

CORRECTIONS

page / Equation, Line, Fig., Table #

Correct form (correction highlighted in red)

p0/back page

Andras Z. Szeri is the Robert Lyle Spencer Professor Emeritus of Mechanical Engineering at the University of Delaware. He is past Technical Editor of *Journal of Tribology* and *Advances in Tribology*, and past Chair of the ASME *Research Committee on Tribology*. Currently, he serves on the Editorial Board of several Journals, including *Microsystem Technologies* and *International Journal of Applied Mechanics and Engineering*.

p19/E1.26

$$W = \left(\frac{\pi \alpha^2}{2}\right) H = \frac{1}{2} H \pi h^2 \tan^2 \theta, \\ F_p = \alpha x H = H x^2 \tan \theta.$$

p61/E2.21

$$\int_{\Delta} \rho \left(\frac{dv}{dt} - f \right) dv = \oint_{\Delta} t ds.$$

p69/4th E

$$\frac{\gamma_s}{dt} = \left(\frac{d\alpha}{dt} + \frac{d\beta}{dt} \right).$$

p83/E2.81

$$\mathbf{R}_\varepsilon \left(\frac{\bar{u}(\partial \bar{u})}{\partial \bar{x}} + \frac{\bar{v}(\partial \bar{u})}{\partial y} \right) = -\frac{\partial P}{\partial \bar{x}} + \frac{\partial^2 \bar{u}}{\partial \bar{y}^2}, \text{ space } \frac{\partial \bar{u}}{\partial \bar{x}} + \frac{\partial \bar{v}}{\partial \bar{y}} = 0.$$

p83/L11

also introduced the change of variables

p133/E3.155

$$\mathbf{h}_\eta(\mathbf{x}) = \mathbf{h}_0(\mathbf{x}) + \mathbf{h}_1(\xi).$$

p135/E3.163

$$= \Lambda \frac{\partial h_\eta}{\partial \xi_1} - \nabla \cdot (h_\eta^3 \nabla_\xi \omega_\eta) - \nabla_\xi (h_\eta^3 \nabla p_1).$$

p136/E3.165

$$\nabla \cdot [A(x) \nabla p_0 + B(x)] = 0, \quad p_0 = 0 \quad \text{on } \partial \Omega,$$

where we consider ∇p_0 a column vector.

p140/Table 3.5

Coefficient of friction (%)

p141/Table 3.6

Coefficient of friction (%)

p142/last L

$\langle \mathbf{1} \rangle_\eta$ pertaining to roughness η

p146/L3

Zür hydrodynamische (separate words)

p156/E4.26b

$$\bar{C}_{\xi\eta} = \frac{\partial f_T}{\partial \xi / \omega} \sin^2 \phi \dots etc. \quad (\text{delete negative sign following } =)$$

p158/E4.36

$$\alpha = \frac{2(\bar{K}_{xy} \bar{C}_{yx} + \bar{K}_{yx} \bar{C}_{xy} - \bar{K}_{yy} \bar{C}_{xx} - \bar{K}_{xx} \bar{C}_{yy})}{(\bar{C}_{xx} + \bar{C}_{yy})}.$$

p179/E4.91	$\overline{Z}_e = \frac{1}{2} \overline{a} (2\overline{t} - 1) \cdot$
p188/E5.4a	$\textcolor{red}{P} = \frac{\rho r^2 \omega^2}{\sinh^2 \alpha_1 } p$
p189/E5.6b	$+ \frac{2 \Delta \sin \hat{\beta}}{h} \frac{\partial u}{\partial \alpha} - \frac{\sinh \hat{\alpha}}{\pi h} \frac{\partial u}{\partial \beta}$
p197/L4	clearance ratio $\left(\textcolor{blue}{C}/R \right)$, i.e., $\textcolor{red}{P}_{RE} < P_{NS}$
p211/E5.64	$+2(f_1 \mathbf{0}^{\textcolor{blue}{T}'''} f_1 \mathbf{1} + f_1 \mathbf{0} f_1 \mathbf{1}^{\textcolor{blue}{T}'''})] + \cdots = \mathbf{0}.$
p223/L19	Let $\{U(x,t), \textcolor{red}{P}(x,t)\}$ and $\{u(x,t), p(x,t)\}$
p237/L22	variables and $\sigma \in \Sigma$ is the vector of parameters $\eta, \vartheta, \textcolor{red}{R}, \varepsilon$.
p238/E6.29	$\vec{G}(\mu) = 0, \qquad \mu = (\textcolor{blue}{u}, \sigma).$
P256/L17	the equations of motion [Eqs. (2.54b)], the equation of continuity [Eq. (2.16c)], and
p263/Fig.7.2	the law of the wall, Eq. (7.32).
p263/E7.35	$\varepsilon_m = A \left(\frac{q^2}{2} \right)^{1/2}, \qquad \Lambda$
p269/L6	$0.125 \textcolor{red}{R}_{\textcolor{blue}{h}}^{0.7}$.
p273/L9	\overline{U} and \overline{W} from Eqs. (7.64a) and (7.64b) directly
p273/last E	$I(\eta) = \int_0^\eta \frac{dY'}{1 + \frac{\varepsilon}{\nu}}, \quad J(\eta) = \int_0^\eta \frac{\textcolor{red}{Y}' dY'}{1 + \frac{\varepsilon}{\nu}}. \quad (\text{NB.: Greek "\textcolor{red}{nu}", not Latin "vee"})$
p275/L18	shows that $m_0 - m_1 =$
p288/L1	assuming that in the neighborhood of contact
p302/Fig. 8.9	for nominal point contact, $\kappa = \mathbf{1}$.
p311/L8	for any $x' \in [x_{j-1} - x_j, \textcolor{red}{x}_{j+1} - x_j]$
p322/E8.101	$\hat{u}^{2h} \leftarrow I_{\textcolor{blue}{h}}^{2h} \hat{u}^h + e^{2h}.$
p322/E8.102	$\hat{u}^{2h} \leftarrow I_{\textcolor{blue}{h}}^{2h} \hat{u}^h$
p330/L16	we may suppose $\textcolor{red}{w}^h$, the displacement
p358/E9.11, E9.12	Use lower case, bold, Latin "vee" $\textcolor{red}{v}$, not Greek "nu" ν .

p359/L1 multiplying \mathbf{v}_k vanishes
 p359/E9.20b, E 9.21 Use lower case, bold, Latin “vee” \mathbf{v} , not Greek “nu” ν .
 p359/ last § the dilatation work $-\mathbf{p} \operatorname{div} \mathbf{v} = 0$ by Eq. (2.16c)
 p359/footnote 3 $\rho \left(\frac{d}{dt} \right) (c_v \Theta) + \mathbf{p} \operatorname{div} \mathbf{v} = 0$ (ρ not bold!)

p361/E9.25b
$$= \frac{\partial}{\partial x_i} v_i' \left(p + \rho \frac{q^2}{2} \right) -$$

p361/E9.27
$$\rho c \left[\bar{v}_j \frac{\partial \bar{\Theta}}{\partial x_j} + \dots \right]$$

p362/E9.28
$$\rho c \bar{v}_j \frac{\partial \bar{\Theta}}{\partial x_j} = \dots$$

p362/E9.29
$$\mu = \frac{\bar{\mu}}{\mu_*}, \quad \xi = \frac{x}{R}, \quad \eta = \frac{y}{h}, \quad \zeta = \frac{2z}{L}.$$

p363/L19
$$\mathbf{R}_k =$$

p363/E9.36a
$$\vartheta = \left\{ \right.$$

p392/E10.4
$$= -\frac{\partial p}{\partial x_1} + \frac{\partial T_{11}}{\partial x_1} \dots$$

$$= -\frac{\partial p}{\partial x_2} + \frac{\partial T_{21}}{\partial x_1} \dots$$

p394/E10.13a
$$\nabla \chi \cdot (\hat{X} - X) + \dots$$

p407/E10.48
$$\frac{\partial w}{\partial y} = A \frac{d\tau_{xy}}{dt} + \tau_{xy} F(\tau_{xy})$$

p418/L8
$$\frac{\mu(p)}{p} \rightarrow 0 \text{ as } p \rightarrow \infty.$$

p422/3rd E
$$\mathbf{v}^{(\alpha)}(x,t) = \dot{x}_\alpha[\chi_\alpha^{-1}(x,t)].$$

P425/L4 quantities in E. (10.90) is now assumed to be a function of the variables of Eq. (10.93),

p440/E10.107
$$\dots \left[\mu_{blood} \sqrt{\frac{c_1^2 D^2}{(1-D^2)c_2^2}} \right]^{2.416} \Delta t^{-0.215}.$$

p468/L23 the velocity at the point Q and of the wall,

p472/Fig. 12.4 Knudsen number
 (---, Continuum; --, Boltzmann eq.; - · - ·, 1st order; etc.)

p480/last § “in isothermal conditions” Boltzmann operator are negligible”

p519/L3
p519/L10

of motion (10.85) and continuity (10.91), for steady flow
body force (cf., 10.95a) and the mixture

p530/4th E

$$\mathbf{M}_{ij} = \begin{bmatrix} \\ \end{bmatrix}$$

$$\mathbf{N}_{ij} = \begin{bmatrix} \\ \end{bmatrix}$$