

MATLAB Session 2 Results

The collection of MATLAB statements and screen display:

```
>> %Finding poles and partial fractions
```

```
>> p = [1 5 4]
```

```
p =
```

```
    1    5    4
```

```
>> poles = roots(p)
```

```
poles =
```

```
    -4
```

```
    -1
```

```
>> p2 = poly(poles)
```

```
p2 =
```

```
    1    5    4
```

```
>> q = 1;
```

```
>> residue(q,p)
```

```
ans =
```

```
 -0.3333
```

```
  0.3333
```

```
>> [a,b,k]=residue(q,p)
```

```
a =
```

```
 -0.3333
```

```
  0.3333
```

```
b =
```

```
    -4
```

```
    -1
```

```
k =
```

```
    []
```

```
>> %The next example
```

```
>> poles=[0 -1 -2 -3];
```

```
>> p=poly(poles);
```

```
>> q=1;
```

```
>> [a,b,k]=residue(q,p)
```

```
a =
```

```
-0.1667
0.5000
-0.5000
0.1667
```

b =

```
-3.0000
-2.0000
-1.0000
0
```

k =

```
[]
```

```
>> %Another Example
```

```
>> q=[1 4 3];
```

```
>> zeros=roots(q)
```

zeros =

```
-3
-1
```

```
>> p=[1 -7 11 7 -12];
```

```
>> poles=roots(p)
```

poles =

```
4.0000
3.0000
1.0000
-1.0000
```

```
>> [a,b,k]=residue(q,p)
```

a =

```
2.3333
-3.0000
0.6667
0
```

b =

```
4.0000
3.0000
1.0000
-1.0000
```

k =

```
[]
```

Warning

"zeros" is a MATLAB function. When we use it as a variable name, the function will no longer work. To revive the function if in case you need to use it, enter "clear zeros" to wipe out the variable. But using "poles" as a variable name is fine. It is "pole" in this case that it is a MATLAB function.

```
>> %Use of pole-zero form and doing "conversions"
```

```
>> q=[6 0 -12];
```

```
>> p=[1 1 -4 -4];
```

```
>> [zeros,poles,k]=tf2zp(q,p)
```

```
zeros =
```

```
    1.4142
```

```
   -1.4142
```

```
poles =
```

```
   -2.0000
```

```
    2.0000
```

```
   -1.0000
```

```
k =
```

```
    6
```

```
>> [q,p]=zp2tf(zeros,poles,k)
```

```
q =
```

```
    0    6.0000   -0.0000  -12.0000
```

```
p =
```

```
    1.0000    1.0000   -4.0000   -4.0000
```

```
>> %Another simple example
```

```
>> zero= -2;
```

```
>> poles=[-4 -3 -1];
```

```
>> k=1;
```

```
>> [q,p]=zp2tf(zero,poles,k)
```

```
q =
```

```
    0    0    1    2
```

```
p =
```

```
    1    8   19   12
```

```
>> %Double check the result
```

```
>> [zero,poles,k]=tf2zp(q,p)
```

```
zero =
```

```
   -2
```

```
poles =
```

```
-4.0000
-3.0000
-1.0000
```

```
k =
```

```
1
```

```
>> %Also can check with:
>> roots(q)
```

```
ans =
```

```
-2
```

```
>> roots(p)
```

```
ans =
```

```
-4.0000
-3.0000
-1.0000
```

```
>> %Use of object-oriented transfer function
>> G1 = tf([1 0], [1 -5 4])
```

```
Transfer function:
```

```
      s
-----
s^2 - 5 s + 4
```

```
>> G2 = tf([6 -12], [1 1 -4 -4])
```

```
Transfer function:
```

```
      6 s - 12
-----
s^3 + s^2 - 4 s - 4
```

```
>> G3 = zpk([], [0 -1 -2 -3], 4)
```

```
Zero/pole/gain:
```

```
      4
-----
s (s+1) (s+2) (s+3)
```

```
>> %Convert between different forms:
>> tf(G3)
```

```
Transfer function:
```

```
      4
-----
s^4 + 6 s^3 + 11 s^2 + 6 s
```

```
>> zpk(G2)
```

```
Zero/pole/gain:
```

```
      6 (s-2)
```

```
-----  
(s+2) (s+1) (s-2)
```

```
>> %Find the poles of a transfer function  
>> pole(G1)
```

```
ans =
```

```
    4  
    1
```

```
>> pole(G2)
```

```
ans =
```

```
 -2.0000  
  2.0000  
 -1.0000
```

```
>> %Extract the information back from a transfer function  
>> [q,p]=tfdata(G1,'v')
```

```
q =
```

```
    0    1    0
```

```
p =
```

```
    1   -5    4
```

```
>> [z,p,k]=zpkdata(G3,'v')
```

```
z =
```

```
Empty matrix: 0-by-1    %<--That's correct, G3 has no zeros
```

```
p =
```

```
    0  
   -1  
   -2  
   -3
```

```
k =
```

```
    4
```

```
>> %MATLAB operators are overloaded for the transfer functions  
>> G1=tf(1,[1 1])
```

```
Transfer function:
```

```
    1  
-----  
s + 1
```

```
>> G2=tf(2,[1 2])
```

Transfer function:

$$\frac{2}{s + 2}$$

```
>> G1+G2
```

Transfer function:

$$\frac{3s + 4}{s^2 + 3s + 2}$$

```
>> G1*G2
```

Transfer function:

$$\frac{2}{s^2 + 3s + 2}$$

```
>> %Looking inside the transfer function object
```

```
>> get(G1)
```

```
      num: {[0 1]}
      den: {[1 1]}
  Variable: 's'
        Ts: 0
  InputDelay: 0
  OutputDelay: 0
ioDelayMatrix: 0
   InputName: {''}
   OutputName: {''}
   InputGroup: {0x2 cell}
   OutputGroup: {0x2 cell}
        Notes: {}
   UserData: []
```

```
>> G1.InputName = 'Flow Rate';
```

```
>> G1.OutputName = 'Level';
```

```
>> G1.Notes = 'My first MATLAB function';
```

```
>> G1
```

Transfer function from input "Flow Rate" to output "Level":

$$\frac{1}{s + 1}$$

```
>> get(G1)
```

```
      num: {[0 1]}
      den: {[1 1]}
  Variable: 's'
        Ts: 0
  InputDelay: 0
  OutputDelay: 0
ioDelayMatrix: 0
   InputName: {'Flow Rate'}
   OutputName: {'Level'}
   InputGroup: {0x2 cell}
   OutputGroup: {0x2 cell}
        Notes: {'My first MATLAB function'}
```

UserData: []

```
>> %Symbolic algebra (reading optional -- it is based on the Web  
Supplement notes)
```

```
>> p = 'a*x^2+b*x+c'
```

```
p =
```

```
a*x^2+b*x+c
```

```
>> diff(p)
```

```
ans =
```

```
2*a*x+b
```

```
>> p = sym('a*x^2+b*x+c')
```

```
p =
```

```
a*x^2+b*x+c
```

```
>> p=[1 2 0 3];
```

```
>> sp=poly2sym(p)
```

```
sp =
```

```
x^3+2*x^2+3
```

```
>> pretty(sp)
```

$$x^3 + 2x^2 + 3$$

```
>> sym2poly(sp)
```

```
ans =
```

```
1      2      0      3
```

```
>> %Illustration of doing Laplace transform
```

```
>> f=sym('exp(-a*t)')
```

```
f =
```

```
exp(-a*t)
```

```
>> F=laplace(f)
```

```
F =
```

```
1/(s+a)
```

```
>> fcheck=ilaplace(F)
```

```

fcheck =

exp(-a*t)

>> laplace(sym('sin(freq*t)'))

ans =

freq/(s^2+freq^2)

>> ilaplace(ans)

ans =

freq/(freq^2)^(1/2)*sin((freq^2)^(1/2)*t) %<--very clumsy result
from the new MATLAB!

>> simplify(ans) %<--add a step to simplify the answer

ans =

csgn(freq)*sin(csgn(freq)*freq*t) %It's correct. csgn is just the
sign

>> f=sym('exp(-a*t)*sin(freq*t)')

f =

exp(-a*t)*sin(freq*t)

>> laplace(f)

ans =

freq/((s+a)^2+freq^2)

>> ilaplace(ans)

ans =

freq/(-4*freq^2)^(1/2)*(exp((-a+1/2*(-4*freq^2)^(1/2))*t)-exp((-a-
1/2*(-4*freq^2)^(1/2))*t))
%This is a big mess too, but we'll not dwell on this MATLAB
deficiency since we won't really use
% symbolic algebra to design controllers

>>
>> syms w t x; %The new version gave me an error without the x
>> laplace(sin(w*x),t)

ans =

w/(t^2+w^2)

>> %Re-visiting Example 2.4 here. We first make the transfer
function
>> q=[6 0 -12];

```

```
>> sq=poly2sym(q);
>> sp=poly2sym([1 1 -4 -4]);
>> g=sq/sp
```

g =

$(6x^2-12)/(x^3+x^2-4x-4)$

```
>> pretty(g)
```

$$\frac{6x^2 - 12}{x^3 + x^2 - 4x - 4}$$

```
>> %Now, we can find the partial fraction and time domain function
```

```
>> diff(int(g))
```

ans =

$1/(x-2)+3/(x+2)+2/(x+1)$

```
>> subs(ans, 's', 'x')
```

ans =

$1/((s)-2)+3/((s)+2)+2/((s)+1)$

```
>> pretty(ans)
```

$$\frac{1}{s-2} + \frac{3}{s+2} + \frac{2}{s+1}$$

```
>> ilaplace(ans)
```

ans =

$\exp(2t)+3\exp(-2t)+2\exp(-t)$

```
>> ilaplace(g) %Maybe it is redundant, but we double the check
results
```

ans =

$\exp(2t)+3\exp(-2t)+2\exp(-t)$

```
>> laplace(ans)
```

ans =

$1/(s-2)+3/(s+2)+2/(s+1)$

```
>> pretty(ans)
```

$$\frac{1}{s-2} + \frac{3}{s+2} + \frac{2}{s+1}$$

```
>> %The last example in the Session
>> poles=[0 -1 -2 -3];
>> p=poly(poles);
>> sp=poly2sym(p)
```

sp =

$x^4+6x^3+11x^2+6x$

```
>> factor(sp)
```

ans =

$x*(x+3)*(x+2)*(x+1)$

```
>> tf=symdiv('1',sp)
```

tf =

$1/(x^4+6x^3+11x^2+6x)$

```
>> ilaplace(tf)
```

ans =

$1/6-1/6*\exp(-3*t)+1/2*\exp(-2*t)-1/2*\exp(-t)$

```
>> diff(int(tf)) %Again, checking with the redundant approach
```

ans =

$1/6/x-1/6/(x+3)+1/2/(x+2)-1/2/(x+1)$

```
>> ilaplace(ans)
```

ans =

$1/6-1/6*\exp(-3*t)+1/2*\exp(-2*t)-1/2*\exp(-t)$

Warning

"tf" is a MATLAB function. When we use it as a variable name, the function will no longer work. To revive the function if in case you need to use it, enter "clear tf" to wipe out the variable.