

Chapter 2 MATLAB Results

The collection of MATLAB statements and screen display for:

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-

Example 2.3

```
>> %Example 2.3
>> roots([1 1 -4 -4])

ans =
-2.0000
2.0000
-1.0000
```

Example 2.4

```
>> %Example 2.4
>> [a,b,k]=residue([6 0 -12],[1 1 -4 -4])

a =
1.0000      %Results returned by MATLAB provide no explanations
3.0000      %That's why we say be careful when you interpret the results
in the text
2.0000

b =
2.0000
-2.0000
-1.0000

k =
[ ]
```

Example 2.5

```
>> %Example 2.5
>> [a,b,k]=residue([6 0],[1 1 -4 -4])

a =
1.0000
-3.0000
```

```
2.0000
```

```
b =  
2.0000  
-2.0000  
-1.0000
```

```
k =  
[ ]
```

Example 2.6

```
>> %Example 2.6  
>> p=poly([-1 -2 -3]);  
>> [a,b,k]=residue(6,p)
```

```
a =  
3.0000  
-6.0000  
3.0000
```

```
b =  
-3.0000  
-2.0000  
-1.0000
```

```
k =  
[ ]
```

Example 2.7

```
>> %Example 2.7  
>> [a,b,k]=residue([1 5],[1 4 13])
```

```
a =  
0.5000 - 0.5000i  
0.5000 + 0.5000i
```

```
b =  
-2.0000 + 3.0000i  
-2.0000 - 3.0000i
```

```
k =  
[ ]
```

Example 2.9

```
>> %Example 2.9  
>> p=poly([-1 -1 -1 -2]);  
>> [a,b,k]=residue(2,p)
```

```
a =  
-2.0000  
2.0000  
-2.0000  
2.0000
```

```
b =  
-2.0000  
-1.0000  
-1.0000  
-1.0000
```

```
k =  
[]
```

Section 2.8

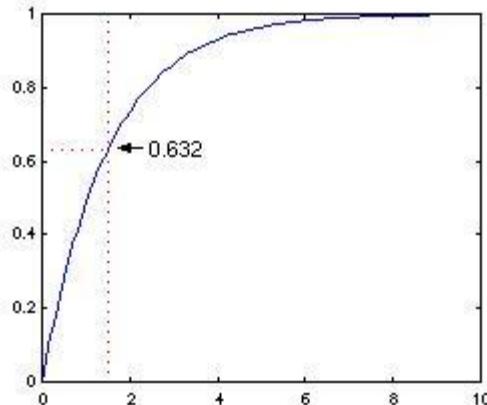
```
%Section 2.8.1 - See Review Problem 14 below
```

```
%Section 2.8.2 - We'll do an illustration on the typical unit step response  
of a first order function  
>> t=0:0.1:10;  
>> G=tf(1,[1.5 1]); %We choose a function with steady state gain = 1 and  
time constant = 1.5  
>> y=step(G,t);  
>> plot(t,y)  
>> hold  
Current plot held  
%We'll add red dotted lines to remind ourselves that when t = time  
constant, the step response is at 63.2%  
%In the following plot, the time constant is 1.5 as stated above  
%  
>> plot([1.5 1.5],[0 1],'r:') %the vertical line at 1.5  
>> 1-exp(-1)
```

```
ans =
```

```
0.6321
```

```
>> plot([0 1.5],[ans ans],'r:') %the horizontal line at 0.6321
```



Chapter 2 Review Problems

Review Problem 6

```
>> %Check the analytical results of No. 6  
>> [a,b,k]=residue(6,[1 1 -4 -4])
```

a =

```
0.5000  
1.5000  
-2.0000
```

b =

```
2.0000  
-2.0000  
-1.0000
```

k =

```
[]
```

Review Problem 9

```
>> %Solve the matrix equation in No. 9,  
>> %which is an alternate (and slower!) way of doing Example 2.9  
>> a=[1 0 0 1; 4 1 0 3; 5 3 1 3; 2 2 2 1];  
>> b=[0; 0; 0; 2];  
>> a\b
```

ans =

```
2.0000  
-2.0000  
2.0000  
-2.0000
```

Review Problem 11

```
>> %Partial fraction in No. 11  
>> p=conv([1 0 0],[1 4 -5]);  
>> roots(p)      %Make a habit of checking the roots
```

ans =

```
0  
0  
-5  
1
```

```
>> [a,b,k]=residue([1 1],p)
```

a =

```
0.0267  
0.3333  
-0.3600  
-0.2000
```

b =

```
-5  
1  
0  
0
```

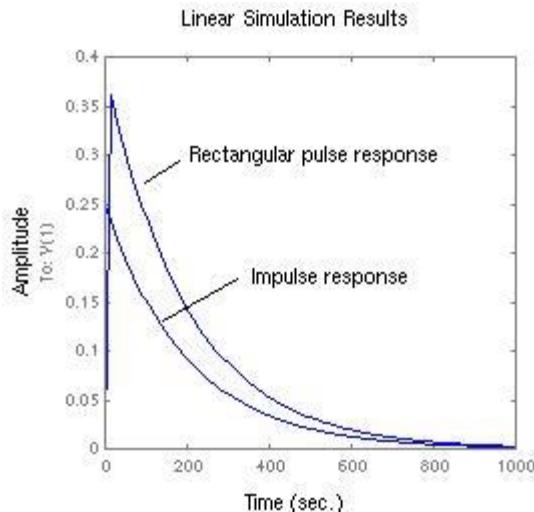
```
k =
```

```
[ ]
```

Review Problem 13 (Section 2.8.1)

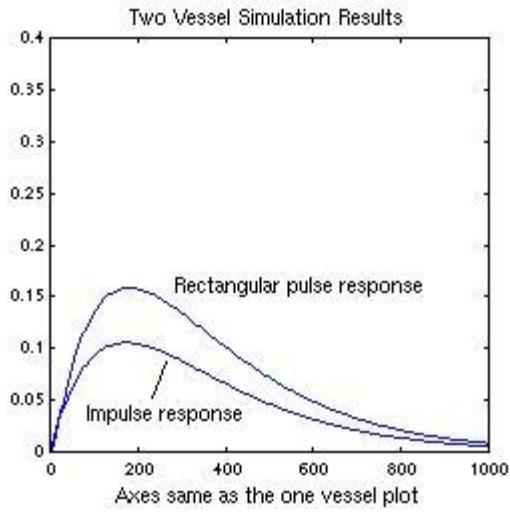
```
>> %Simulations in No. 13  
>> tau1=200;  
>> G1=tf(1,[tau1 1]);  
>> pulselength=10;  
>> delt=5;  
>> t=0:delt:1000;  
>> u=zeros(size(t));  
>> u(1:pulselength/delt+1)=5;  
>> lsim(G1,u,t); %The response of the rectangular pulse  
>> hold  
Current plot held  
>> y=50*impulse(G1,t); %Add on the impulse response  
>> plot(t,y)
```

Note: if you have trouble, reverse the plotting order of the two curves. With an impulse input, the response rises to a nonzero value instantaneously and then it decays exponentially.



```
>> %Now the response of two vessels  
>> tau2=150;  
>> G2=tf(1,[tau2 1]);  
>> G=G1*G2;  
>> lsim(G,u,t)  
>> y=50*impulse(G,t);  
>> hold  
Current plot held  
>> plot(t,y)
```

Note: The plot below takes a bit extra work to make it look nicer.



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Resources for 'PROCESS CONTROL: A First Course with MATLAB' by Pao C. Chau, published by Cambridge University Press, 2002.

More examples and info at: www.cambridge.org/processcontrol