

Errata for “Methods of Applied Mathematics”

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- **p. 14.** The equation in Example 1.1 (above the footnotes) is missing an equal sign. It should be

$$\dots \rightarrow \mathbf{adj}(A) A = A \mathbf{adj}(A) = \begin{pmatrix} 27 & 0 & 0 \\ 0 & 27 & 0 \\ 0 & 0 & 27 \end{pmatrix}$$

- **p. 15.** In Example 1.2, there are wrong signs for the off-diagonal terms for $\mathbf{adj}(\lambda I - A)$ and $(\lambda I - A)^{-1}$. They should be

$$\begin{aligned} \mathbf{adj}(\lambda I - A) &= \begin{pmatrix} \lambda - a_{22} & a_{12} \\ a_{21} & \lambda - a_{11} \end{pmatrix} \\ (\lambda I - A)^{-1} &= \frac{1}{\lambda^2 - (\mathbf{tr}(A))\lambda + \mathbf{det}(A)} \begin{pmatrix} \lambda - a_{22} & a_{12} \\ a_{21} & \lambda - a_{11} \end{pmatrix} \end{aligned}$$

- **p. 29.** Line below equation (1.29), missing word “from”. It should be

“... is obtained from A by replacing ...”

- **p. 29.** In example 1.10, missing \mathbf{det} operations in last equation on page. It should be

$$x_2 = \dots = \frac{\mathbf{det} \begin{pmatrix} 1 & 2 & 2 \\ 2 & 3 & 0 \\ -1 & 2 & 3 \end{pmatrix}}{\mathbf{det} \begin{pmatrix} 1 & 0 & 2 \\ 2 & 2 & 0 \\ -1 & -1 & 3 \end{pmatrix}} = \frac{11}{6}$$

- **p. 30.** Error in vector p and matrix X for the numerical illustration of example 1.11 (middle portion of the page). It should be

...

As a numerical illustration, let $N = 2$ and $R = 2$ and

$$\mathbf{F} = \dots \quad \text{and} \quad \mathbf{p} = \begin{pmatrix} 0.4 \\ 0.5 \\ 0.4 \\ 0.6 \end{pmatrix}$$

⋮

$$W = \dots \quad X = \begin{pmatrix} 0.1429 & 0.6190 \\ 0 & 0.3333 \end{pmatrix}$$

- **p. 34.** Wrong signs in matrix result (last equation) of example 1.14. It should be

$$\int_0^\pi \dots d\theta = \begin{pmatrix} p_1 & p_2 \end{pmatrix} \begin{pmatrix} 0 & 2 \\ -2 & 0 \end{pmatrix} \begin{pmatrix} p_1 \\ p_2 \end{pmatrix} = 0$$

- **p. 53.** In last line on the page, replace R by U . It should be

$$\dots \mathbf{x}^T Q \mathbf{x} = \mathbf{x}^T L \mathbf{x} = \mathbf{x}^T U \mathbf{x}.$$

- **p. 163.** In Table 4.4, wrong sign for the matrix representation of $\mathbf{a} \times \mathbf{b}$. It should be

$$\mathbf{a} \times \mathbf{b} \qquad \qquad \qquad -H^{[a]}\mathbf{b}$$

- **p. 199.** Last line of **E4.11** (line above **E4.12**), replace \mathbf{w} by \mathbf{u} . It should be

... takes vector \mathbf{y} and yields vector \mathbf{u} .

- **p. 238.** Error in right portion of equation above **Remarks**. It should be

$$\hat{y} = \frac{1}{2} \left(\frac{\hat{C}}{\hat{x}^2} - 1 \right) \quad \rightarrow \quad \dots$$

- **p. 240.** In theorem 6.1, definitions of \tilde{x} and \tilde{y} are missing x and y , respectively. It should be

... transformations given by $\tilde{x} = \lambda^\alpha x$ and $\tilde{y} = \lambda^\beta y$, where ...

- **p. 253.** Missing parenthesis in equation (2 equations above equation (6.55)). It should be

$$\frac{d}{dt} \left(e^{-At} \mathbf{x} \right) = e^{-At} \mathbf{b}(t)$$

- **p. 255.** (In middle portion of page) The reference to equation (6.14) should instead be to “last equation” It should be

... with respect to λ , of both sides of the last equation and then setting ...

- **p. 263.** For last equation before the exercises, the upper limit in integral should be t instead of ∞ . It should be

$$\begin{aligned} \mathbf{x} &= \dots \\ &= \dots \\ &= e^{At} \mathbf{x}(0) + \int_0^t e^{A(t-\tau)} \mathbf{b}(\tau) d\tau \end{aligned}$$

- **p. 269.** Wrong headings in Table 6.1. It should be

Data set 1			Data set 2			Data set 3		
Time	x_A	x_B	Time	x_A	x_B	Time	x_A	x_B
	\vdots			\vdots			\vdots	

- **p. 287.** In equation (7.38) and the previous equation, replace a_i by α_i . It should be

$$y_{k+1} = \sum_{i=0}^m \alpha_i y_{k-i} + h \sum_{j=-1}^m b_j f(y_{k-j})$$

the BDF methods ... formula to be

$$y_{k+1} = \sum_{i=0}^m \alpha_i y_{k-i} + hb_{-1} f(y_{k+1}) \quad (7.38)$$

- **p. 302.** In the equation before example 7.8, replace \mathbf{x}_0 by \mathbf{z}_0 . It should be

$$\text{IVS} \left[\left(\frac{d}{dt} \mathbf{z} = \mathbf{A}(t)\mathbf{z} + \mathbf{b}(t), \mathbf{z}_0 = \begin{pmatrix} 0 \\ \vdots \\ 0 \end{pmatrix} \right) \right] \longrightarrow \mathbf{z}(t = T)$$

- **p. 303.** Wrong sign in last equation result of example 7.8. It should be

$$\mathbf{x}(0) = \dots = \begin{pmatrix} 0 \\ -20.182 \end{pmatrix}$$

- **p. 307.** Last line of **E7.5**, change “attached CDROM” to “book’s webpage”.
- **p. 465.** In line above equation (12.42), insert word “of” between “root” and “ $\text{den}(z)$ ”.
- **p. 474.** Wrong derivative in left side of equation (12.78). It should be

$$\mathcal{L} \left[\frac{\partial^k}{\partial x^k} u(x, t) \right] = \frac{d^k}{dx^k} \mathcal{L} [u(x, t)] = \frac{d^k}{dx^k} \widehat{U}(x, s) \quad (12.78)$$

- **p. 475.** Wrong partial derivative in right side of equation (12.79). It should be

$$\mathcal{L} \left[\frac{\partial^k}{\partial t^k} u(x, t) \right] = s^k \widehat{U}(x, s) - \dots \quad (12.78)$$

- **p. 557.** Error in partial differential equation in exercise **E14.11**. It should be

$$\left(\frac{\partial^2 v_z}{\partial x^2} + \frac{\partial^2 v_z}{\partial y^2} \right) = -\beta$$