} < 1$, then the system converges

on the equilibrium value. On the other hand, if $1 < -\frac{d}{b}$, then the system diverges from equilibrium.

(ii)

Since $0 < -\frac{d}{b}$, then the systems does not oscillate.

An example of this type of situation is given in Question 2(ii) in which $-\frac{d}{b} = \frac{1}{2}$, which we shall consider next.

Question 2

 (i)

The system is:

$$q_d(t) = 100 - 2 p(t)$$

$$q_s(t) = -20 + 3 p(t-1)$$

with initial condition $p_0 = 10$

```
> solve(100-2*pt=-20+3*pt_1,pt);
```

$$60 - \frac{3}{2} \text{pt}_1$$

with equilibrium price:

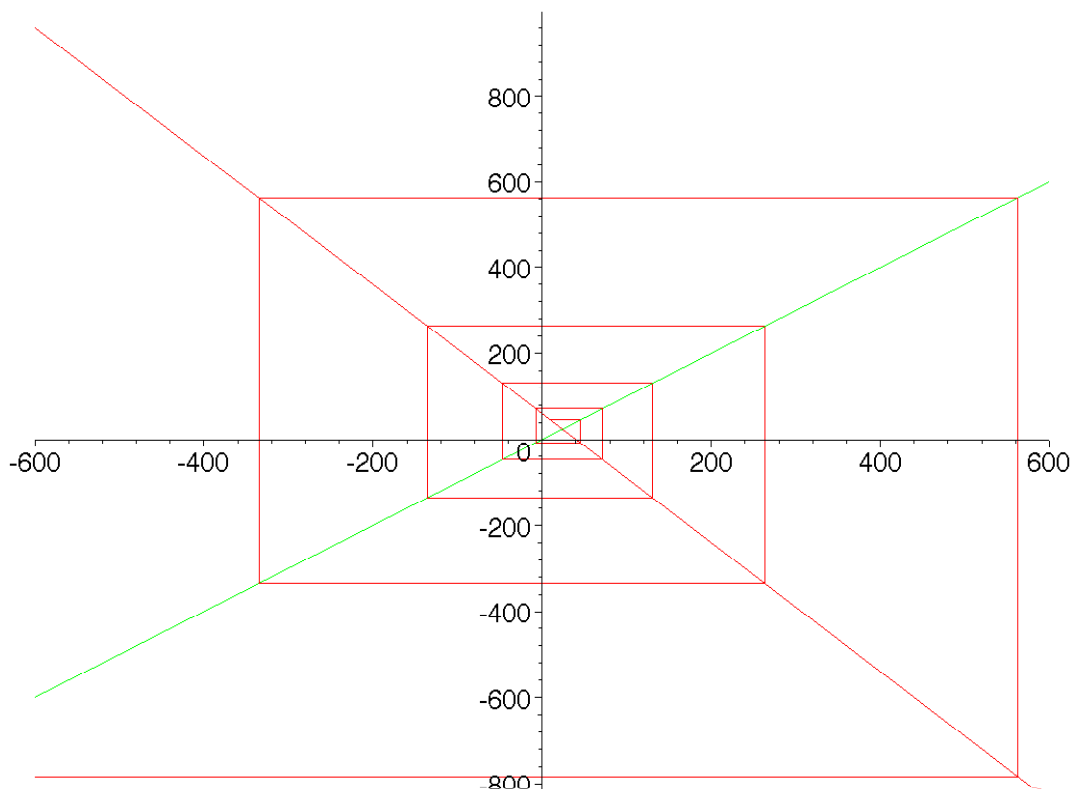
```

> solve(p=60-(3/2)*p,p);

24

> f:=p->60-1.5*p;
       $f := p \rightarrow 60 - 1.5p$ 
> fn:=(p,n)->simplify((f@@n)(p));
       $fn := (p, n) \rightarrow \text{simplify}((f^{(n)})(p))$ 
> list1:=transpose(array([[seq(fn(10,n),n=0..10)],
      [seq(fn(10,n),n=0..10)] ] ));
> list2:=convert(convert(list1,vector),list):
> list3:=convert(transpose(array([
      list2[1..nops(list2)-1],list2[2..nops(list2)] ] )
      ),listlist):
> list4:=list3[2..nops(list3)]:
> web:=plot(list4):
> lines:=plot({f(p),p},p=-600..600):
> display(web,lines);

```



Since we shall be using cobwebs frequently in this chapter, it is useful to provide a small programme, using *Maple's* **proc** command.

```

> cobweb:=proc(f,p0,n,minp,maxp)
  local fk,list1,list2,list3,list4,web,lines;
    fk:=(p,k)->simplify((f@@k)(p));
    list1:=transpose(array([[seq(fk(p0,k),k=0..n)],
      [seq(fk(p0,k),k=0..n)] ] ));
    list2:=convert(convert(list1,vector),list):
    list3:=convert(transpose(array([
      list2[1..nops(list2)-1],

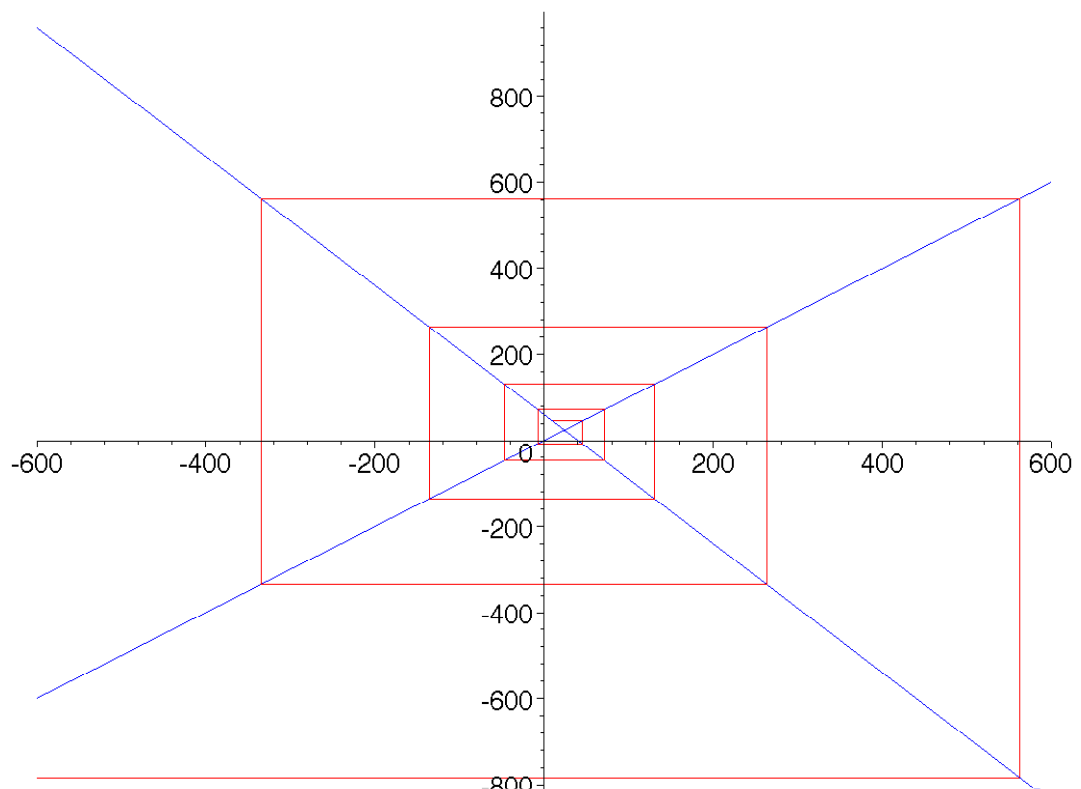
```

```

        list2[2..nops(list2)] ]) ),listlist):
    list4:=[list3[2..nops(list3)]]:
    web:=plot(list4):
    lines:=plot({f(p),p},p=minp..maxp,colour=blue):
    display(web,lines);
end;
cobweb := proc(f,p0,n,minp,maxp)
local fk,list1,list2,list3,list4,web,lines;
    fk := (p,k) → simplify((f@@k)(p));
    list1 :=
        transpose(array([ [seq(fk(p0,k),k=0..n)], [seq(fk(p0,k),k=0..n)] ]))
        ;
    list2 := convert(convert(list1,vector),list);
    list3 := convert(
        transpose(array([ list2[1..nops(list2)-1], list2[2..nops(list2)] ])),
        listlist);
    list4 := [list3[2..nops(list3)]];
    web := plot(list4);
    lines := plot({p,f(p)},p=minp..maxp,colour=blue);
    display(web,lines)
end proc
> f:p->60-1.5*p; cobweb(f,10,10,-600,600);

```

$$p \rightarrow 60 - 1.5p$$





(ii)

The system is:

$$q_d(t) = 5 + 2 p(t)$$

$$q_s(t) = 35 + p(t - 1)$$

with initial condition $p_0 = 5$.

First we need to derive the difference equation.

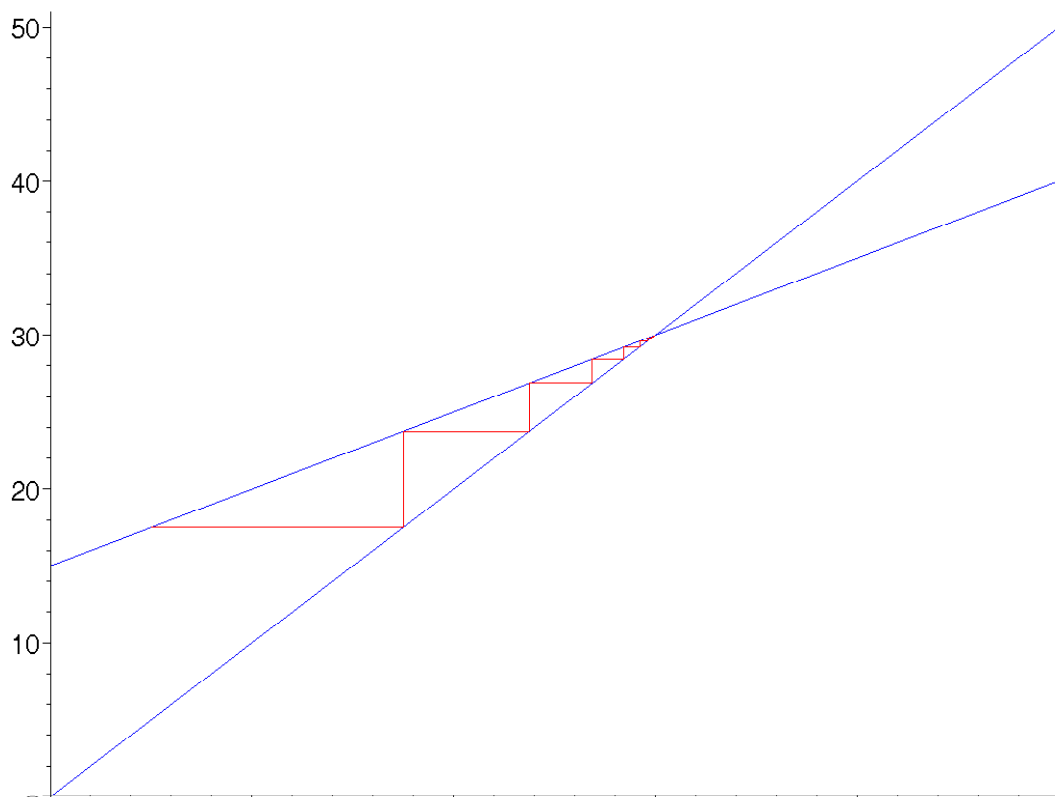
> `solve(5+2*pt=35+pt_1,pt);`

$$15 + \frac{1}{2} p_{t-1}$$

So our difference equation is $p(t) = 15 + .5 p(t - 1)$. Using the procedure above for the cobweb, we have:

> `f:=p->15+0.5*p; cobweb(f,5,10,0,50);`

$$f := p \rightarrow 15 + .5 p$$



(iii)

The system is

$$q_d(t) = 100 - 2 p(t)$$

$$q_s(t) = -20 + 2 p(t - 1)$$

with initial condition $p_0 = 24$.

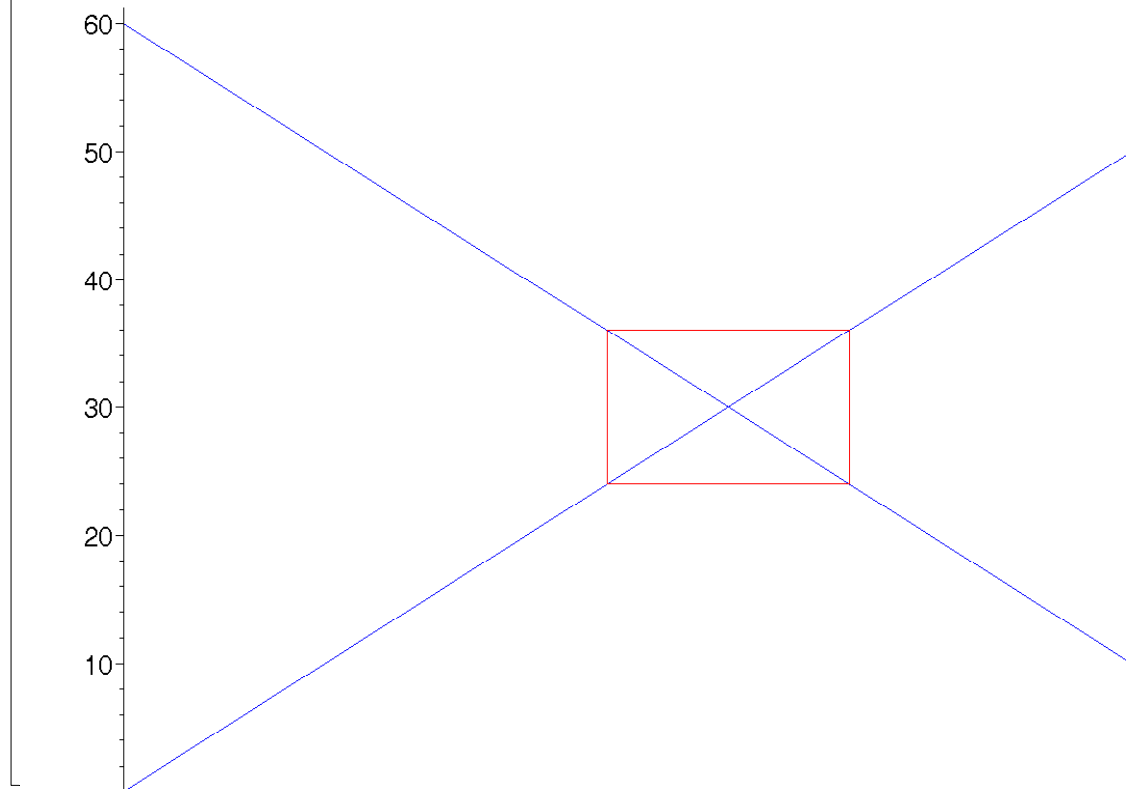
First we need to derive the difference equation.

> `solve(100-2*pt=-20+2*pt_1,pt);`

$$60 - p_{t-1}$$

> `f:=p->60-p; cobweb(f,24,10,0,50);`

$$f := p \rightarrow 60 - p$$



[This illustrates an oscillatory cobweb which is cyclical.



(iv)

The system is

$$q_d(t) = 18 - 3 p(t)$$

$$q_s(t) = -10 + 4 p(t - 1)$$

with initial condition $p_0 = 1$.

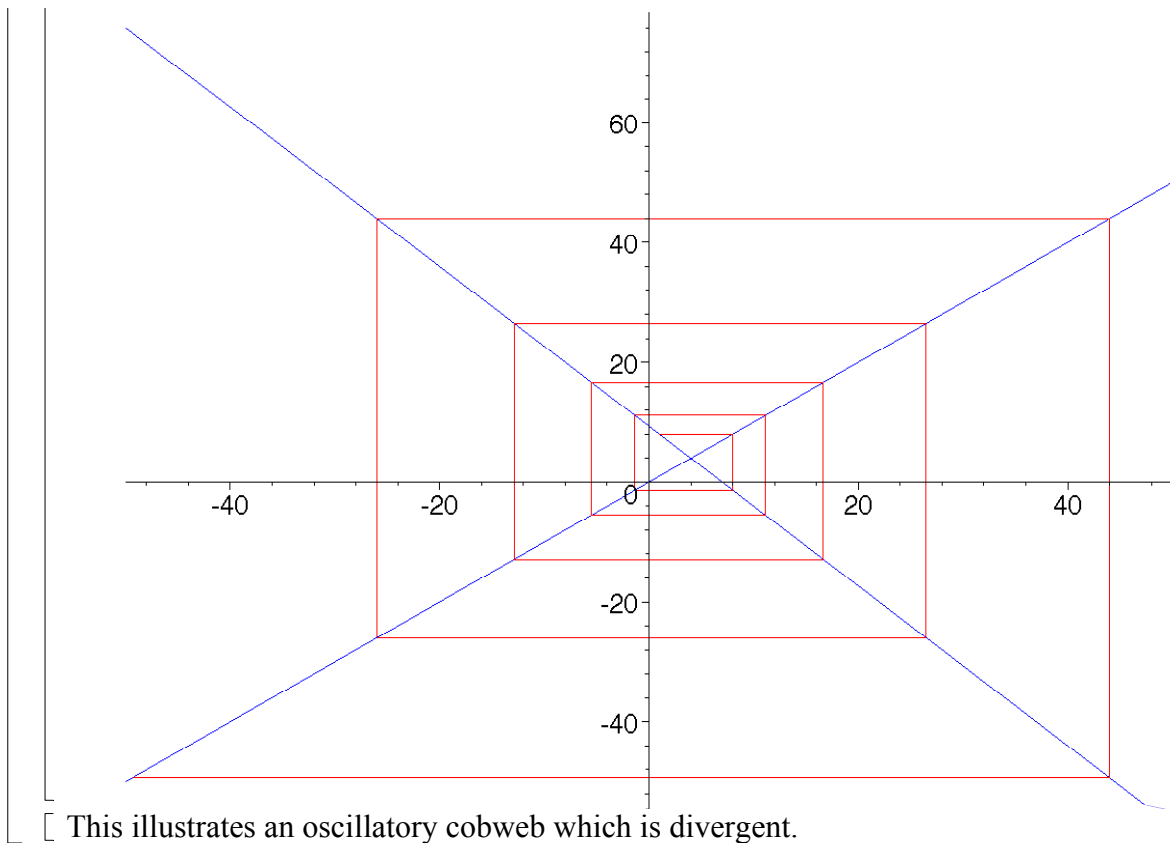
[First we need to derive the difference equation.

> `solve(18-3*pt=-10+4*pt_1,pt);`

$$\frac{28}{3} - \frac{4}{3} p_{t-1}$$

> `f:=p->(28/3)-(4/3)*p; cobweb(f,1,10,-50,50);`

$$f := p \rightarrow \frac{28}{3} - \frac{4}{3} p$$



Question 3

For the general model:

$$q_d(t) = a - b p(t) \quad 0 < b$$

$$q_s(t) = c + d (p^e)_t \quad 0 < d$$

$$q_d(t) = q_s(t) = q$$

$$(p^e)_t = (p^e)_{t-1} - \lambda ((p^e)_{t-1} - p_{t-1}) \quad 0 \leq (\lambda \leq 1)$$

$$p_t = \frac{\lambda (a - c)}{b} + \left[1 - \lambda - \frac{\lambda d}{b} \right] p_{t-1}$$

We can deal with each problem by substituting the parameter values and then solving the difference equation.

(i)

```
> const:=lambda*( (a-c)/b) ;
```

$$const := \frac{\lambda (a - c)}{b}$$

```
> coef:=(1-lambda-(lambda*d/b)) ;
```

$$coef := 1 - \lambda - \frac{\lambda d}{b}$$

```
> const1:=subs ({a=100,b=2,c=-20,d=3,lambda=0.5},const) ;
```

$$const1 := 30.00000000$$

```
> coef1:=subs ({a=100,b=2,c=-20,d=3,lambda=0.5},coef) ;
```



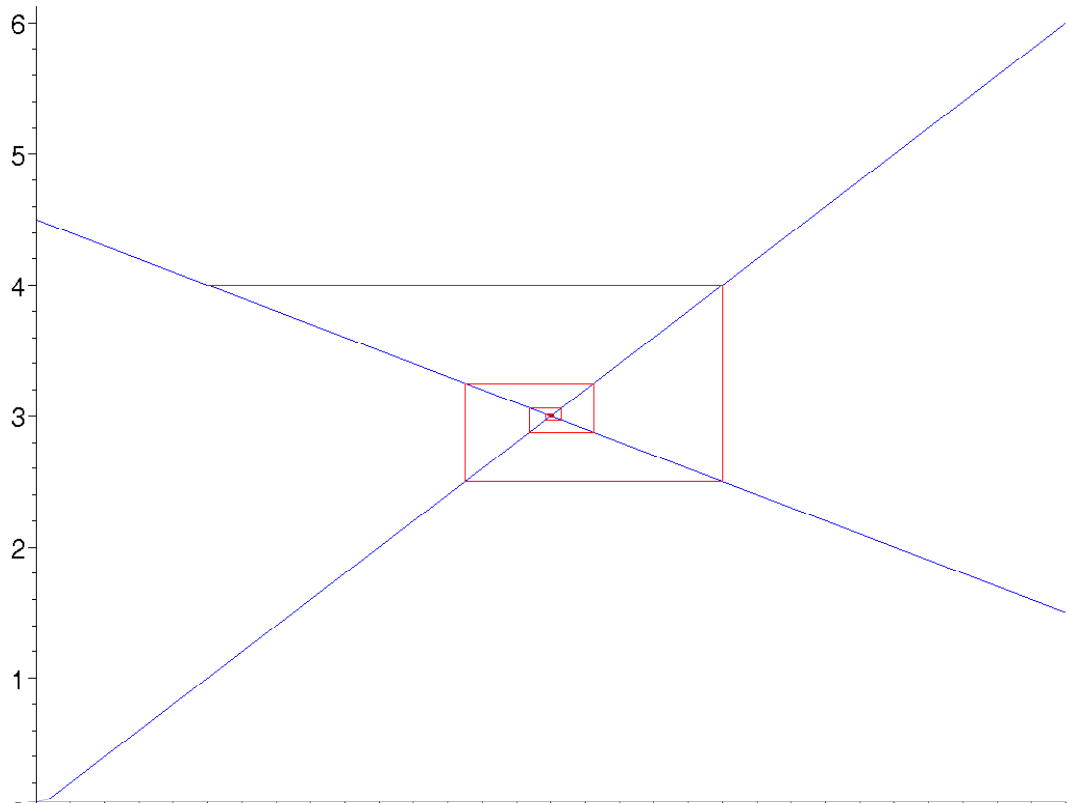
```
> f:=p->4.5-0.5*p;
```

```
f:=p → 4.5 - .5 p
```

```
> solve(p=f(p),p);
```

```
3.
```

```
> cobweb(f,1,10,0,6);
```



(ii)

Given

$$q_d(t) = 100 - .5 p(t)$$

$$q_s(t) = 50 - .1 p(t-1)$$

$$q_d(t) = q_s(t) = q(t)$$

then

```
> solve(100-0.5*pt=50-0.1*pt_1,pt);
```

```
100. + .2000000000 pt_1
```

```
> f:='f'; p:='p'; p0:='p0';
```

```
f:=f
```

```
p:=p
```

```
p0:=p0
```

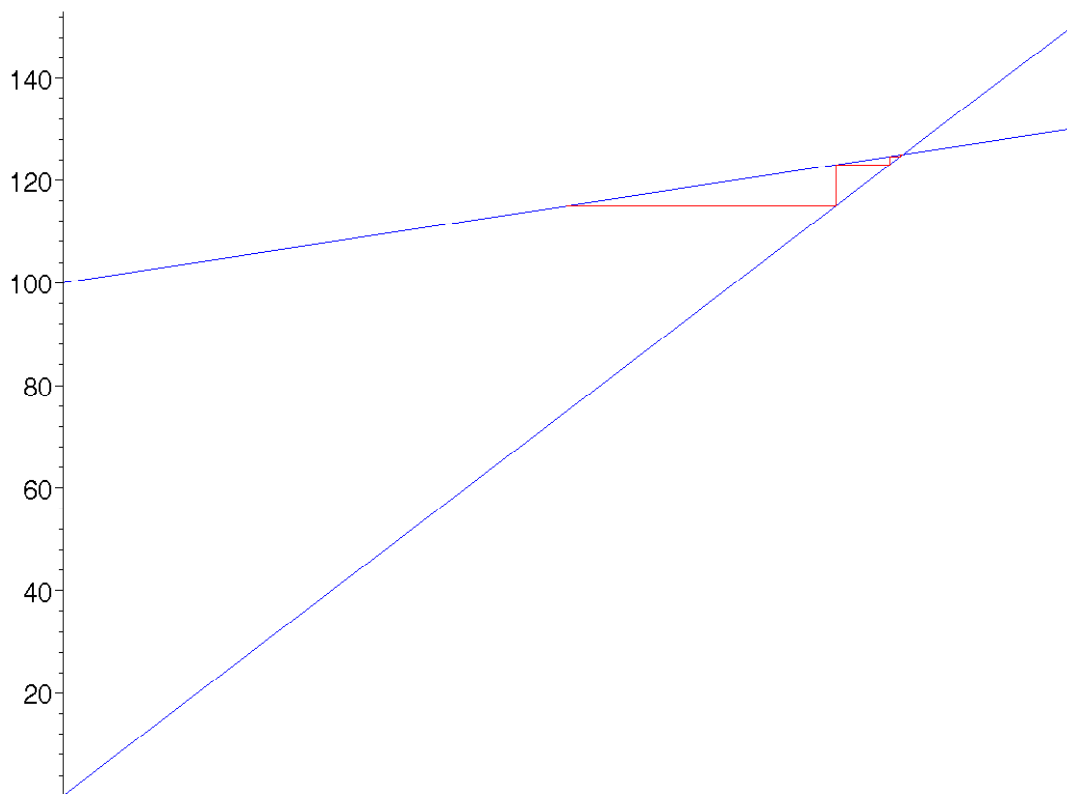
```
> f:=p->100+0.2*p;
```

```
f:=p → 100 + .2 p
```

```
> solve(p=f(p),p);
```

```
125.
```

```
> cobweb(f,75,10,0,150);
```



As pointed out above, this system is non-oscillatory and convergent.

Question 5

(i)

Given the equations

$$q_d(t) = 50 - 4 p(t)$$

$$q_s(t) = 10 + 10 p(t-1) - p_{t-1}^2$$

$$q_d(t) = q_s(t) = q(t)$$

then

```
> solve(50-4*pt=10+10*pt_1-pt_2^2,pt);
```

$$10 - \frac{5}{2} p_{t-1} + \frac{1}{4} p_{t-2}^2$$

Maple cannot solve this

difference equation with the **rsolve** command.

First establish the fixed points.

```
> solve(p=10-(5/2)*p+(1/4)*p^2,p);
```

4, 10

The difference equation can be linearized in the neighbourhood of the fixed point by using

$$p_t = f(pe) + \left(\frac{\partial}{\partial p} f(pe) \right) (p - pe)$$

where pe denotes the fixed point and $f(p) = 10 - \frac{5p}{2} + \frac{1}{4} p^2$.

```
> f:='f'; f:=p->10-(5/2)*p+(1/4)*p^2;
```

$f:=f$

$$f := p \rightarrow 10 - \frac{5}{2}p + \frac{1}{4}p^2$$

```
> subs(p=4,diff(f(p),p));
```

$$-\frac{1}{2}$$

```
> subs(p=10,diff(f(p),p));
```

$$\frac{5}{2}$$

Thus,

$$p_t = 4 - \frac{1(p-4)}{2} \quad \text{which is stable since } \left| \frac{\partial}{\partial p} pe \right| < 1$$

$$p_t = 10 + \frac{5(p-10)}{2} \quad \text{which is unstable since } 1 < \left| \frac{\partial}{\partial p} pe \right|$$

Although the linear approximations can give us some insight about stability and instability, there is no guarantee that the non-linear system may lead to a cyclical solution. To see what might be taking place around each equilibrium, we shall utilise the procedure for constructing non-linear cobwebs.

Consider first the fixed point $pe = 4$.

```
> f:='f'; p:='p'; p0:='p0';
```

$$f := f$$

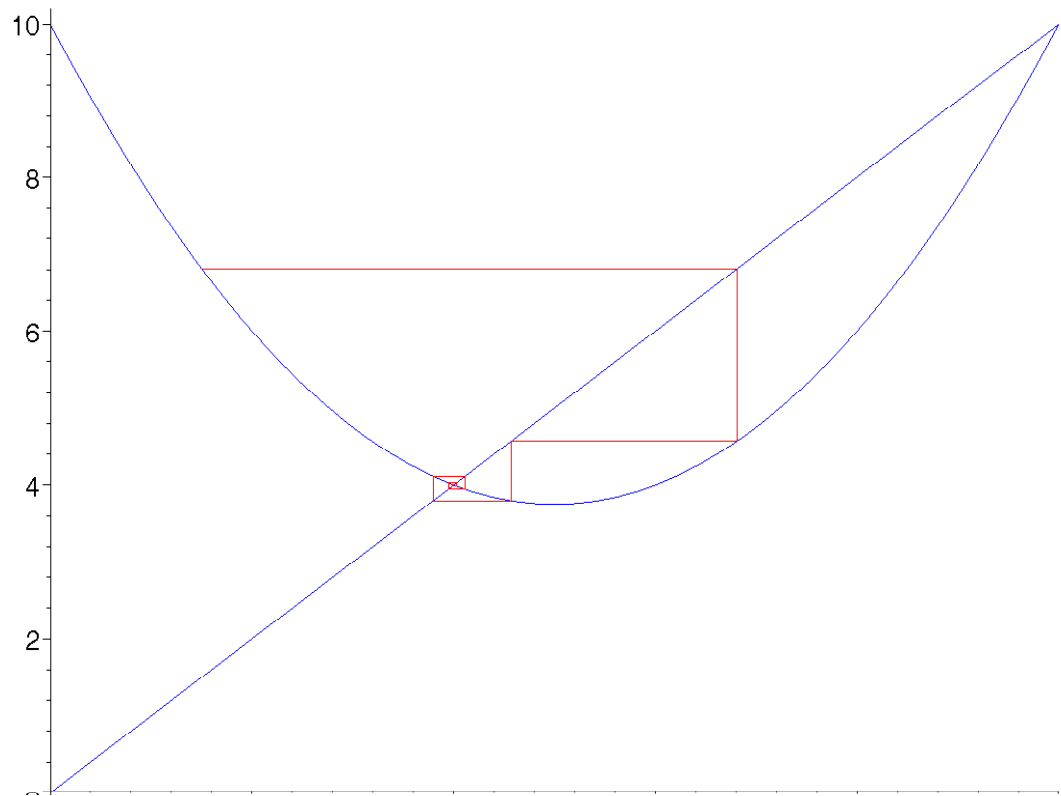
$$p := p$$

$$p0 := p0$$

```
> f:=p->10-(5/2)*p+(1/4)*p^2;
```

$$f := p \rightarrow 10 - \frac{5}{2}p + \frac{1}{4}p^2$$

```
> cobweb(f,1.5,8,0,10);
```



Consider next the fixed point $pe = 10$.

> **f:='f'; p:='p'; p0:='p0';**

$f := f$

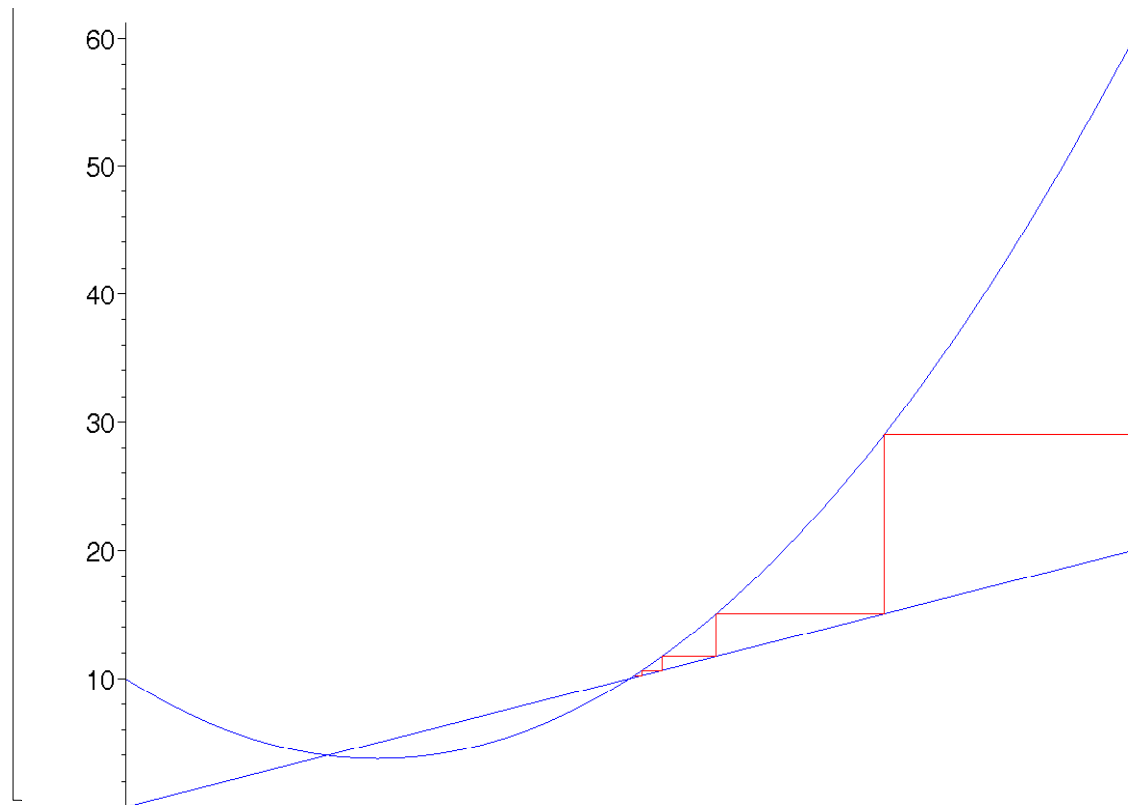
$p := p$

$p0 := p0$

> **f:=p->10-(5/2)*p+(1/4)*p^2;**

$f := p \rightarrow 10 - \frac{5}{2}p + \frac{1}{4}p^2$

> **cobweb(f,10.1,5,0,20);**



(ii)

Given the equations

$$q_d(t) = 50 - 4p(t)$$

$$q_s(t) = 2 + 10p(t-1) - p_{t-1}^2$$

$$q_d(t) = q_s(t) = q(t)$$

then

> `solve(50-4*pt=2+10*pt_1-pt_2^2,pt);`

$$12 - \frac{5}{2}pt_1 + \frac{1}{4}pt_2^2$$

Maple cannot solve this

difference equation with the **rsolve** command.

First establish the fixed points.

> `solve(p=12-(5/2)*p+(1/4)*p^2,p);`

6, 8

> `f:='f'; f:=p->12-(5/2)*p+(1/4)*p^2;`

$f:=f$

$$f:=p \rightarrow 12 - \frac{5}{2}p + \frac{1}{4}p^2$$

> `subs(p=6,diff(f(p),p));`

$\frac{1}{2}$

>

> `subs(p=8,diff(f(p),p));`

$$\frac{3}{2}$$

Thus

$$p_t = 6 + \frac{1(p-6)}{2} \quad \text{which is stable since } \left| \frac{\partial}{\partial p} p_e \right| < 1$$

$$p_t = 8 + \frac{3(p-8)}{2} \quad \text{which is unstable since } 1 < \left| \frac{\partial}{\partial p} p_e \right|$$

Again, let us investigate the non-linear system in the neighbourhood of each equilibrium value. Take first $p_e = 6$.

```
> f:='f'; p:='p'; p0:='p0';
```

```
f:=f
```

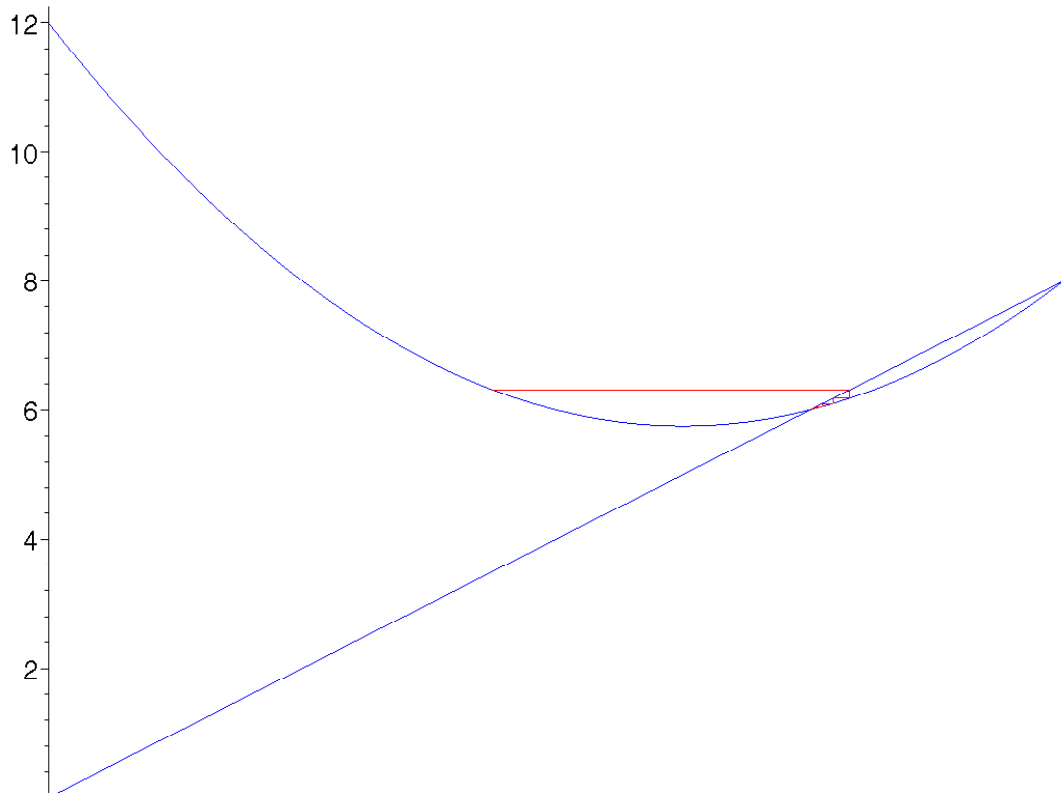
```
p:=p
```

```
p0:=p0
```

```
> f:=p->12-(5/2)*p+(1/4)*p^2;
```

$$f := p \rightarrow 12 - \frac{5}{2}p + \frac{1}{4}p^2$$

```
> cobweb(f,3.5,20,0,8);
```



Take next the fixed point $p_e = 8$.

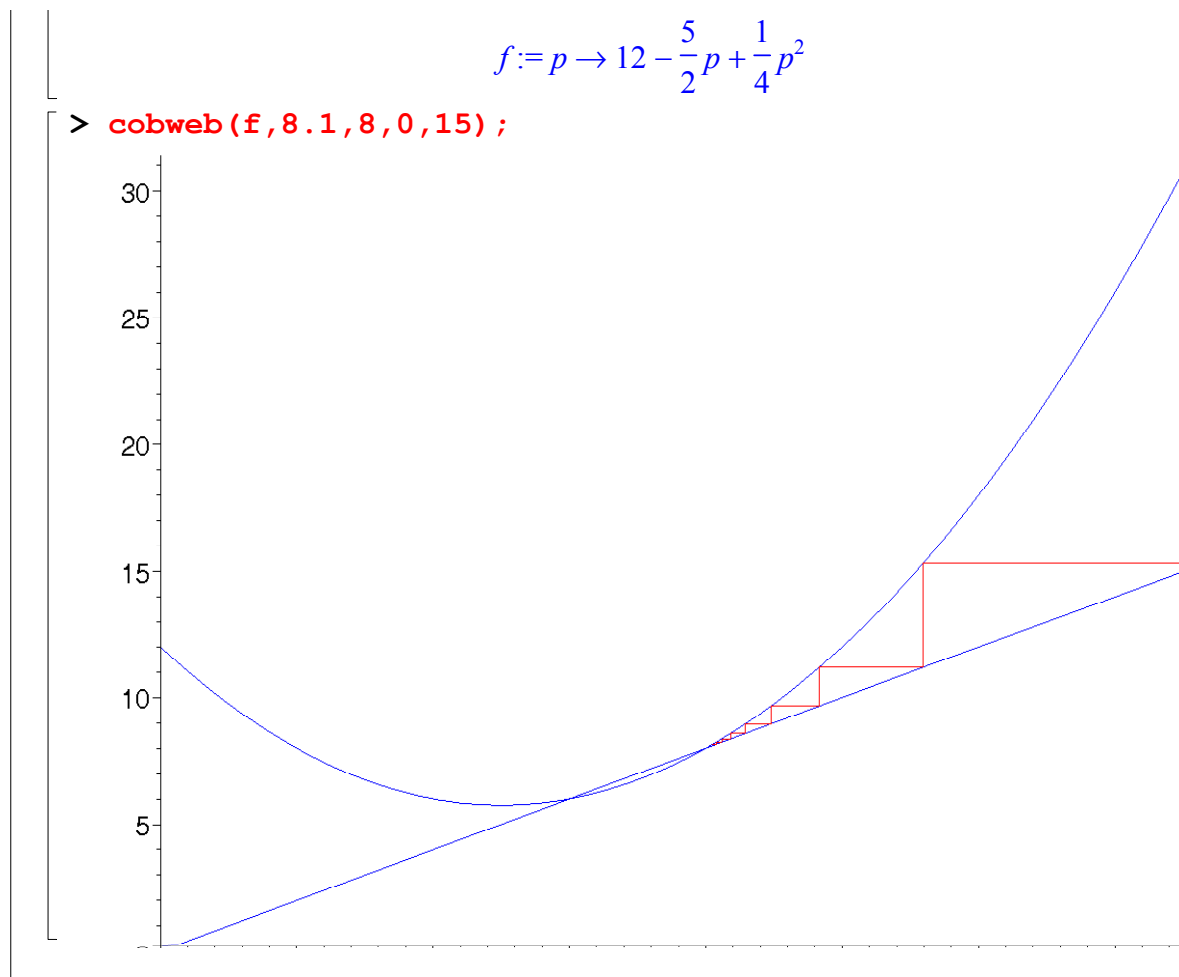
```
> f:='f'; p:='p'; p0:='p0';
```

```
f:=f
```

```
p:=p
```

```
p0:=p0
```

```
> f:=p->12-(5/2)*p+(1/4)*p^2;
```



- Question 6

(i)

We have the following system of equations:

$$q_d(t) = 52 - 9p(t)$$

$$q_s(t) = 3 + 5p(t-1)$$

$$q_d(t) = q_s(t) = q(t)$$

First we need to solve the system for equilibrium price and quantity. Solving we obtain

```
> solve(52-9*pt=3+5*pt_1,pt);
```

$$\frac{49}{9} - \frac{5}{9}pt_1$$

```
> solve(p=(49/9)-(5/9)*p,p);
```

$$\frac{7}{2}$$

We solve for equilibrium q

```
> subs(p=7/2,52-9*p);
```

$$\frac{41}{2}$$

The equilibrium price and quantity are: $pe = 3.5$ and $qe = 20.5$.

(ii)

The initial price is,

> $p_0 := 3.5 - 0.1 * 3.5;$

$p_0 := 3.15$

t	$p(t)$	%dev
0	3.1500	10.0000
1	3.6944	-5.5555
2	3.3919	3.0864
3	3.5600	-1.7146
4	3.4666	.9525
5	3.5185	-.5292
6	3.4897	.2940
7	3.5057	-.1633
8	3.4968	.0907
9	3.5017	-.0504
10	3.4990	.0280

It is readily seen that by period 4 the price is within 1% of the of the equilibrium price.

Question 7

Equation 8.16 of the text, p.336 gave the general result

$$p_t = \frac{\lambda (a - c)}{b} + \left[1 - \lambda - \frac{\lambda d}{b} \right] p_{t-1}$$

substituting the values $a = 52$, $b = 9$, $c = 3$ and $d = 5$, then

$$p_t = \frac{\lambda (52 - 3)}{9} + \left[1 - \lambda - \frac{5 \lambda}{9} \right] p_{t-1}$$

$$p_t = \frac{49 \lambda}{9} + \left[1 - \lambda - \frac{5 \lambda}{9} \right] p_{t-1}$$

We can first check this result by obtaining the equilibrium and showing that it is independent of λ .

> $\text{solve}(p = (49/9) * \lambda + (1 - \lambda - (5/9) * \lambda) * p, p);$

$\frac{7}{2}$

(i)-(iv)

Using the equation for p_t and the initial value $p_0 = 3.15$ we obtain the following results.

t	$p_1(t)$	$p_2(t)$	$p_3(t)$	$p_4(t)$	$\%dev_1$	$\%dev_2$
0	3.150	3.150	3.150	3.150	10.000	10.000
1	3.694	3.558	3.422	3.286	-5.555	-1.666
2	3.391	3.490	3.482	3.369	3.086	.277
3	3.560	3.501	3.496	3.420	-1.714	-.046
4	3.466	3.499	3.499	3.451	.952	.007
5	3.518	3.500	3.499	3.470	-.529	-.001
6	3.489	3.499	3.499	3.481	.294	.000
7	3.505	3.500	3.499	3.488	-.163	-.000
8	3.496	3.499	3.499	3.493	.090	.600 10^{-5}
9	3.501	3.500	3.499	3.495	-.050	-.971 10^{-6}
10	3.499	3.499	3.499	3.497	.028	.200 10^{-6}

From the spreadsheet we have the following periods when the price series comes within 1% of the equilibrium price:

For $\lambda = 1$, period 4

For $\lambda = .75$, period 2

For $\lambda = .5$, period 2

For $\lambda = .25$, period 5

Question 8

(i)

Given

$$q_d(t) = 250 - 50 p(t) - 2 \left(\frac{\partial}{\partial t} p(t) \right)$$

$$q_s(t) = 25 + 25 p(t)$$

then we can solve for $\frac{\partial}{\partial t} p$ as follows:

> **solve (250-50*p-2*dp=25+25*p, dp) ;**

$$\frac{225}{2} - \frac{75}{2} p$$

> **dsolve (diff (p (t) , t) = (225/2) - (75/2) *p (t) , p (t)) ;**

$$p(t) = 3 + e^{(-75/2)t} \text{ _CI}$$

(ii)

We can establish the stability by considering the limit of this equation.

> `limit(3+c1*exp(-75*t/2), t=infinity);`

3

Hence the market is stable.

Question 9

(i)

Equating demand and supply and solving for w_t we get

> `solve(42-4*wt=2+6*wt_1, wt);`

$$10 - \frac{3}{2} w_{t-1}$$

Thus, our equation is $w_t = 10 - \frac{3}{2} w_{t-1}$

> `solve(w=10-(3/2)*w, w);`

4

(ii)

We have just established that

$$w_t = 10 - \frac{3}{2} w_{t-1}$$

and at the minimum wage of $w = 3$, we have

> `solve(3=10-(3/2)*w, w);`

$$\frac{14}{3}$$

Hence we have the equation

$$f(w) = 10 - 1.5 w \quad w \leq \frac{14}{3}$$

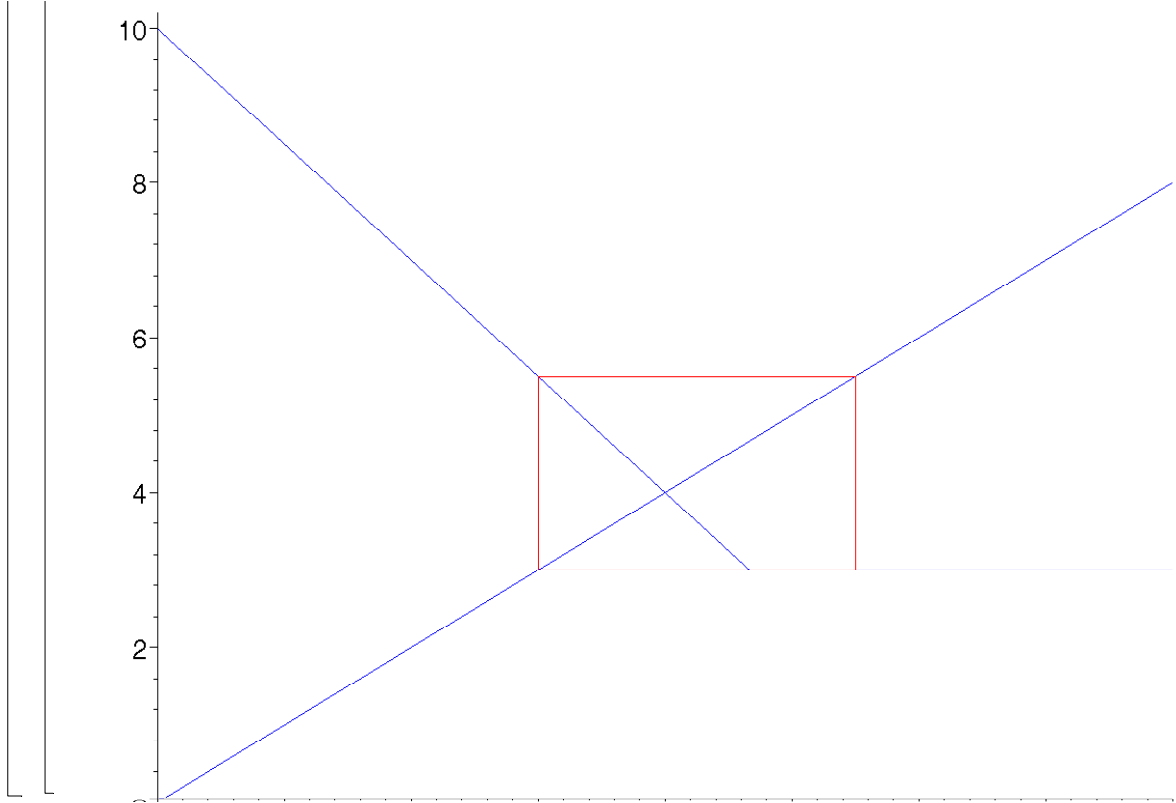
$$=3 \quad \frac{14}{3} < w$$

> `f:='f'; f:=w->piecewise(w<=14/3, 10-1.5*w, w>14/3, 3);`

$$f:=f$$

$$f:=w \rightarrow \text{piecewise}\left(w \leq \frac{14}{3}, 10 - 1.5 w, \frac{14}{3} < w, 3\right)$$

> `cobweb(f, 5, 8, 0, 8);`



Question 10

This is purely a theoretical question, but we can approach it in the following manner. Let the demand and supply system be given by:

$$q_t^d = a - b p_t$$

$$q_t^s = c + d p_{t-1}$$

$$q_t^d = q_t^s = q_t$$

in equilibrium

$$a - b p_t = c + d p_{t-1}$$

$$p_t = a - c + \left(-\frac{d}{b}\right) p_{t-1}$$

with solution

> **p:='p' ; p0:='p0' ;**

$$p := p$$

$$p0 := p0$$

> **rsolve ({p (t) = (a-c) + (-d/b) *p (t-1) , p (0) =p0} , p (t)) ;**

$$p0 \left(-\frac{d}{b}\right)^t - \frac{b(a-c) \left(-\frac{d}{b}\right)^t}{b+d} + \frac{b(a-c)}{b+d}$$

So the solution for $p(t)$ can be written

$$p(t) = \frac{a b - b c}{b + d} + \left(-\frac{d}{b}\right)^t \left(p_0 - \frac{a b - b c}{b + d}\right)$$

If $|b| > |d|$ then $|d/b| < 1$ and $0 < (-d/b)$

oscillatory fashion. The greater the absolute value of the demand curve relative to the supply curve, the larger the parameter b and the smaller $(-d/b)$, hence the smaller the oscillations around the equilibrium and so the sooner equilibrium is reached.

Question 11

```
> p:='p' ; p0:='p0' ;
```

$p := p$

$p_0 := p_0$

```
> solve(10-2*pt=4+2*pt_1,pt) ;
```

$3 - p_{t-1}$

```
> solve(p=3-p,p) ;
```

$\frac{3}{2}$

With difference equation,

$$p_t = 1.5 + (-1)^t (p - 1.5)$$

The periodicity and the periodic values are readily established using the **rsolve** command.

```
> rsolve({p(t)=3-p(t-1),p(0)=p0},p(t)) ;
```

$$p_0 (-1)^t - \frac{3}{2} (-1)^t + \frac{3}{2}$$

with periodic values p_0 when t is even and $3 - p_0$ when t is odd.

Question 12

First let us establish the fixed points of the system. Equating demand and supply and solving for equilibrium p we find,

```
> solve(4-3*p=p^2,p) ;
```

$-4, 1$

Since a negative price is ruled out, we consider only $p_e = 1$.

Before considering the cobweb version of this non-linear model, consider the stability of the linear approximation. First we need to obtain the difference equation for p .

```
> solve(4-3*pt=pt_1^2,pt) ;
```

$$\frac{4}{3} - \frac{1}{3} p_{t-1}^2$$

Thus, $p_t = f(p_{t-1}) = \frac{4}{3} - \frac{1}{3} p_{t-1}^2$ and $\frac{\partial}{\partial p} f = -\frac{2}{3}$ with $f'(p_e=1) = -2/3$. Since $|f'(p_e)| < 1$, then the system is stable. The linear approximation is given by:

$$p_t = 1 - \frac{2(p_{t-1} - 1)}{3}$$

which can be expressed,

$$p_t = \frac{5}{3} - \frac{2p_{t-1}}{3}$$

```
> rsolve({p(t)=(5/3)-(2/3)*p(t-1),p(0)=p0},p(t));
```

$$p0\left(\frac{-2}{3}\right)^t - \left(\frac{-2}{3}\right)^t + 1$$

which can be expressed:

$$p_t = 1 + \left(-\frac{2}{3}\right)^t (p_0 - 1)$$

```
> f:='f'; p0:='p0';
```

$f:=f$

$p0:=p0$

```
> f:=p->(4/3)-(1/3)*p^2;
```

$$f:=p \rightarrow \frac{4}{3} - \frac{1}{3}p^2$$

```
> cw:=array(1..2,1..2);
```

$cw := \text{array}(1..2, 1..2, [])$

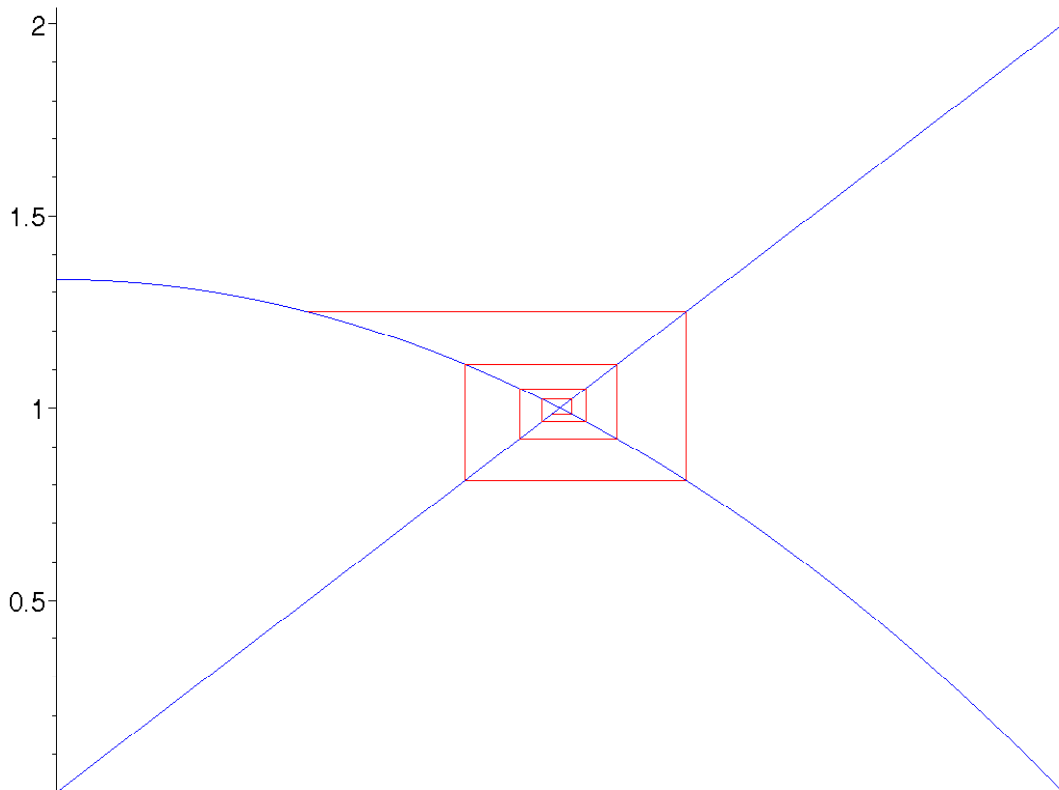
```
> cw[1,1]:=cobweb(f,0.5,8,0,2);
```

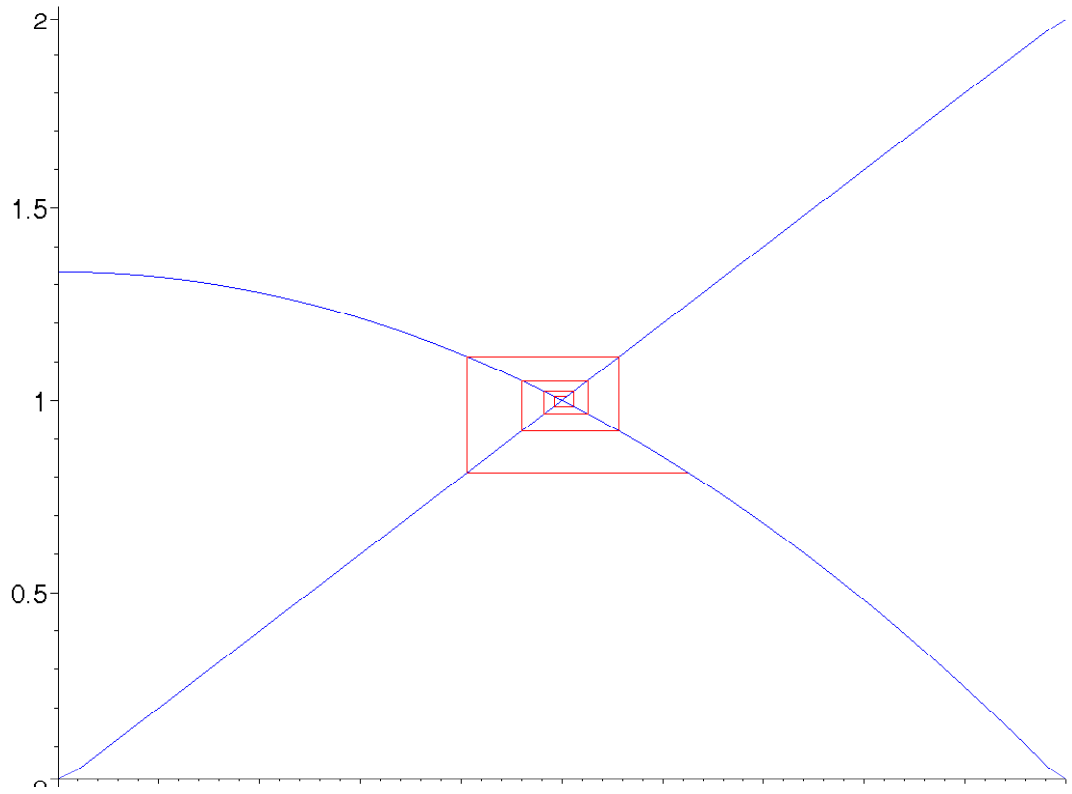
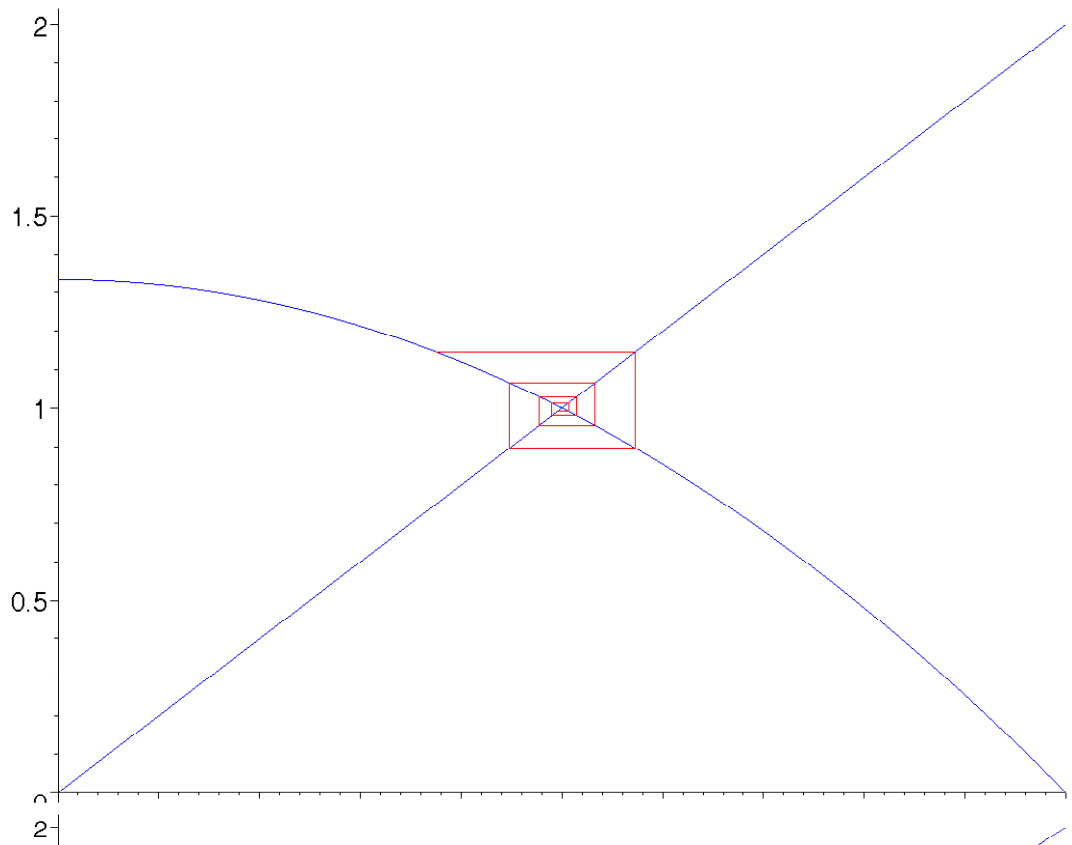
```
> cw[1,2]:=cobweb(f,0.75,8,0,2);
```

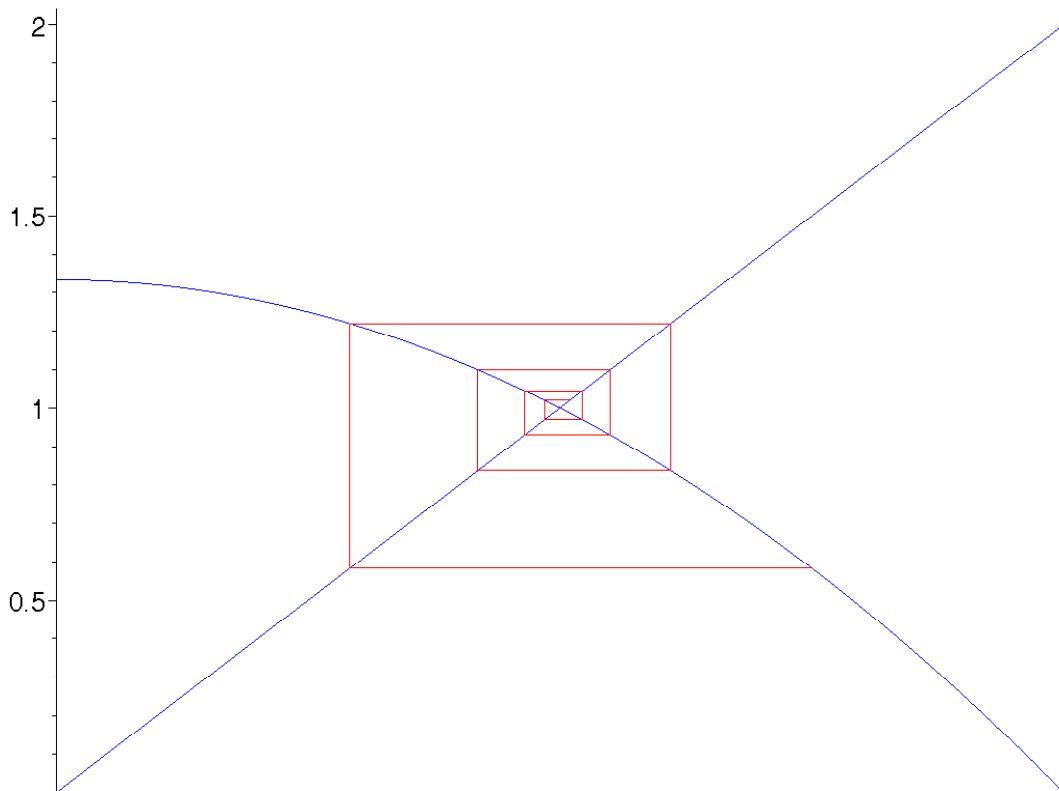
```
> cw[2,1]:=cobweb(f,1.25,8,0,2);
```

```
> cw[2,2]:=cobweb(f,1.5,8,0,2);
```

```
> display(cw[1,1]); display(cw[1,2]); display(cw[2,1]);
display(cw[2,2]);
```







Question 13

Equation 8.16 of the text, p.336 gave the general result

$$p_t = \frac{\lambda(a-c)}{b} + \left[1 - \lambda - \frac{\lambda d}{b} \right] p_{t-1}$$

substituting the values $a = 24$, $b = 5$, $c = -4$ and $d = 2$, then

$$p_t = \frac{\lambda(24+4)}{5} + \left[1 - \lambda - \frac{2\lambda}{5} \right] p_{t-1}$$

$$p_t = \frac{28\lambda}{5} + \left[1 - \frac{7\lambda}{5} \right] p_{t-1}$$

We can first check this result by obtaining the equilibrium and showing that it is independent of λ .

```
> solve(p=(28*lambda/5)+(1-(7*lambda/5))*p,p);
```

4

```
> eq0:=(28*lambda/5)+(1-(7*lambda/5))*p;
```

$$eq0 := \frac{28}{5}\lambda + \left(1 - \frac{7}{5}\lambda \right) p$$

```
> eq1:=subs(lambda=0.25,eq0);
```

$$eq1 := 1.400000000 + .6500000000 p$$

```
> eq2:=subs(lambda=0.5,eq0);
```

$$eq2 := 2.800000000 + .3000000000 p$$

```
> eq3:=subs(lambda=0.75,eq0);
```

$$eq3 := 4.200000000 - .0500000000 p$$

```
> eq4:=subs(lambda=1,eq0);
```

$$eq4 := \frac{28}{5} - \frac{2}{5}p$$

```
> f1:=p->1.4+0.65*p; f2:=p->2.8+0.3*p; f3:=p->4.2-0.05*p;
f4:=p->5.6-0.4*p;
```

$$f1 := p \rightarrow 1.4 + .65 p$$

$$f2 := p \rightarrow 2.8 + .3 p$$

$$f3 := p \rightarrow 4.2 - .05 p$$

$$f4 := p \rightarrow 5.6 - .4 p$$

```
> graph:=array(1..2,1..2);
```

```
graph:=array(1..2,1..2,[ ])
```

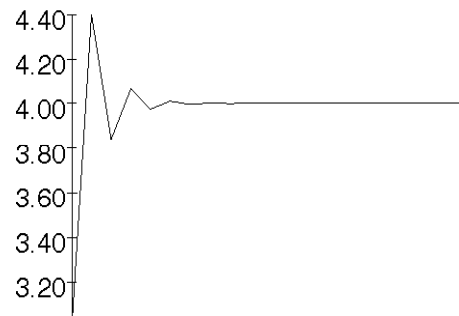
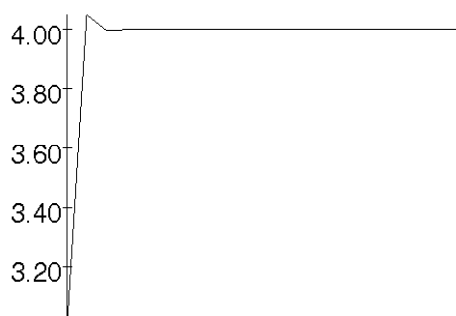
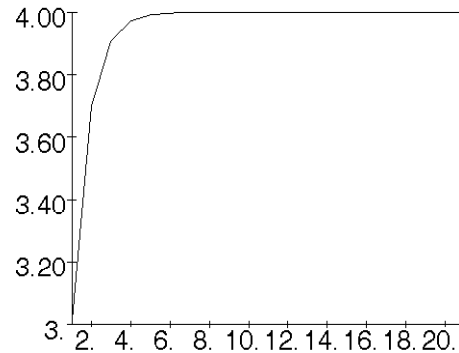
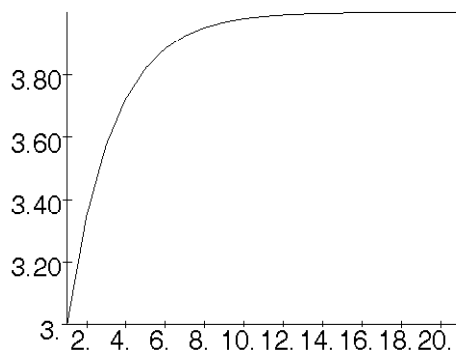
```
> graph[1,1]:=listplot([seq((f1@@k)(3),k=0..20)]):
```

```
> graph[1,2]:=listplot([seq((f2@@k)(3),k=0..20)]):
```

```
> graph[2,1]:=listplot([seq((f3@@k)(3),k=0..20)]):
```

```
> graph[2,2]:=listplot([seq((f4@@k)(3),k=0..20)]):
```

```
> display(graph);
```



Question 14

(i)

The linear approximation is given by:

$$\frac{\partial}{\partial t} P = r(P - Pe) - \left(\frac{\partial}{\partial h} R(he) \right) (h - he)$$

$$\frac{\partial}{\partial t} h = \left(\frac{\partial}{\partial P} g(Pe) \right) (P - Pe) - (d + n)(h - he)$$

(ii)

Given the assumptions, then

$$\frac{\partial}{\partial t} P = .05 (P - Pe) + .5 (h - he)$$

$$\frac{\partial}{\partial t} h = P - Pe - .03 (h - he)$$

Assume $Pe = 1$ and $he = 1$, then if $\frac{\partial}{\partial t} P = 0$ and $\frac{\partial}{\partial t} h = 0$,

```
> solve(0.05*(P-1)+0.5*(h-1)=0,P);
11. - 10. h
> solve((P-1)-0.03*(h-1)=0,P);
.9700000000 + .03000000000 h
```



(iii)

```
> A:=matrix([[0.05, 0.5], [1, -0.03]]);
A := [ .05 .5
       1 -.03 ]
> eigenvalues(A);
.7182372484, -.6982372484
```

Because eigenvalues r and s

This is also verified by the fact that the determinant is negative, thus

```
> det(A);
-.5015
> eigenvectors(A);
[.7182372484, 1, { [.5990963249, .8006769594] }],
[-.6982372484, 1, { [-.5892025114, .8817265314] }]
```



Question 15

The equation we wish to investigate is

$$p_{t+1}^e = (1 - \lambda) p_t^e + \frac{\lambda a}{b} - \frac{\lambda \arctan(\mu p_t^e)}{b}$$

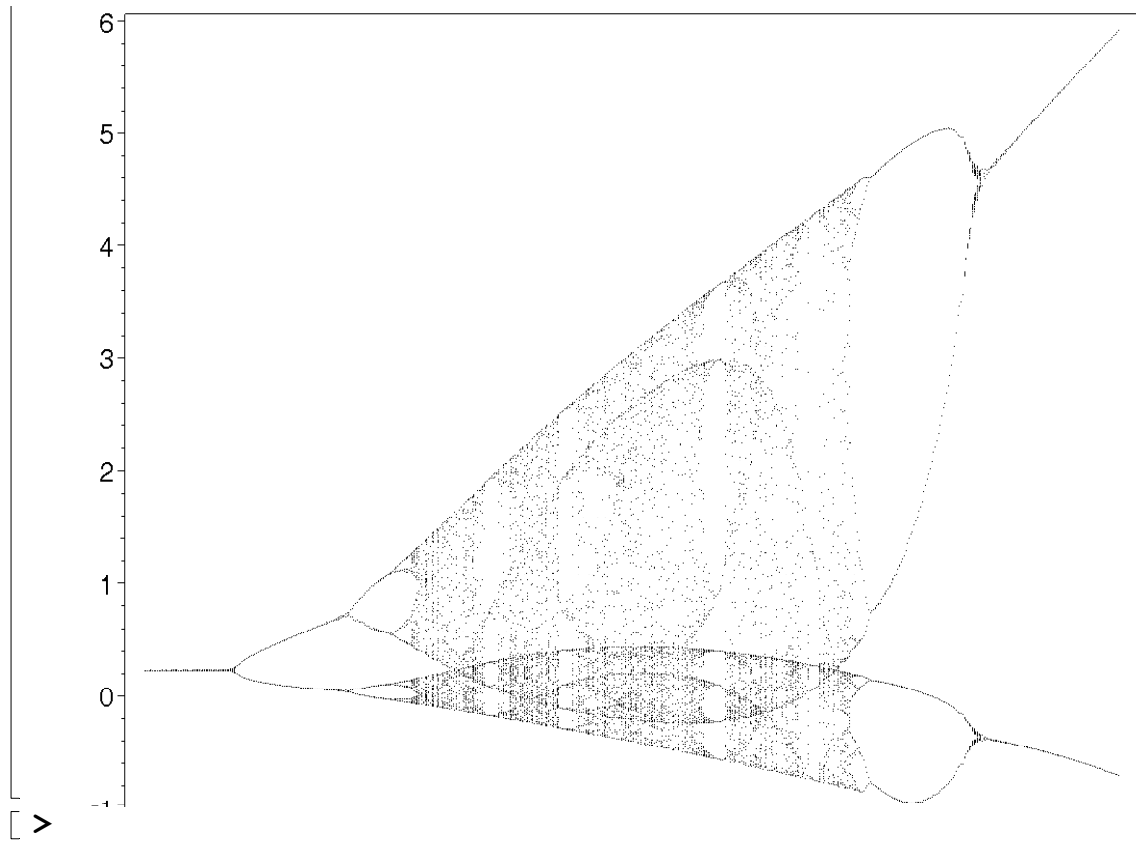
with $a = .8$, $b = .25$ and $\mu = 4$.

Note

The following plot takes a long time to produce and may exhaust your computer's c in the equation for λ .

The range for c will then need to be altered so λ ranges from 0.15 to 0.75.

```
> lambda:='lambda': c:='c':
> f:=pe->(1-lambda)*pe+lambda*0.8/0.25-lambda*arctan(4*pe)/0.25;
f:=pe -> (1 - lambda) pe + 3.200000000 lambda - 4.000000000 lambda arctan(4 pe)
> lambda:=0.15+0.001*c;
lambda := .15 + .001 c
> points:=evalf(seq(seq([lambda, (f@@k) ((f@@50) (0.5))], k=0..50), c=0..600), 4):
> pointplot({points}, symbol=point, axes=BOXED);
```



[>

When λ has a value around 0.15 the model exhibits a stable equilibrium expected price. As λ increases infinitely many doubling bifurcations occur, eventually reaching chaotic behaviour. However, as λ continues to increase there are many period halving bifurcations arising and expected price behaviour takes on a more regular pattern once again. At λ around 0.75 the system settles down to a stable two-period cycle. Also note that as λ increases so does the amplitude of the expected price oscillations.